Optimization of M3D for the Cray X1 and Neoclassical Closures

Don Spong, Steve Hirshman, Diego Castillo-Negrete, Ed D'Azevedo, Mark Fahey, Richard Mills Oak Ridge National Laboratory

Introduction

- ORNL LDRD awarded in October under the Terascale Computing and Simulation Science Initiative for "Terascale Computations of Multiscale Magnetohydrodynamics"
 - Team members: Don Spong (PI), Ed D'Azevedo (Co-PI), Steve Hirshman, Diego Castillo-Negrete, D. Batchelor, M. Fahey, R. Mills, Steve Jardin, W. Park, G. Y. Fu

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- Motivated by ORNL's selection for the National Leadership Computing Facility (NLCF)



Our goals/motivations

- Adapt/optimize M3D for Cray systems
 - Opportunity to be involved again in MHD physics
 - Support future stellarator experiment (QPS)
 - ITER physics
- Adapt/optimize stellarator Monte Carlo code (DELTA5D) to Cray systems
 - Self-consistent non-local transport studies
 - Incorporate viscosity-base methods
- Develop improved particle-based closure relations for study of NTM's
- Programmatic: prepare for future involvement in:
 - Fusion scientific end station
 - Fusion Simulation Project
 - Multiscale Mathematics Initiative

M3D optimization issue for vector machines: sparse matrix solver

- Development of efficient sparse matrix solvers important to Cray X1, Red Storm
 - Common issue for PDE's based on finite elements/differences
 - Addressed by specialized storage schemes
 - E.g., jagged diagonal scheme successfully used on the Earth Simulator
 - Methods we have tested (code from SPARSKIT2 (by Yosef Saad, Univ. Minnesota - performs matrix multiply 1000 times)
 - Compressed sparse matrix row storage
 - ELLPACK
 - Diagonal
 - Jagged diagonal





parallel scaling on NERSC Seaborg





Source: PhD Dissertation of Richard Vuduc, available at Bebop.cs.berkeley.edu.

ELLPACK Format

- Assume each row has similar number of nonzeros
- Store and operate on extra zeros
- Do j=1,ncol
 - Do i=1,n
 - y(i) = y(i) + a(i,j) * x(ja(i,j))
- Regular computation is good for vectorization
- Bad if a few rows have many nonzeros

Jagged Diagonal Format

- Pre-sort rows by number of nonzeros (require permutation in result y(:) vector)
- Long vectors good for vectorization
- Do ii=1,jdiag
 - ! compute length and offset k1
 - Do j=1,len
 - y(j) = y(j) + a(k1+j) * x(ja(k1+j))
- Ellpack like computation for multiple diagonals with same length

7pt Stencil 50x50x50

- N=110592, nnz=760320
- Minnz=6, maxnz=7
- Ellpack 86% filled
- 7 jagged diagonals
- 7 diagonals

	IBM Power4 SGI Altix Cray X1		
CSR	4.08	16.74	21.90
JAG	5.04	13.06	1.60
Ellpack	5.58	13.59	1.67
Diag	4.51	8.69	0.97
Mflops	372	175	1569

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BCSSTK18 (Structural Engineering)

- N=11948, nnz=80519
- Minnz=1, maxnz=31
- Ellpack 21% filled
- 31 jagged diagonals
- 1243 diagonals

	IBM Power4 SG	I Altix Cra	Cray X1	
CSR	0.37	0.55	1.75	
JAG	0.41	0.28	0.13	
Ellpack	1.54	2.58	0.63	
Diag	57.39	211.58	20.42	
Mflops	435	575	1239	

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Particle-based closure relations

- We are interested both in utilizing the existing M3D hybrid method and using techniques from DELTA5D, as appropriate
- Computational issues
 - Global memory access (co-array Fortran or other methods)
 - Parallelization over particles or over particles in volumetric regions
 - Implicit stepping methods for particles averaging over fast time scale bounce and transit motions
 - NTM: Ohm's law -> electrons
- Physics issues
 - Viscosity based calculation of bootstrap current
 - I = 2 Legendre harmonic moment
 - Not as sensitive to neglect of field-on-particle collisions, momentum restoring terms in collision operator, avoids large canceling terms of *I* = 1 moments
 - Such methods have recently been adapted/applied to 3D equilibria (H. Sugama, S. Nishimura, POP-2002, D. Spong Tues. morning invited talk)

Current Status

- DELTA5D ported to Cray X1 factor of 10 faster than similar clock speed IBM-SP scalar systems (Seaborg)
 - Further optimization should be possible
- M3D partially ported
 - Runs under some domain decomposition options, but not others
- Potential performance increase ~100 in going from existing IBM-SP to Cray 100 TF system
 - TFlops: ~5 to 100
 - Efficiency: ~6% to 35%