Fourier-Based Preconditioning for 3D Two-Fluid Computations and Scaling

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Outline

- Introduction
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- Parallel scaling
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Introduction: NIMROD's 'implicit leapfrog' algorithm is tailored for coefficients of high-order spatial expansions.

• A plane (poloidal) of 2D spectral elements and finite Fourier series in the periodic coordinate (toroidal angle) allow spectral convergence.

- Implicit advances require solution of large algebraic systems at each step.
 - With symmetric geometry and equilibria, linear computations solve a separate linear system for each Fourier component, like separate 2D computations.
 - Matrices for nonlinear 3D computations have matrix elements that couple different Fourier components. They are <u>smaller</u> than the matrix elements for the poloidal-plane coupling <u>by at least one factor of the perturbation amplitude</u>.
 - Our use of FFTs to compute Fourier-component couplings scales well in production calculations, but algebraic representation of the complete '3D' matrix is not practical.
- Krylov-space solvers iterate with matrix-vector product operations but not elements of the matrix. Approximate matrices are used to 'precondition.'

Hall-MHD in 3D has been problematic because fluctuations do not contribute to the diagonal of the **B**-advance operator, and the whistler is the fastest mode of the system.

• With A being a test function and dropping surface terms,

$$-\frac{\Delta t}{2} \int \mathbf{A} \cdot \nabla \times \left(\frac{1}{\mu_0 \overline{n} e} \tilde{\mathbf{B}}^{j+1/2} \times \nabla \times \Delta \mathbf{B} \right) dVol =$$
$$-\frac{\Delta t}{2} \int \frac{1}{\mu_0 \overline{n} e} (\nabla \times \mathbf{A}) \cdot \tilde{\mathbf{B}}^{j+1/2} \times (\nabla \times \Delta \mathbf{B}) dVol$$

• When the test and trial functions are expanded, the resulting matrix has mixed partials on the diagonal due to the cross product.

• With a Fourier expansion, the first-order toroidal derivatives lead to imaginary terms on the diagonal.

- The operator is non-Hermitian.
- It detracts from diagonal dominance when $\tilde{\mathbf{B}}^{j+1/2}$ and Δt are sufficiently large.

Aside: implicit electron inertia, even at physical m_e/m_i ratios, helps matrix condition numbers.

• The HPD part of our system is increased by adding the $\frac{1}{\varepsilon_0 \omega_e^2} \frac{\partial}{\partial t} \mathbf{J}$ part of electron inertia.

$$\Delta \mathbf{B} - \frac{\Delta t}{2} \nabla \times \left(\mathbf{V}^{j+1} \times \Delta \mathbf{B} \right) + \frac{\Delta t}{2} \nabla \times \frac{1}{\overline{n}e} \left(\mathbf{J}^{j+1/2} \times \Delta \mathbf{B} + \Delta \mathbf{J} \times \mathbf{B}^{j+1/2} \right)$$
$$+ \Delta t \nabla \times \left(\frac{\eta}{2} + \frac{d_e^2}{\Delta t} \right) \nabla \times \Delta \mathbf{B} - \Delta t \kappa_{divb} \nabla \nabla \cdot \Delta \mathbf{B}$$

for the lhs of the **B**-advance, also showing the divergence cleaning term. The electron skin depth is $d_e = c/\omega_e$.

• Physically, electron inertia leads to the electron cyclotron resonance, which keeps the *R*-mode phase speed from growing indefinitely as k_{max} increases with spatial resolution.

• This helps limit stiffness, hence condition numbers, in two-fluid computations.

Preconditioning Strategies

NIMROD's standard strategy is to use only the large matrix elements that couple coefficients of the same Fourier index.

• This approach works well for semi-implicit MHD with predictor/corrector advection where matrices are HPD [JCP **195**, 355 (2004)] and for semi-implicit MHD with implicit advection and/or gyroviscosity, where the non-Hermitian part is small.

Three new (for NIMROD) strategies for substantially non-HPD matrices have been tested this past year. Two have been discarded:

- 1. Polynomial approximation can reduce GMRES iteration in the two-fluid **B**-advance, but its iteration is just as costly.
- 2. Evaluating 2D poloidal 'slices' at a set of uniformly spaced toroidal angles was intended to complement the standard Fourier-based scheme.
 - Stand-alone 'slicing' is effective for sufficiently small Δt .

• At Δt of interest for production simulations, lack of diagonal dominance on the toroidal grid prevents convergence, even when used as a multiplicative step with the standard Fourier-based scheme.

3) An approach based on limited off-diagonal Fourier coupling has advantages over the other two strategies.

• For block Gauss-Seidel preconditioning, the Fourier representation helps keep the spectral radius of $(D+L)^{-1}U$ less than 1 at large time-step, unlike the slicing strategy. [Here, the notation refers to block-based splitting A=L+D+U.]

• With limited couplings, matrix elements can be generated, and matrixvector products are fast relative to full matrix-free product operations.

- The required coding for these matrices is a generalization of existing code for the diagonal-in-Fourier systems.
- When used in iteration, these matrices are not factored.

• Generating matrix elements is computationally intensive but scales well in parallel. [Generation of full convolution matrices is not practical, however, even in parallel.]

• The extra communication during Jacobi/Gauss-Seidel iteration (preconditioner looping) is point-to-point.

The limited Fourier coupling helps avoid increasing GMRES iteration as toroidal resolution is increased.

• The test case here is a small two-fluid 1/1 cylindrical kink. [The physics is helically symmetric, but NIMROD treats it as a 3D computation.]

• Here, the representation is 9×9 biquintic, and $\Delta t/\tau_{Hp} = 2$.



G-S passes makes the iteration nearly independent of the number of Fourier comps (N_{Four}) in this case.

Serial CPU time is shown per Fourier comp. Data at N_{Four} =11 is from Bassi unlike others.

- The near-constant iteration count with increasing N_{Four} is important.
- This case is dominated by n=1; others may be more challenging.

Parallel Scaling

Improving resolution requires increasing use of parallelism that is available in new multi-core massively parallel computers.

• The new preconditioner has been developed to provide good scaling with NIMROD's two types of domain decomposition (poloidal blocks and Fourier layers).

• Application is a two-fluid kink in the early nonlinear stage; $\Delta t = 0.1 \tau_A$.

• Results are from the Cray XT4 at NERSC ("Franklin"), quad-core.

• Parameters provide a weak scaling of a production computation.

• New preconditioner help keep GMRES iterations fixed with increasing N_{Four} .

• Largest computation has 1.8×10^8 degrees of freedom (coefficients of the high-order representation) and exceeds the 1-TFlop level of actual performance.



Blue: 32 blocks; Black: 64 blocks; Red: 128 blocks. Within color shows increasing N_{Four} .

Memory may be the limiting factor in this scaling.

• Results include recent efficiency improvements that reduce latency in the communication operations before and after FFTs.

- The two types of decomposition are algorithmically independent.
- Both 64- and 128-block sets are scaled to 86 Fourier components with 2 components per layer. $\begin{bmatrix} Memory - - & \end{bmatrix}_{1}^{2}$
- Computations with 128 blocks approach maximum average available memory per core.
- Improvements in new release of SuperLU_DIST may help.
- LBL group (X. Li) is developing an ILU version of SuperLU_DIST, which may be more efficient for preconditioning.



Internal Kink Application

Application of NIMROD to the nonlinear two-fluid internalkink is both a nonlinear benchmark and a research study.

- Cylindrical results (see poster BP6.00042) can be benchmarked against others.
 - Germaschewski will present the same type of fast reconnection behavior from a full model in presentation GI1.00004.
- Toroidal results summarized here may be new.

Simulations of the internal kink in <u>toroidal</u> geometry investigate inherently three-dimensional evolution.

- Equilibria are generated with the new NIMEQ code: E. Howell, BP6.00041.
- Profiles for the circular cross-section, R/a=4 torus are specified as P=const $(\beta=5\times10^{-3})$ and

$$F = 3.44 + 0.12(1 - \psi) + 0.064\psi(\psi - 1)$$

where ψ is the normalized ring flux.

- Here q(0)=0.97, q(a)=1.61.
- Other parameters are:

$$S = \tau_r / \tau_{Hp} = 1.48 \times 10^6 \quad \tau_{Hp} = 2\pi a^2 \sqrt{\mu_0 \rho} / \mu_0 I_p$$

$$d_e = 5 \times 10^{-3} \quad \delta = d_i / 2 = 0.11 \quad \rho_s = 1.5 \times 10^{-2}$$

$$\mu_0 v_{iso} / \eta = \text{Pm} = 0.1 \quad T_i \approx 0$$



Mesh of spectral elements reflects slight Shafranov shift and is packed near 1/1 resonance.

Moderate and high resolution computations obtain a nonlinearly increasing kinetic energy growth-rate.



- First case has a 20×20 mesh, degree of polynomials is 8, and $0 \le n \le 42$.
- Second case has a 24×32 mesh, degree of polynomials is 8, and $0 \le n \le 85$.
- The moderate and large computations were run on 300 and 1376 cores of "Franklin" in quad-core configuration.

The computations show a transition from current-sheet to x-point reconnection when the growth-rate of kinetic energy increases.



Just before the increase in growth rate (t *t*=4.67×10⁻³ τ_r), there is a broad layer of parallel current density (grayscale) where field-lines are reconnecting.



Near the peak growth rate (t $t=4.95\times10^{-3}$ τ_r), x-point reconnection is evident, and parallel current is concentrated.

• While the toroidal cases are inherently 3D, initial R/a=4 results are qualitatively similar to helically symmetric cylindrical results.

Conclusions

- Improvements to NIMROD's computational linear algebra are proving essential for studying two-fluid macroscopic dynamics in 3D.
- The implicit Hall term is non-Hermitian, but its impact on diagonal dominance is minimized by NIMROD's Fourier representation.
- Implicit electron inertia is a HPD operator and limits numerical stiffness from the *R*-mode, even with realistic m_e/m_i .
- Incorporating limited Fourier coupling is proving reasonably effective and scalable in production two-fluid computations.
- The algorithmic improvements are being used successfully in a two-fluid study of internal kink.
 - Also RFP tearing--see J. King, poster NP6.00071.
- Toroidal geometry computations are inherently 3D, but initial twofluid results are qualitatively similar to the cylindrical results.

List of NIMROD-related Presentations, APS-DPP 2008

- 1. BP6.00041, Howell, NIMEQ: MHD Equilibrium Solver for NIMROD
- 2. BP6.00042, Sovinec, Preconditioning for Three-Dimensional Two-Fluid NIMROD Applications
- 3. BP6.00043, Kruger, Anisotropic Heat Transport in the Presence of Resonant Magnetic Perturbations
- 4. BP6.00044, Sharma, Parallel heat flow and stress tensor in toroidal plasmas
- 5. BP6.00046, Cone, FRC Formation and Translation Simulations with Anisotropic Viscosity
- 6. BP6.00047, Nelson, Results from the PSI-Center Interfacing Group
- 7. BP6.00048, Kim, Kinetic Studies of ICC Devices using High Order PIC in Finite Elements
- 8. BP6.00074, Schlutt, An. and comp. inv. of the effect of finite par. heat trans. on the form. of mag. isl. in 3-D pl. eq.
- 9. CP6.00018, Jenkins, Modeling of RF/MHD coupling using NIMROD and GENRAY
- 10. CP6.00042, Ji, Relaxation of non-Maxwellian moments: an. solutions of the kinetic equation for uniform plasmas
- 11. CP6.00044, Cheng, Progress on the Kinetic MHD model
- 12. CP6.00070, Ebrahimi, Finite pressure effects in the Reversed Field Pinch
- 13. CP6.00075, Zhu, Nonlinear Ballooning Filament: Structure and Growth
- 14. CP6.00077, Squires, Dynamic Behavior of Peeling-Ballooning Modes in a Shifted-Circle Tokamak
- 15. GO3.00013, Granetz, Studies of runaway electrons during disruptions in Alcator C-Mod
- 16. GP6.00025, Murphy, Magnetic reconnection with asymmetry in the outflow direction
- 17. JP6.00012, Bird, Numerical Simulation of MHD Relaxation during Non-Inductive Startup of STs
- 18. JP6.00065, Izzo, Simulation of DIII-D Plasma Shutdown by Deuterium Dilution Cooling
- 19. NO3.00001, Weatherford, Spheromak Simulation in 3+1 Dimensions Using Multiscale Space/Time Spectral Elements
- 20. NP6.00028, Suzuki, Linear stability of resistive interchange modes in a cylindrical RFP plasma
- 21. NP6.00071, King, Numerical Studies of Nonlinear Two Fluid Tearing Modes in Cylindrical RFPs
- 22. NP6.00139, O'Bryan, Computational study of a non-ohmic flux compression startup method for STs
- 23. PO3.00013, Wu, 1-D Modeling of Massive Particle Injection (MPI) in Tokamaks
- 24. UP6.00023, Carey, MHD stability of extragalactic jets with azimuthal rotation
- 25. TP6.00087, McLean, Final Results from the SSPX Spheromak Program
- 26. TP6.00089, Stewart, Virtual diagnostics in NIMROD simulations for direct comparison to SSPX measurements
- 27. TP6.00090, Romero-Talamas, Numerical and experimental investigations of helicity sustainment in spheromaks
- 28. TP6.00092, Cohen, The Relationship of the n=1 Column Mode to Spheromak Formation
- 29. TP6.00091, Hooper, Spheromak aspect-ratio effects on poloidal flux amplification
- 30. TP6.00093, Lodestro, Multipulsed edge-current drive in a spheromak
- 31. TP6.00101, Akcay, NIMROD Simulations of Decaying and Driven Hit-SI Plasmas
- 32. TP6.00105, Machab Extended MHD Simulations of the Formation, Merging, and Heating of Compact Tori
- 33. TP6.00118, Held, Numerical methods for anisotropic heat transport in high-temperature plasmas
- 34. UP6.00035, Forest, MHD Modeling of a Plasma Dynamo Experiment
- 35. YP6.00076, Takahashi, Kinetic effects of energetic particles on resistive MHD stability
- 36. YP6.00089, Brennan, Helical phase lag between coupled nonlinear res. MHD instabilities in toroidal flow shear