## Implementations and applications of continuum closures

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#### Outline



Solve full plasma kinetic equation using continuum method.

- Apply 2-D finite-elements (FE) in Chapman-Enskog-like kinetic equation.
- Slowing down of diffuse ion beam.
- 2 Solve drift kinetic equation using continuum method.
  - Recap of recursive drift kinetic theory.
  - Application to sound wave damping problem.
  - One recursion introduces drift effects.

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#### Solve Chapman-Enskog-like (CEL) kinetic equation.

• Couple solutions of 6-D, time-dependent Chapman-Enskog-like kinetic equation to evolving fluid equations through closures for **q** and **Π**:  $\frac{\partial F}{\partial t} + \mathbf{v} \cdot \nabla F + \mathbf{a} \cdot \nabla F = C(F + f_M) - \frac{m}{T} (\mathbf{v}' \mathbf{v}' - \mathbf{v}'^2 \frac{1}{3}) : \nabla \mathbf{u} - \frac{2f_m}{3p} L_1^{(3/2)} [\nabla \cdot \mathbf{q} + \mathbf{\Pi} : \nabla \mathbf{V} - Q] + \mathbf{v}' \cdot \left[ \frac{f_m}{p} (\nabla \cdot \mathbf{\Pi} - \mathbf{R}) + \frac{f_m}{T} L_1^{(5/2)} \nabla T \right]$ where  $f_M = n(\mathbf{x}, t) \left( \frac{m}{2\pi T(\mathbf{x}, T)} \right)^{3/2} e^{-\frac{m(\mathbf{v} - \mathbf{u})^2}{2T}}$ and  $\mathbf{v} = v_{||} \mathbf{b} + v_{\perp} (\mathbf{e}_2 sin\gamma - \mathbf{e}_3 cos\gamma)$ .

Apply 2-D finite-elements (FE) in Chapman-Enskog-like kinetic equ Slowing down of diffuse ion beam.

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#### Use 2-D FE, 1-D Fourier basis for F.

- Expand distribution function as  $F = F_0 + \sum_{n>0} F_n e^{in\gamma} + F_n^{\dagger} e^{-in\gamma}$ , with Fourier coefficients expanded as  $F_n = \sum_i F_{ni}(\mathbf{x}, t) \alpha_i(\mathbf{v}_{\perp}, \mathbf{v}_{\parallel})$ .
- At present, test particle portion of linearized Coulomb collision operator is implemented.
  - $$\begin{split} &\int d\mathbf{v} \alpha C(f_{\alpha}, f_{M\beta}) = \\ &- \frac{2\pi q_{\alpha}^2 q_{\beta}^2 \ln \Lambda_{ab}}{m_{\alpha}^2} \frac{n_{\beta}}{n_{\alpha}} \frac{1}{z_{\beta}} \int d\mathbf{v} (4 \frac{m_{\alpha}}{m_{\beta}} \frac{1}{v_{T\beta}} G(\mathbf{z}_{\beta} \cdot \frac{\partial \alpha}{\partial \mathbf{v}}) f_{\alpha} + \\ &(E G) (\frac{\partial \alpha}{\partial \mathbf{v}} \cdot \frac{\partial f_{\alpha}}{\partial \mathbf{v}}) + (\frac{3G E}{z_{\beta}^2}) (\mathbf{z}_{\beta} \cdot \frac{\partial \alpha}{\partial \mathbf{v}}) (\mathbf{z}_{\beta} \cdot \frac{\partial f_{\alpha}}{\partial \mathbf{v}}) . \end{split}$$

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#### Apply test-particle operator to beam ions.



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#### After 1 collision time.



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#### After 3 collision times.



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#### After 5 collision times.



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#### After 20 collision times distribution is Maxwellian.



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#### Future work on full continuum solution.

- Test-particle operator implemented.
- Implement field terms of linearized Coulomb operator.
- Implement nonlinear terms.
- Develop coding necessary to extend solution to spatial domain.

Recap of recursive drift kinetic theory. Application to sound wave damping problem. One recursion introduces drift effects.

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### Drift kinetic theory a la Hazeltine '73.

- Define  $L = d/dt \Omega \partial/\partial \gamma$ , total time derivative without the rapid gyro-motion. Here  $\Omega = qB/m$ .
- Hazeltine suggests solving  $\Omega \frac{\partial \tilde{f}}{\partial \gamma} = -(L - C)f + \langle (L - C)f \rangle,$ by approximating *f* on right as  $\bar{f}$  (the gyro-angle

independent part).

- Can repeat this by step by using  $f = \overline{f} + \widetilde{f}_1$  on right to get an improved f.
- Finally, insert  $f = \overline{f} + \widetilde{f}_j$  after *j* recursions into  $\langle (L C)f \rangle = 0$  and solve for  $\overline{f}$ .

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# Zero recursions ( $\tilde{f} = 0$ ) leads to lowest-order CEL-drift kinetic equation.

 Solve lowest-order equation for electrons and ions to compute parallel closures, q<sub>||</sub>and "<sub>||</sub>:

 $\frac{\partial F}{\partial t} + \mathbf{v}_{||} \cdot \nabla F + \frac{q}{m} E_{||} \frac{v_{||}}{v} \frac{\partial F}{\partial v} = \\ \langle C(F + f_M) \rangle - \frac{mv^2}{T} f_M (\mathbf{bb} - \frac{\mathbf{l}}{3}) : \nabla \mathbf{u} -$ 

$$+\frac{2f_m}{3p}L_1^{(3/2)}\left[\nabla\cdot\mathbf{q}+\mathbf{\Pi}{:}\nabla\mathbf{V}-Q-S_0^{r\!f}\right]+$$

 $\mathbf{v}_{||} \cdot \left[ \frac{f_m}{\rho} \left( \nabla \cdot \mathbf{\Pi} - \mathbf{R} - F_0^{rf} \right) + \frac{f_m}{T} L_1^{(5/2)} \nabla T \right]$ 

• Expand  $F = \sum_{l=0}^{nl} F_l(\mathbf{x}, t, s) P_l(v_{||}/v)$ , where the coefficients  $F_l(\mathbf{x}, t, s)$  are determined on a grid of *ns* grid points in the normalized speed,  $s = v/v_T$ .

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#### Time-discretization and centering issues.

- Present implementation centers *F<sub>e</sub>* and *F<sub>i</sub>* with *n*, **B**, *T<sub>e</sub>*, *T<sub>i</sub>* in time.
- *n*, **B**, *T<sub>e</sub>* and *T<sub>i</sub>* dependence in Maxwellian drives approximately centered in implicit *F* advance.
- Advance **V**, n,  $F_e$ ,  $F_i$ , compute closures.
- Advance *T<sub>e</sub>*, *T<sub>i</sub>* and **B**, solve again for *F<sub>e</sub>*, *F<sub>i</sub>* with approximately centered *n*, **B**, *T<sub>e</sub>*, *T<sub>i</sub>*, and recompute closures.
- Advance  $T_e, T_i$  and **B** with approximately centered closures.

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Apply to sound wave damping problem.

Test stress damping of sound waves with adiabatic equation of state.



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#### Test convergence in velocity space.

- Number of Legendre polynomials = nl. Number of grid points in speed = ns.
- Limits on workstation with 4 GB of memory: nl=12 and ns=4.



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## Future work on lowest-order continuum solution to CEL-DKE.

- Implement RF quasilinear source terms imported from GENRAY.
- Implement finite flow corrections in Maxwellian drives.
- Implement calculation of self-consistent, equilibrium  $F_e$  and  $F_i$  (needed when there is equilibrium current and flow).
- Test continuum solution to CEL-DKE on various problems.

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#### Compare with Chang/Callen '92.

- One-pole approximations for linear closures were given as:  $\begin{aligned} \mathbf{b} \cdot \nabla \cdot \tilde{\mathbf{\Pi}} &\approx n_0 m_i \frac{3}{5} \left[ \sqrt{\pi} k_{||} \mathbf{v}_{Ti} - \frac{6}{5} (\frac{\partial}{\partial t} + 0.32 \nu_{ii}) \right] \tilde{u}_{||i} \\ &+ \frac{2}{5} \left[ k_{||} \mathbf{v}_{Ti} - \sqrt{\frac{3\pi}{10}} (\frac{\partial}{\partial t} + 0.42 \nu_{ii}) \right] \frac{n_0}{k_{||} \mathbf{v}_{Ti}} (\nabla_{||}^{-} T) \\ \tilde{q}_{||} &\approx \frac{2}{5} \left[ k_{||} \mathbf{v}_{Ti} - \sqrt{\frac{3\pi}{10}} (\frac{\partial}{\partial t} + 0.42 \nu_{ii}) \right] \frac{p_i}{k_{||} \mathbf{v}_{Ti}} \tilde{u}_{||i} \\ &- \frac{9}{5\pi} \left[ \sqrt{\pi} k_{||} \mathbf{v}_{Ti} - \frac{72}{25\pi} (\frac{\partial}{\partial t} + 0.42 \nu_{ii}) \right] \frac{n_0}{k_{||}^2} (\nabla_{||}^{-} T) \end{aligned}$
- Compare linear damping results between theory, kinetic MHD and continuum closure calculations.

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#### Drift corrections needed for many problems.

- Do one level of recursive theory to incorporate drift effects.
- Integrate,  $\Omega \frac{\partial \tilde{f}_1}{\partial \gamma} = -(L-C)\bar{f} + \langle (L-C)\bar{f} \rangle.$
- Insert  $f = \overline{f} + \widetilde{f}_1$  into  $\langle (L C)f \rangle = 0$  and solve for  $\overline{f}$ .
- Solve: ∂F/∂t + (V<sub>||</sub> + V<sub>D</sub>) · ∇F + a∂F/∂ε = Maxwellian drives including drift effects.