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Scalable Parallel Solver Strategies

Two-Part Overall Strategy

- Physics-based preconditioning (PBP) is used to reduce the order of matrices and make them diagonally dominant (Chacón). Already implemented.
- Multigrid provides a scalable parallel method for solving diagonally-dominant matrices.

Coarsening and Refining Strategies

- **Geometric (GMG):** coarser and finer grids. Not suitable for spectral elements.
- **Algebraic (AMG):** choose largest matrix elements for coarsening. PETSc/Hypre/BoomerAMG. Tested for spectral elements; unsuccessful.
- **Spectral Element (SEMG):** Specifically designed to exploit spectral elements; uses nest spaces of higher and lower polynomial degrees within each grid cell.
- **Smoothers and Solvers**
	- **Jacobi:** Based on diagonal dominance of nodal basis representation. Used on all fine levels.
	- **Parallel Direct Solve:** Currently used on the coarsest level. Limits scalability.
	- **AMG:** Will be tested as a scalable replacement for Parallel Direct Solve.

References

- E. M. Ronquist and A. T. Patera, "Spectral Element Multigrid I: Formulation and Numerical Results," J. Sci. Comput. **2**, 4, 389-406 (1987).
- Y. Madera and R. Muñoz, "Spectral Element Multigrid II: Theoretical Justification," J. Sci. Comput. **3**, 4, 323-353 (1988).

Abstract Multigrid Algorithm

Abstract Elliptic Problem

Hilbert space H , bilinear elliptic form a, linear form g.

Find $v \in \mathcal{H}$ such that $\forall u \in \mathcal{H}$, $a(u, v) = g(u)$

Nested Finite-Dimensional Subspaces

 $\mathcal{M}_1 \subset \mathcal{M}_2 \subset \cdots \subset \mathcal{M}_j \subset \mathcal{H}$ Simplest case $j = 1, 2$. Find $v_j \in \mathcal{M}_j$ such that $\forall u \in \mathcal{M}_j$, $a(u, v_j) = g(u)$

Smoother

 $b(u, v) \approx a(u, v)$, but easier to solve, e.g. Jacobi smoother, $b \sim Diag(a)$.

Multigrid V-Cycle

- 1. $m/2$ smoother iterations. Find $S\varphi \in \mathcal{M}_2$ such that $\forall u \in \mathcal{M}_2, \quad a(u, \mathcal{S}\varphi - \varphi) = g(u) - a(u, \varphi)$
	-
- 2. Coarse correction. Find $\bar{\varphi} \in \mathcal{M}_1$ such that

$$
\forall u \in \mathcal{M}_1, \quad a(u, \mathcal{S}\varphi - \bar{\varphi}) = g(u) - a(u, \varphi), \quad \mathcal{C}\varphi \equiv \varphi + \bar{\varphi}
$$

3. $m/2$ smoother iterations.

Operator Expression

 $u^{1} = S^{m/2} C S^{m/2} u^{0}$

Convergence Theorem

Generalized Eigenvalue Problem

$$
\forall u \in \mathcal{M}_1, \quad a(u, \Psi_i) = \lambda_i b(u, \Psi_i)
$$

Rescale $b \rightarrow \frac{b}{\lambda_{\text{max}}}, \quad 0 < \lambda_1 \le \lambda_2 \le \cdots \le \lambda_P = 1$

Nesting Hypothesis

The fine space is the span of all P eigenvectors, $\mathcal{M}_2 = {\Psi_1, \Psi_2, \dots, \Psi_P}.$ The coarse space is the span of the lowest p eigenvectors, $\mathcal{M}_1 = {\Psi_1, \Psi_2, \dots, \Psi_p}.$

Convergence Theorem

Let $e^j \equiv u - u^j$, the error after the *j*th iteration.

 $a(e^1, e^1) \le (1 - \lambda_{p+1})^{2m} a(e^0, e^0)$

Interpretation

The largest "rough" eigenvalues, closest to 1, converge rapidly. The smallest "smooth" eigenvalues, closest to 0, converge slowly.

The coarse correction eliminates the smooth eigenvalues by transferring them to a coarse grid and solving exactly.

Coarsening and Refining

Lobatto Nodal Basis Functions

$$
u(x) = u_i \alpha_i(x), \quad x \in (-1, 1), \quad i = 0, \ldots, n
$$

$$
\alpha_i(x) \equiv \prod_{j \neq i} \left(\frac{x - \xi_j}{\xi_i - \xi_j} \right), \quad (1 - \xi_i^2) P_n^{(0,0)}(\xi_i) = 0
$$

Coarsening and Refining Operations

$$
u^m(x) = \sum_{i=0}^m u_i^m \alpha_i^m(x), \quad u^n(x) = \sum_{i=0}^n u_i^n \alpha_i^n(x), \quad m < n
$$

$$
C_{ij}^{mn} \equiv \alpha_i(\xi_j^n), \quad u_i^m = C_{ij}^{mn} u_j^n, \quad i = 0, \dots, m, \quad j = 0, \dots, n
$$

$$
\mathbf{C}^{mn} = \{C_{ij}^{mn}\}, \quad \mathbf{u}^m = \mathbf{C}^{mn} \mathbf{u}^n
$$

$$
\mathbf{R}^{nm} = (\mathbf{C}^{mn})^T, \quad \mathbf{u}^n = \mathbf{R}^{nm} \mathbf{u}^n
$$

Coarsener: evaluating fine basis functions at coarse nodes. Refiner is the transpose of the coarsener

1D Stiffness Matrix

Coarse and Fine Stiffness Matrices

$$
u, Lv) \equiv -\int_{-1}^{1} dx u \frac{\partial^2 v}{\partial x^2} = \int_{-1}^{1} dx \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} = u_i A_{ij} v_j
$$

$$
A_{ij}^m \equiv \int_{-1}^{1} dx \frac{\partial \alpha_i^m}{\partial x} \frac{\partial \alpha_j^m}{\partial x}, \quad i, j = 1, ..., m
$$

$$
A_{kl}^n \equiv \int_{-1}^{1} dx \frac{\partial \alpha_k^n}{\partial x} \frac{\partial \alpha_l^n}{\partial x}, \quad k, l = 1, ..., n
$$

$$
m < n, m = \text{coarse}, n = \text{fine}.
$$

Coarsening the Stiffness Matrix

Given the fine stiffness matrix, we can coarsen it with the refining matrix R .

 $u_i^m A_{ij}^m v_j^m = R_{ki}^{nm} u_i^m A_{kl}^n R_{lj}^{nm} v_j^m$

$$
A_{ij}^m = R_{ki}^{nm} A_{kl}^n R_{lj}^{nm}, \quad \mathbf{A}^m = (\mathbf{R}^{nm})^T \mathbf{A}^n \mathbf{R}^{nm}
$$

Analytical Test Case

1D Poisson Equation

$$
-u''(x) = g(x),
$$
 $u(x) = 0$ at $x = \pm 1$

Convergence Theorem

Using the Lobatto nodal basis functions of degree N , with the scaled diagonal matrix as the smoother, convergence for one element and 2 levels is given by

$$
a(u - u1, u - u1) = \mu a(u - u0, u - u0)
$$

$$
\mu = \left[1 - \frac{N+2}{2(N-1)}\right]^{2m}
$$

$$
\mu < 1 \text{ for } N > 2
$$

Implementation of SEMG in the 2D HiFi Code

- \triangleright SEMG is implemented in a Fortran 95 module, 3300 lines of new code written and tested.
- Uses PETSc library for distributed parallel operation and high-level matrix operations.
- \triangleright Fortran 95 derived types are defined for multigrid levels, diagonal blocks matrices, scatter contexts between native and PETSc vectors, and a full SEMG problem.
- Coarsening and refining use low-order (np+1) matrices **C** and **R**.
- Scaled diagonal Jacobian smoother uses low-order (nqty) matrix **D**.
- Jacobian scale factor, largest eigenvalue, is computed by power iteration.
- \triangleright Recursive Fortran 95 subroutine calls itself at successively coarser levels, with a full parallel direct solve on the coarsest level.
- \triangleright Highly modular code structure, facilitating easy modification, testing, and improvement.

Weak Parallel Scaling Study: Test Case

2D Poisson Equation

 $-\nabla^2 u(x, y) = \rho(x, y)$

Homogeneous Dirichlet Boundary Conditions

$$
u(0, y) = u(1, y) = u(x, 0) = u(x, 1) = 0
$$

Random Source Term and Initial Conditions

$$
\rho(x,y) = \sum_{m=1}^{m_{\text{max}}} \sum_{n=1}^{n_{\text{max}}} \rho_{mn} \sin\left(\frac{mx}{\pi}\right) \sin\left(\frac{ny}{\pi}\right)
$$

$$
u(x,y) = \sum_{m=1}^{m_{\text{max}}} \sum_{n=1}^{n_{\text{max}}} u_{mn} \sin\left(\frac{mx}{\pi}\right) \sin\left(\frac{ny}{\pi}\right)
$$

 ρ_{mn} and u_{mn} random

Weak Scaling Study

Hold the work per processor fixed.

Successively double n_x , n_y , m_{max} , and n_{max} and quadruple the number of paralllel cores.

V-cycle: polynomial degree $n_p = 8, 4, 2, 1, 2, 4, 8$

Jacobi iterations per multigrid level $= 3$ Multigrid cycles to 10^{-5} convergence = 27

Weak Parallel Scaling Study: Random Solutions

Initial State Final State 8° ∞ 6 \circ \geq $\overline{\mathcal{A}}$ > 4 \mathbf{C} \mathbf{C} \circ \circ $\boldsymbol{0}$ $\boldsymbol{0}$ $\frac{4}{x}$ 8 $\overline{2}$ 4 6 8 $\overline{2}$ 6 $\mathbf X$

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2010 APS/DPP Meeting, Glasser & Lukin, Slide 11

Summary and Future Work

- \triangleright Formulation and implementation of SEMG are general.
- \triangleright Tested for scalability on the 2D Poisson equation.
- \triangleright Improvements to be studied:
	- More scalable alternative to the direct coarse solve, *e.g.* AMG.
	- More general boundary conditions.
- \triangleright Following this, it will be tested on:
	- Simple linear 2D wave equation.
	- Ideal MHD waves in a periodic plane.
	- GEM challenge problem.
- After completion of 2D development, it will be ported to the 3D HiFi and M3D-C1 codes. The latter will require the development of a different coarsener.

