A Study of Linear Ideal MHD Waves with the SEL Spectral Element Code

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Ideas That Change the World

Presented at the CEMM Meeting Missoula, Montana, April 25, 2004

Ideal MHD Waves

$$\beta \equiv \frac{P}{2\mu_0 B^2}, \quad \gamma = \frac{5}{3}, \quad \cos \theta \equiv \frac{\mathbf{k} \cdot \mathbf{B}}{kB}$$
$$c_A^2 \equiv \frac{B^2}{\mu_0 \rho}, \quad c_S^2 \equiv \frac{\gamma P}{\rho}, \quad \frac{c_A^2}{c_s^2} = \frac{\gamma \beta}{2}, \quad v \equiv \frac{\omega}{k}$$
$$v_{\pm}^2 = \frac{1}{2} \left\{ \left(c_A^2 + c_S^2 \right) \pm \left[\left(c_A^2 + c_S^2 \right)^2 - 4c_A^2 c_S^2 \cos^2 \theta \right]^{1/2} \right\}, \quad v_A^2 = c_A^2 \cos^2 \theta$$

Friedrichs Diagram, $\beta = 10\%$



Consequences

For
$$\mathbf{k} \cdot \mathbf{B} \rightarrow 0$$
, $\omega_{-}, \omega_{A} \ll \omega_{+}$

These lowest-frequency modes are the most easily destabilized by small effects like pressure gradients, bootstrap currents, and resistivity. Accurate treatment of such subtle effects requires accurate representation of

$$k_{||} << a,R << k_{\perp}$$

Spatial Discretization

Flux-Source Form of Equations

$$\frac{\partial u^i}{\partial t} + \nabla \cdot \mathbf{F}^i = S^i$$

$$\mathbf{F}^i = \mathbf{F}^i(t, \mathbf{x}, u^j, \nabla u^j)$$

$$S^i = S^i(t, \mathbf{x}, u^j, \nabla u^j)$$

Galerkin Expansion

$$u^{i}(t, \mathbf{x}) \approx \sum_{j=0}^{n} u_{j}^{i}(t) \alpha_{j}(\mathbf{x})$$

Weak Form of Equations

$$(\alpha_i, \alpha_j)\dot{u}_j^k = \int_{\Omega} d\mathbf{x} \left(S^k \alpha_i + \mathbf{F}^k \cdot \nabla \alpha_i \right) - \int_{\partial \Omega} d\mathbf{x} \alpha_i \mathbf{F}^k \cdot \hat{\mathbf{n}}$$

Alternative Polynomial Bases





- Uniformly-spaced nodes
- Diagonally subdominant



- Lagrange interpolatory polynomials
- Nodes at roots of $(1-x^2) P_n^{(0,0)}(x)$
- Diagonally dominant

Spectral (Modal) Basis



- Jacobi polynomials (1+x)/2, (1-x)/2, (1-x²) P_n^(1,1)(x)
- Nearly orthogonal
- Manifest exponential convergence

Fully Implicit Newton-Krylov Time Step

 $M\dot{u} = r$

$$\mathbf{M}\left(\frac{\mathbf{u}^{+}-\mathbf{u}^{-}}{h}\right) = \theta \mathbf{r}^{+} + (1-\theta)\mathbf{r}^{-}$$
$$\mathbf{R}\left(\mathbf{u}^{+}\right) \equiv \mathbf{M}\left(\mathbf{u}^{+}-\mathbf{u}^{-}\right) - h\left[\theta \mathbf{r}^{+} + (1-\theta)\mathbf{r}^{-}\right] = 0$$
$$\mathbf{J} \equiv \mathbf{M} - h\theta \left\{\frac{\partial r_{i}^{+}}{\partial u_{j}^{+}}\right\}$$

 $\mathbf{R} + \mathsf{J}\delta \mathbf{u}^{+} = \mathbf{0}, \quad \delta \mathbf{u}^{+} = -\mathsf{J}^{-1}\mathbf{R}\left(\mathbf{u}^{+}\right), \quad \mathbf{u}^{+} \to \mathbf{u}^{+} + \delta \mathbf{u}^{+}$

- Nonlinear Newton-Krylov iteration.
- Elliptic equations: $\mathbf{M} = 0$.
- Static condensation, fully parallel.
- PETSc: GMRES with Schwarz ILU, overlap of 3, fill-in of 5.

Static Condensation

$$\mathbf{L}\mathbf{u} = \mathbf{r} \tag{1}$$

Partition: (1) element edges: (2) element interiors

$$\mathbf{u} = \begin{pmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \end{pmatrix}, \quad \mathbf{r} = \begin{pmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \end{pmatrix}, \quad \mathbf{L} = \begin{pmatrix} \mathbf{L}_{11} & \mathbf{L}_{12} \\ \mathbf{L}_{21} & \mathbf{L}_{22} \end{pmatrix}$$
(2)

$$\mathbf{L}_{11}\mathbf{u}_1 + \mathbf{L}_{12}\mathbf{u}_2 = \mathbf{r}_1 \tag{3}$$

$$\mathbf{L}_{22}\mathbf{u}_2 = \mathbf{r}_2 - \mathbf{L}_{21}\mathbf{u}_1 \tag{4}$$

$$\bar{\mathbf{r}}_{11} \equiv \mathbf{L}_{11} - \mathbf{L}_{12} \mathbf{L}_{22}^{-1} \mathbf{L}_{21}$$

$$\bar{\mathbf{r}}_{1} \equiv \mathbf{r}_{1} - \mathbf{L}_{12} \mathbf{L}_{22}^{-1} \mathbf{r}_{2}$$
(5)

$$\bar{\mathbf{L}}_{11}\mathbf{u}_1 = \bar{\mathbf{r}}_1 \tag{6}$$

Equation (4) solved by local LU factorization and back substitution.
Equation (6), substantially reduced, solved by global Newton-Krylov.

Linear Ideal MHD

 $\mathbf{B} = (\sin\theta\cos\phi, \ \sin\theta\sin\phi, \ \cos\theta)$

$$\rho \frac{\partial \mathbf{v}}{\partial t} = \mathbf{j} \times \mathbf{B} - \nabla p, \quad \mathbf{j} = \nabla \times \mathbf{b}$$
$$\frac{\partial \mathbf{b}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}), \quad \nabla \cdot \mathbf{b} = 0$$
$$\frac{\partial p}{\partial t} + \gamma P \nabla \cdot \mathbf{v} = 0, \quad \mathbf{b} = b_z \hat{\mathbf{z}} + \hat{\mathbf{z}} \times \nabla \psi$$

Flux-Source Form

 $\mathbf{u} \equiv (\rho v_x, \ \rho v_y, \ \rho v_z, \ \psi, \ b_z, \ p)$

 $\frac{\partial}{\partial t} \left(\rho \mathbf{v} \right) + \nabla \cdot \mathbf{T} = 0, \quad \mathbf{T} \equiv \left(p + \mathbf{b} \cdot \mathbf{B} \right) \mathbf{I} - \left(\mathbf{b} \mathbf{B} + \mathbf{B} \mathbf{b} \right)$

$$\frac{\partial \psi}{\partial t} = \hat{\mathbf{z}} \cdot \mathbf{v} \times \mathbf{B}, \quad \frac{\partial b_z}{\partial t} + \nabla \cdot (\mathbf{v}B_z - \mathbf{B}v_z) = 0$$

$$\frac{\partial p}{\partial t} + \nabla \cdot (\gamma P \mathbf{v}) = 0$$

Frequencies and Polarizations

$$\begin{aligned} \frac{\partial^2 \mathbf{v}}{\partial t^2} &= c_A^2 \left\{ \nabla \times \left[\nabla \times (\mathbf{v} \times \mathbf{n}) \right] \right\} \times \mathbf{n} + c_S^2 \nabla \nabla \cdot \mathbf{v} \\ \mathbf{v}(\mathbf{x}, t) &= \mathbf{v}_0 \exp \left[i \left(\mathbf{k} \cdot \mathbf{x} - \omega t \right) \right], \quad \mathbf{L} \cdot \mathbf{v}_0 = 0 \\ \mathbf{L} &= c_A^2 \left[k_{\parallel}^2 \mathbf{l} - k_{\parallel} (\mathbf{kn} + \mathbf{nk}) + \mathbf{kk} \right] + c_S^2 \mathbf{kk} - \omega^2 \mathbf{l} \\ \det \mathbf{L} &= \left(k_{\parallel}^2 c_A^2 - \omega^2 \right) \left[k^2 k_{\parallel}^2 c_A^2 c_S^2 - \omega^2 k^2 \left(c_A^2 + c_S^2 \right) + \omega^4 \right] = 0 \\ \hat{\mathbf{e}}_1 &\equiv \mathbf{n} = \frac{\mathbf{B}}{B}, \quad \hat{\mathbf{e}}_2 &\equiv \frac{\mathbf{k} \times \mathbf{B}}{|\mathbf{k} \times \mathbf{B}|}, \quad \hat{\mathbf{e}}_3 &\equiv \hat{\mathbf{e}}_1 \times \hat{\mathbf{e}}_2, \quad \mathbf{B} = B \hat{\mathbf{e}}_1, \quad \mathbf{k} = k_{\parallel} \hat{\mathbf{e}}_1 + k_{\perp} \hat{\mathbf{e}}_3 \\ \mathbf{L} &= \left(c_A^2 k_{\parallel}^2 - \omega^2 \right) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \left(c_A^2 + c_S^2 \right) \begin{pmatrix} k_{\parallel}^2 & 0 & k_{\parallel} k_{\perp} \\ 0 & 0 & 0 \\ k_{\parallel} k_{\perp} & 0 & k_{\perp}^2 \end{pmatrix} - c_A^2 k_{\parallel} \begin{pmatrix} 2k_{\parallel} & 0 & k_{\perp} \\ 0 & 0 & 0 \\ k_{\perp} & 0 & 0 \end{pmatrix} \end{aligned}$$

For
$$\omega^2 = c_A^2 k_{\parallel}^2$$
, $\mathbf{v}_0 = (0, 1, 0)$

For
$$\omega^2 = \frac{1}{2} \left\{ \left(c_A^2 + c_S^2 \right) k^2 \pm \left[\left(c_A^2 + c_S^2 \right)^2 k^4 - 4 c_A^2 c_S^2 k^2 k_{\parallel}^2 \right]^{1/2} \right\}, \quad \mathbf{v}_0 = (v_{\parallel}, 0, 1), \quad v_{\parallel} \equiv \frac{c_S^2 k_{\parallel} k_{\perp}}{\omega^2 - c_S^2 k_{\parallel}^2}$$

Selection of Parameters

Domain: x, y = (0,1); wave numbers: $kx = ky = 2\pi$.

→ Grid parameters: (nx, ny, np, procs) = (8, 8, 2, 8), (4, 4, 4, 8), (2, 2, 8, 4).

> Magnetic field: spherical coordinates about z axis:

- $Bx = \sin \theta \cos \phi$, $By = \sin \theta \cos \phi$, $Bz = \cos \theta$
- $\theta = 90^{\circ}$ (in x-y plane), $\phi \rightarrow 135^{\circ}$ (approaching transverse propagation).

≻ Beta: 10%.

- > Time: tmax = shear Alfven period, dt = tmax/64, nt = 64, polarization = Shear Alfven.
- > Solution procedure: GMRES, ILU-5 preconditioning + static condensation for np > 2.

> Reported Results

- Ksp: number of GMRES iterations in 64 time steps
- Cpu: run time on Linux cluster, 3.1 GHz Xeons, Gigabit network
- Errt: relative error in wave period.
- Errx: relative spatial truncation error, from convergence of polynomials
- CFL: Courant number relative to fast wave frequency, $\omega_f dt$.

Measurement of Wave Period



Summary of Numerical Results

➤ (nx, ny, np, procs) = (8, 8, 2, 8)

- No static condensation
- For $\varphi = 130, 131, 132, 133$:
 - o Ksp = 770, 1023, 1472, 2792
 - o Cpu = 8.6, 9.9, 13.4, 22.7 s
- Errx = 10%, Errt ~ 8×10^{-4} , CFL = 2.9
- ➤ (nx, ny, np, procs) = (4, 4, 4, 8)
 - Static condensation
 - For $\phi = 130 134.9999$
 - o Ksp = 64 128
 - o Cpu $\sim 4 s$
 - Errx ~ $3x10^{-4}$, Errt ~ $8x10^{-4}$, CFL = $5x10^{4}$
- ➤ (nx, ny, np, procs) = (2, 2, 8, 4)
 - Static condensation
 - For $\phi = 130 134.9999$:
 - o Ksp = 64 137
 - o Cpu $\sim 6 8$ s
 - Errx ~ 10^{-8} , Errt ~ $8x10^{-4}$, CFL = $5x10^{4}$

Conclusions

- ➢ Accurate computation of shear Alfven and slow waves as $\mathbf{k} \cdot \mathbf{B} \rightarrow 0$ is essential for study of tokamak stability.
- > Stiffness makes this numerically challenging.
 - Explicit methods require very small time steps.
 - Implicit methods have very large condition numbers.
- Spectral elements provide rapid convergence + parallelization.
- Static condensation is very effective in treating large condition numbers.
- Precise study of linear wave motion provides an important test bed for numerical properties.