

*SCIDAC Center for Extended MHD Modeling*

# **ISSUES RELATED TO INTEGRATED MODELING IN FUSION SCIENCE**

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# OVERVIEW

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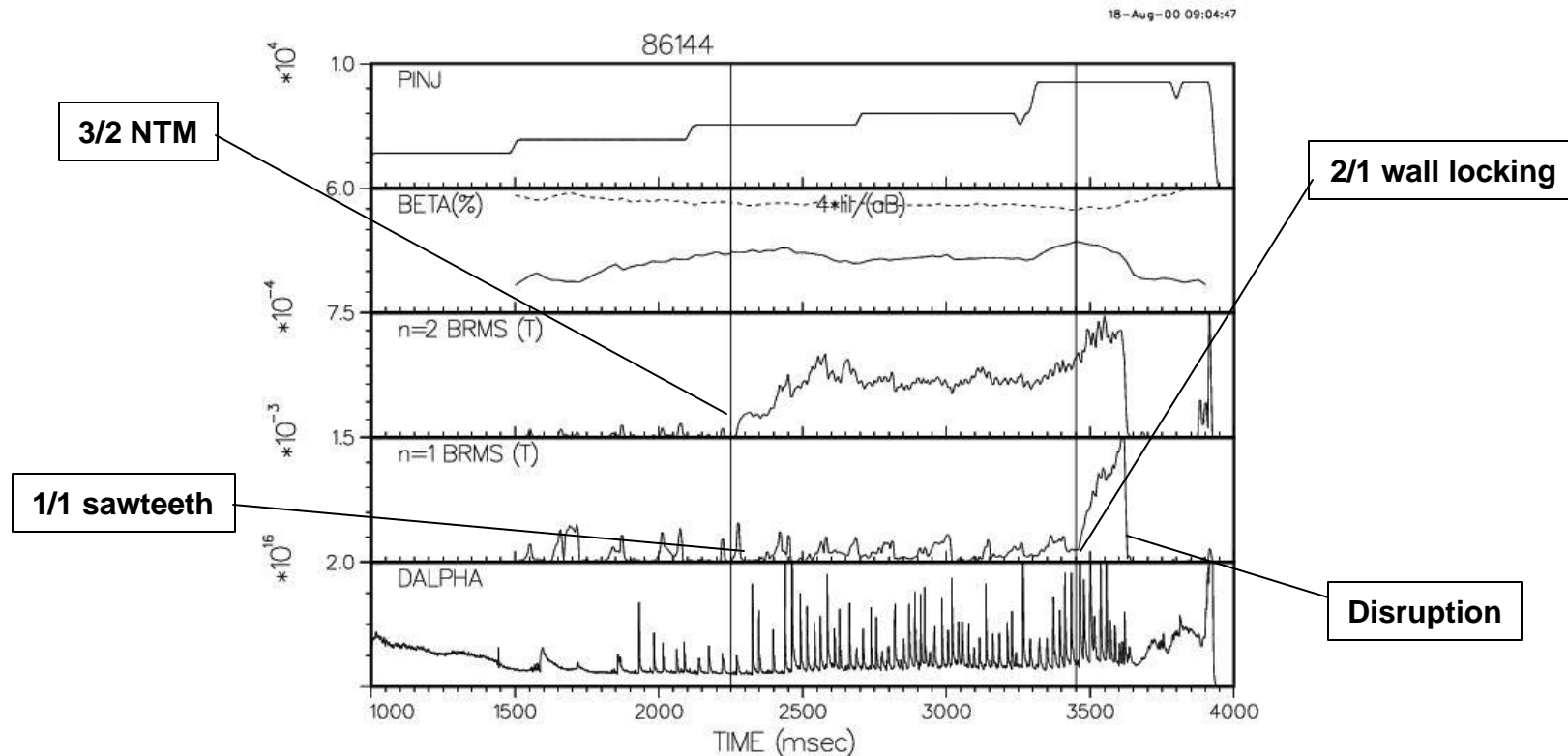
- **Goal of integrated modeling**
  - A predictive simulation model of fusion plasma dynamics with realistic parameters and geometry
- **Constraints imposed by physics, algorithms, and hardware**
  - 3-D fluid-based model is only practical approach
  - More detailed physics, longer time scale models must be integrated into this central module
- **The computational challenges of fluid model:**
  - Extreme separation of time scales
  - Extreme separation of spatial scales
  - Extreme anisotropy
  - Importance of geometry, boundary conditions
  - Causality: *can't parallelize over time!*

***At least a challenging as hydrodynamic turbulence!***
- **Present computational approaches:**
  - Implicit time differencing
  - Specialized spatial grids
- **Status of present models**
- **Vision for integrated modeling**



# DESIRED PREDICTABILITY: MODAL DYNAMICS

Example: DIII-D shot 86144

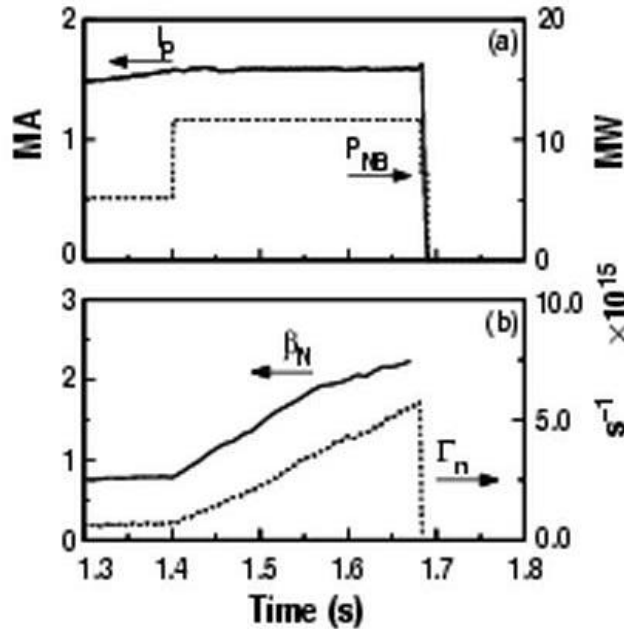


- Sawtooth discharge
- 3/2 NTM triggered at 2250 msec
- 2/1 locks to the wall

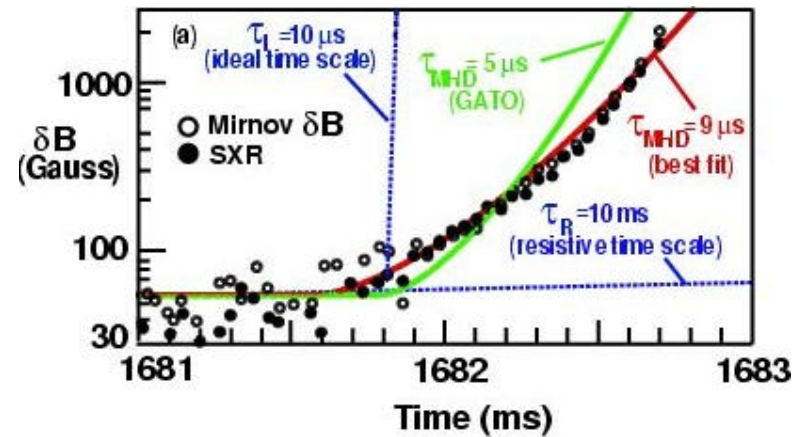


# DESIRED PREDICTABILITY: DISRUPTION

Example: DIII-D shot 87009



- Increase in neutral beam power
- Plasma pressure increases
- Sudden termination (disruption)



- Time dependence at disruption onset
- Growing 3-D magnetic perturbation
- Nonlinear evolution?
- Effect on confinement?
- Can this be predicted?



# PREDICTIVE MODEL OF PLASMA DYNAMICS

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- **Magnetic perturbations**  
**Electromagnetic model**
- **Slow evolution**  
**1 msec. - 1 sec. problem time**
- **Plasma shaping**  
**Realistic geometry required**
- **High temperature**  
**Large “Reynolds’ numbers”**
- **Low collisionality**  
**Kinetic (velocity space) physics affects global evolution**
- **Strong magnetic field**  
**Dynamics are highly anisotropic**
- **Resistive wall**  
**Non-ideal boundary conditions**
- **Sources**  
**RF and beam interaction with plasma for heating, current drive**
- **Engineering calculations**  
**Heat loads, stresses, etc.**



# FUSION SCIENCE MODELS

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- **Source models (*fastest time scales; light waves*)**
  - Interaction of RF waves or neutral beams with static 2-D background plasma
  - Sources of heat, mass, and electric field
- **Global kinetic models (*first-principles; particle time scales*)**
  - Solve kinetic (“gyrokinetic”) equations
  - 5 dimensional (3 space, 2 velocity) + time
  - Provide direct calculation of anomalous transport
- **Fluid (MHD) models (*low frequency; no particles*)**
  - 3 space dimensions (*realistic geometry*)
  - Single fluid (*lumped ions and electrons*)
  - Time dependent, temporally very stiff
  - No kinetic (particle) effects
- **Extended fluid models (*fluid; non-conventional closures*)**
  - Separate fluids for ions and electrons
  - Non-fluid effects through low dimensional or analytic “closures”
- **Transport models (*long time scale; low dimensionality; no inertia*)**
  - “1.5” dimensional, axisymmetric geometry
  - Time dependent, long time evolution
  - No waves: force balance + diffusion with sources

*Disparate models must be “integrated” for predictive capability*



# A CONSTRAINT ON ALGORITHMS

Balance of algorithm performance and model requirements with available cycles

$$\underbrace{\frac{N^a Q}{\Delta t}}_{\text{Algorithms}} = 3 \times 10^7 \underbrace{\frac{eP}{CT}}_{\text{Constraints}}$$

## Algorithms:

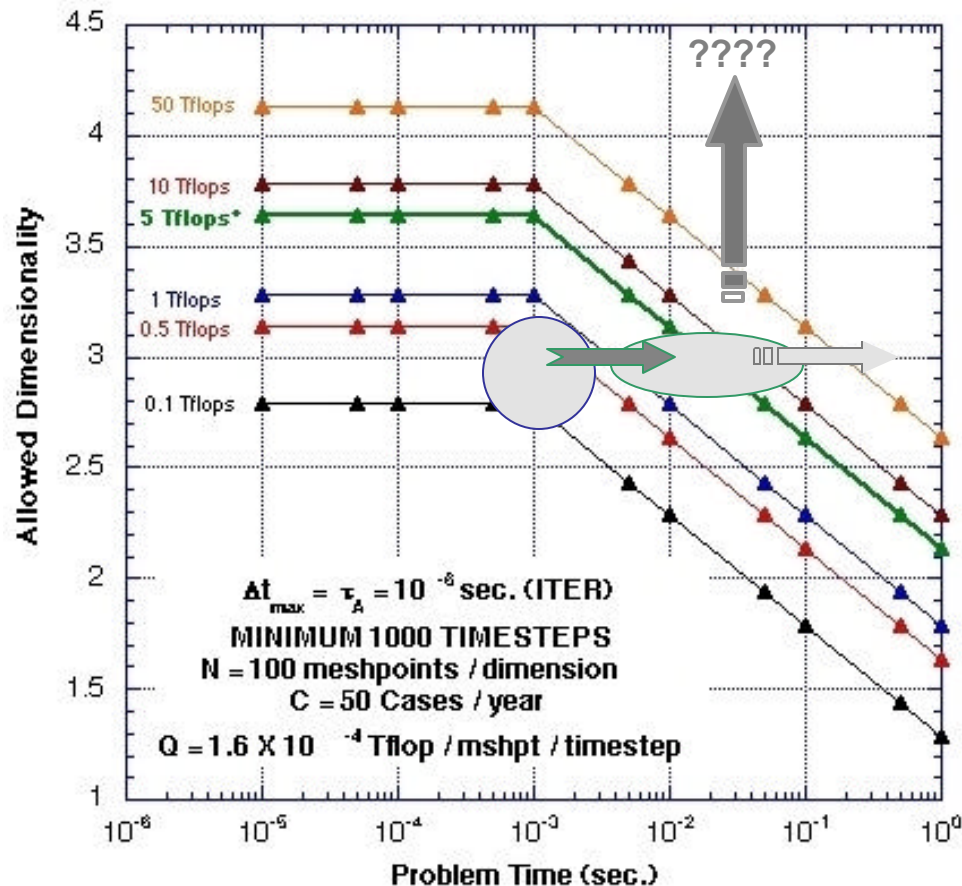
- $N$  - # of meshpoints for each dimension
- $a$  - # of dimensions
  - 1.5 - transport
  - 3 (spatial) fluid
  - 5-6 kinetic (spatial + velocity)
- $Q$  - code-algorithm requirements (Tflop / meshpoint / timestep)
- $\Delta t$  - time step (seconds)

## Constraints:

- $P$  - peak hardware performance (Tflop/sec)
- $e$  - hardware efficiency
  - $eP$  - delivered sustained performance
- $T$  - problem time duration (seconds)
- $C$  - # of cases / year
  - 1 case / week  $\implies C \sim 50$



# PERFORMANCE CONSTRAINTS



## Assumptions:

- Performance is *delivered*
- Implicit algorithm
- Q ind. of  $\Delta t$  (!!)

## Requirements:

- At least 3-D physics required
- Required problem time: 1 msec - 1 sec

## Conclusions:

- 3-D (i.e., fluid) calculations for times of  $\sim 10$  msec within reach
- Longer times require next generation computers (or better algorithms)
- Higher dimensional (kinetic) long time calculations unrealistic
- Integrated kinetic effects must come through low dimensionality fluid closures

**3-D extended fluid calculation must form basis of integrated model**





## A 3-D FLUID BASED MODEL FOR INTEGRATION

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- ***Cannot afford higher dimensionality for experimental time scales!***
- **Capture kinetic effects through 2-fluid closures**
  - Analytic
  - Heuristic
  - Minority species (e.g., energetic ions)
- **Can represent vacuums, realistic geometry and boundary conditions**
- **Produces data necessary for other integration components**
  - ***Edge models***
    - Details of specialized plasma regions
  - ***Kinetic theory models***
    - First principles tests of closures and sub-grid scale physics
  - ***Source models***
    - Details of heating and fueling
  - ***Transport models***
    - Longer time scale evolution
  - ***Engineering models***
    - Stresses on components, etc.



# CLOSURES FOR FLUID MODELS

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- Kinetic models of plasmas based on distribution function for each charge species
- Satisfies *kinetic equation*

$$\frac{df_a}{dt} = \sum_b C[f_a, f_b]$$

$f_a(\mathbf{x}, \mathbf{v}, t)$  - six dimensions plus time  
- computationally impractical for time scales of interest

- *Fluid models* derived by taking successive velocity moments of kinetic equation
  - Reduce dimensionality by 3
- Hierarchy of equations for  $n, \mathbf{v}, \rho, P, \mathbf{q}, \dots$
- Equations truncated by closure relations
  - Express high order moments in terms of low order moments
  - Capture *kinetic effects* in these moments



## 2-FLUID MODEL

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- Maxwell (no displacement current):

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E} \quad , \quad \nabla \times \mathbf{B} = \mu_0 \mathbf{J} \quad ,$$

- Momentum, energy, and continuity for each species ( $a = e, i$ ):

$$m_a n_a \left( \frac{\partial \mathbf{v}_a}{\partial t} + \mathbf{v}_a \cdot \nabla \mathbf{v}_a \right) = -\nabla \cdot \mathbf{P}_a + q_a n_a (\mathbf{E} + \mathbf{v}_a \times \mathbf{B}) + \sum_b \mathbf{R}_{ab} + \mathbf{S}_a^m$$

$$\frac{\partial p_a}{\partial t} + \mathbf{v}_a \cdot \nabla p_a = -\frac{3}{2} p_a \nabla \cdot \mathbf{v}_a - \mathbf{P}_a : \nabla \mathbf{v}_a - \nabla \cdot \mathbf{q}_a + \mathbf{Q}_a$$

$$\frac{\partial n_a}{\partial t} = -\nabla \cdot (n_a \mathbf{v}_a) + S_a^n$$

- Current and quasi-neutrality:

$$\mathbf{J}_a = n_a q_a \mathbf{v}_a, \quad n = n_e = Z n_i$$



## SINGLE FLUID FORM

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- Add electron and ion momentum equations:

$$\rho \left( \frac{d\mathbf{v}}{dt} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla \cdot \mathbf{P}' + \mathbf{J} \times \mathbf{B}$$

- Subtract electron and ion momentum equations (Ohm's law):

$$\mathbf{E} = - \underbrace{\mathbf{v} \times \mathbf{B}}_{\text{Ideal MHD}} + \underbrace{\frac{h\mathbf{J}}{ne}}_{\text{Resistive MHD}} + \underbrace{\frac{1-n}{ne(1+n)} \mathbf{J} \times \mathbf{B}}_{\text{Hall Effect}}$$

$$- \underbrace{\frac{1}{ne(1+n)} \nabla \cdot (\mathbf{P}'_e - n\mathbf{P}'_i)}_{\text{Diamagnetic Effects and Closures}} + \underbrace{\frac{1}{e_0 \omega_{pe}^2 (1+n)} \left[ \frac{d\mathbf{J}}{dt} + \nabla \cdot (\mathbf{v}\mathbf{J} + \mathbf{J}\mathbf{v}) \right]}_{\text{Electron Inertia}}$$

**All effects beyond resistivity constitute Extended MHD**



# COMPUTATIONAL CHALLENGES

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- ***Extreme separation of time scales***
  - Realistic “Reynolds’ numbers”
  - Implicit methods
- ***Extreme separation of spatial scales***
  - Important physics occurs in internal boundary layers
  - Small dissipation cannot be ignored
  - Requires grid packing or adaptation
- ***Extreme anisotropy***
  - Special direction determined by magnetic field
  - Accurate treatment of  $\mathbf{B} \cdot \nabla$  operator is important*
  - Requires specialized gridding

***At least as challenging as hydrodynamic turbulence!***



# 1. SEPARATION OF TIME SCALES

$$\underbrace{t_A}_{\text{Affvén transit time}} < \underbrace{t_S}_{\text{Sound transit time}} \ll \underbrace{t_{\text{evol}}}_{\text{MHD evolution time}} \ll \underbrace{t_R}_{\text{Resistive diffusion time}}$$

Lundquist number:  $S = \frac{t_R}{t_A} \sim 10^8 \gg 1$

Explicit time step impractical:

$$\Delta t < \frac{\Delta x}{L} t_A \approx \frac{t_A}{N} \llll t_{\text{evol}}$$

**Require implicit methods**



# IMPLICIT METHODS

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- **Partially implicit methods**
  - Treat fastest time scales implicitly
  - Time step still limited by waves
- **Semi-implicit methods**
  - Treat linearized ideal MHD operator implicitly
  - Time step limited by advection
  - Many iterations
- **Fully implicit methods**
  - Newton-Krylov treatment of full nonlinear equations
  - Arbitrary time step
  - Still a research project



## EXAMPLE: IDEAL MHD

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$$\mathbf{r}_0 \frac{\eta^2 \mathbf{v}}{\eta t^2} = \nabla \times \nabla \times (\mathbf{v} \times \mathbf{B}_0) \times \mathbf{B}_0$$

- Linearized, ideal MHD wave equation
- Wide spectrum of normal modes
- Highly anisotropic spatial operator
- Basis of many implicit formulations
- *Not* a simple Laplacian
- Requires specialized pre-conditioners

***Challenge: find optimum algorithm for inverting this operator  
with CFL ~ 1000***





# LINEAR SOLVER REQUIREMENTS

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- **Extremely large condition number :  $> 10^{10}!!$** 
  - **Specialized pre-conditioners**
  - **Anisotropy**
- **Ideal MHD is self-adjoint**
  - **Symmetric matrices**
  - **CG**
- **Advection and some 2-fluid effects (whistler waves) are not self-adjoint**
  - **Need for efficient non-symmetric solvers**
- **Everything must be efficient and scalable in parallel**
- **Should interface easily with F90**



## 2. SEPARATION OF SPATIAL SCALES

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- Important dynamics occurs in internal boundary layers
  - Structure is determined by plasma resistivity or other dissipation
  - Small dissipation cannot be ignored
- Long wavelength along magnetic field
- Extremely localized across magnetic field:

$$d/L \sim S^{-a} \ll 1 \text{ for } S \gg 1$$

- It is these long, thin structures that evolve nonlinearly on the slow evolutionary time scale



### 3. EXTREME ANISOTROPY

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- Magnetic field locally defines special direction in space
- Important dynamics are extended along field direction, very narrow across it
- Propagation of normal modes (waves) depends strongly on local field direction
- Transport (heat and momentum flux) is also highly anisotropic

==> Requires accurate treatment of operator  $\mathbf{B} \cdot \nabla$

***Inaccuracies lead to “spectral pollution” and anomalous perpendicular transport***



# GRIDDING AND SPATIAL REPRESENTATION

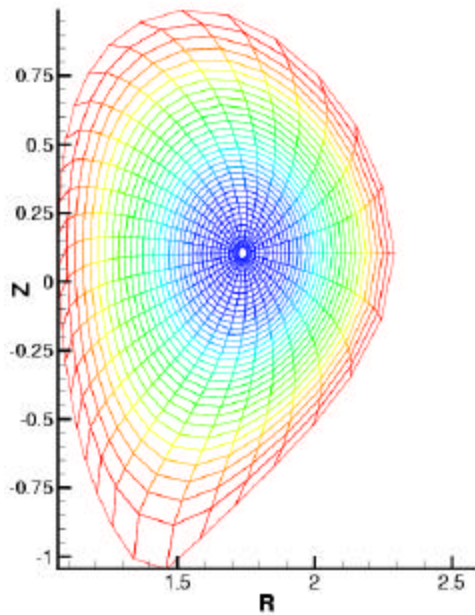
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- **Spatial stiffness and anisotropy require special gridding**
  - Toroidal and poloidal dimensions treated differently
- **Toroidal ( $f$ , primarily along field)**
  - Long wavelengths, periodicity => FFTs (finite differences also used)
- **Poloidal plane ( $R, Z$ )**
  - Fine structure across field direction
  - Grids aligned with flux surfaces ( $\sim$  field lines)
  - Unstructured triangular grids
  - Extreme packing near internal boundary layers
- **Finite elements**
  - High order elements essential for resolving anisotropies
- **Dynamic mesh adaptation in research phase**

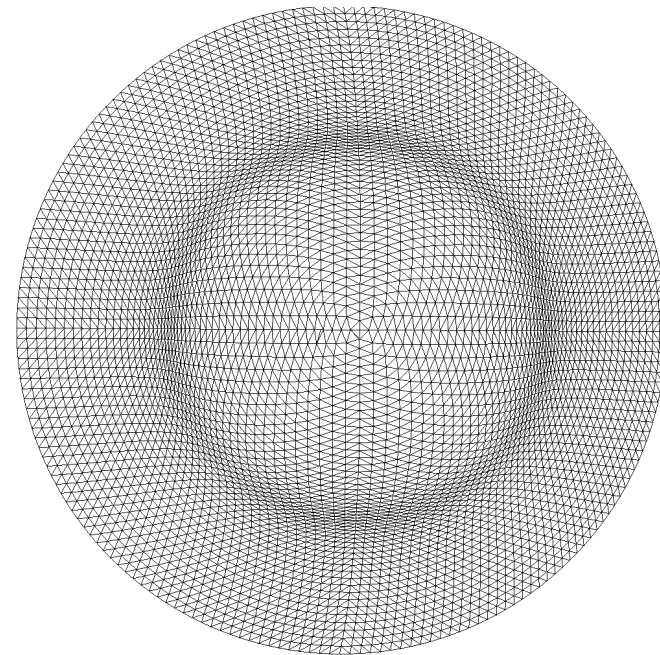


# POLOIDAL GRIDS

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**DIII-D poloidal cross-section with  
flux aligned grid (NIMROD)**



**Circular poloidal cross-section with  
triangles and grid packing (M3D)**

**Poloidal grids from SciDAC development projects**



## BEYOND RESISTIVITY - EXTENDED MHD

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- **2-fluid effects**
  - Whistler waves (Hall term) require implicit advance with non-symmetric solver
  - Electron inertia treated implicitly
  - Diamagnetic rotation may cause accuracy, stability problems
- **Kinetic effects - influence of non-Maxwellian populations**
  - Analytic closures
    - Seek *local* expressions for  $P$ ,  $q$ , etc.
  - Particle closures
    - Subcycle gyrokinetic  $df$  calculation
    - Minority ion species - beam or  $\alpha$ -particles



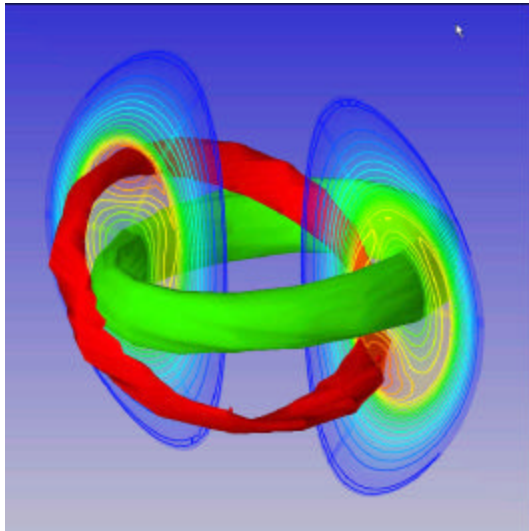
# STATUS

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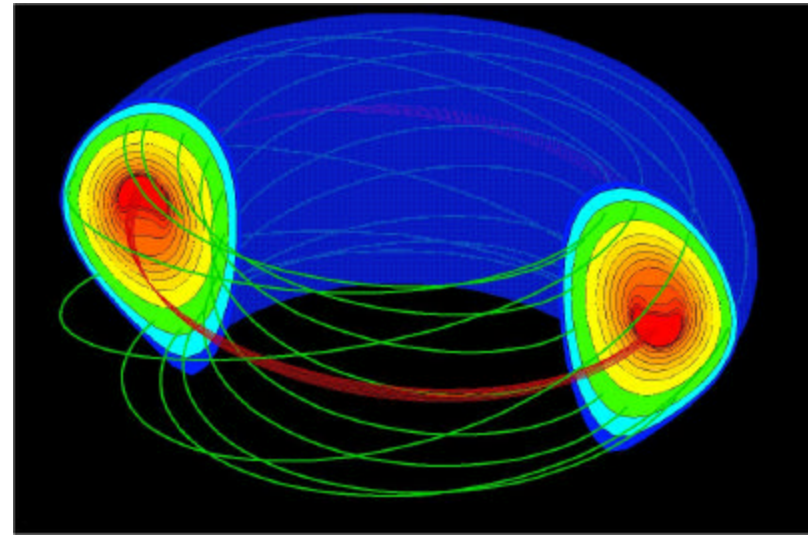
- 2 major SciDAC development projects for time-dependent models
  - M3D - multi-level, 3-D, parallel plasma simulation code
    - Partially implicit
    - Toroidal geometry - suitable for stellarators
    - 2-fluid model
    - Neo-classical and particle closures
  - NIMROD - 3-D nonlinear extended MHD
    - Semi-implicit
    - Slab, cylindrical, or axisymmetric toroidal geometry
    - 2-fluid model
    - Neo-classical closures
    - Particle closures being implemented
- *Both codes have exhibited good parallel performance scaling*
- Other algorithms are being developed in the fusion program



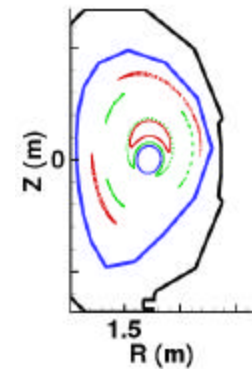
# STATUS - RESISTIVE MHD



Sawtooth in NSTX computed by M3D

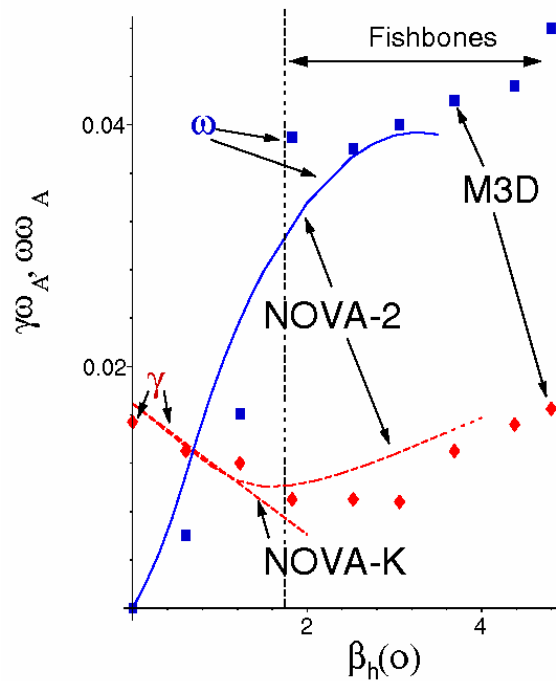


Secondary magnetic islands generated during sawtooth crash in DIII-D shot 86144 by NIMROD

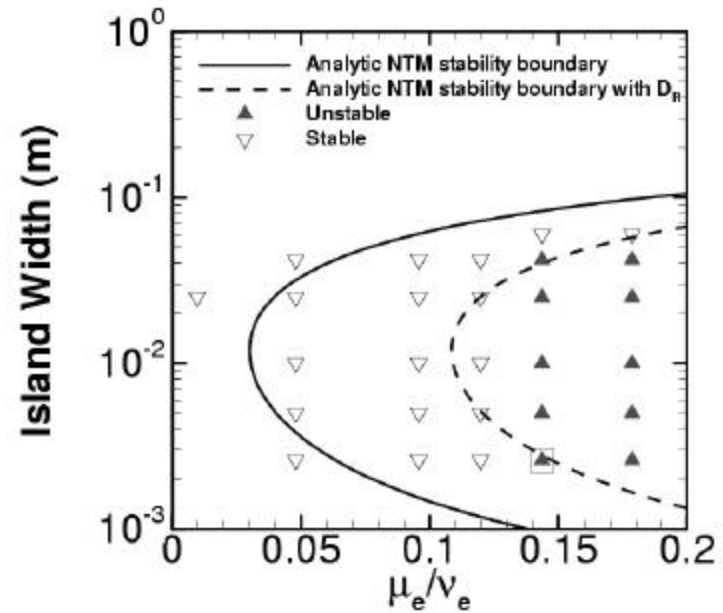




# STATUS - EXTENDED MHD



- Effect of energetic particles on MHD instability
- Subcycling of kinetic calculation



- Effect of trapped electrons and ions on resistive stability
- Analytic/heuristic fluid closure



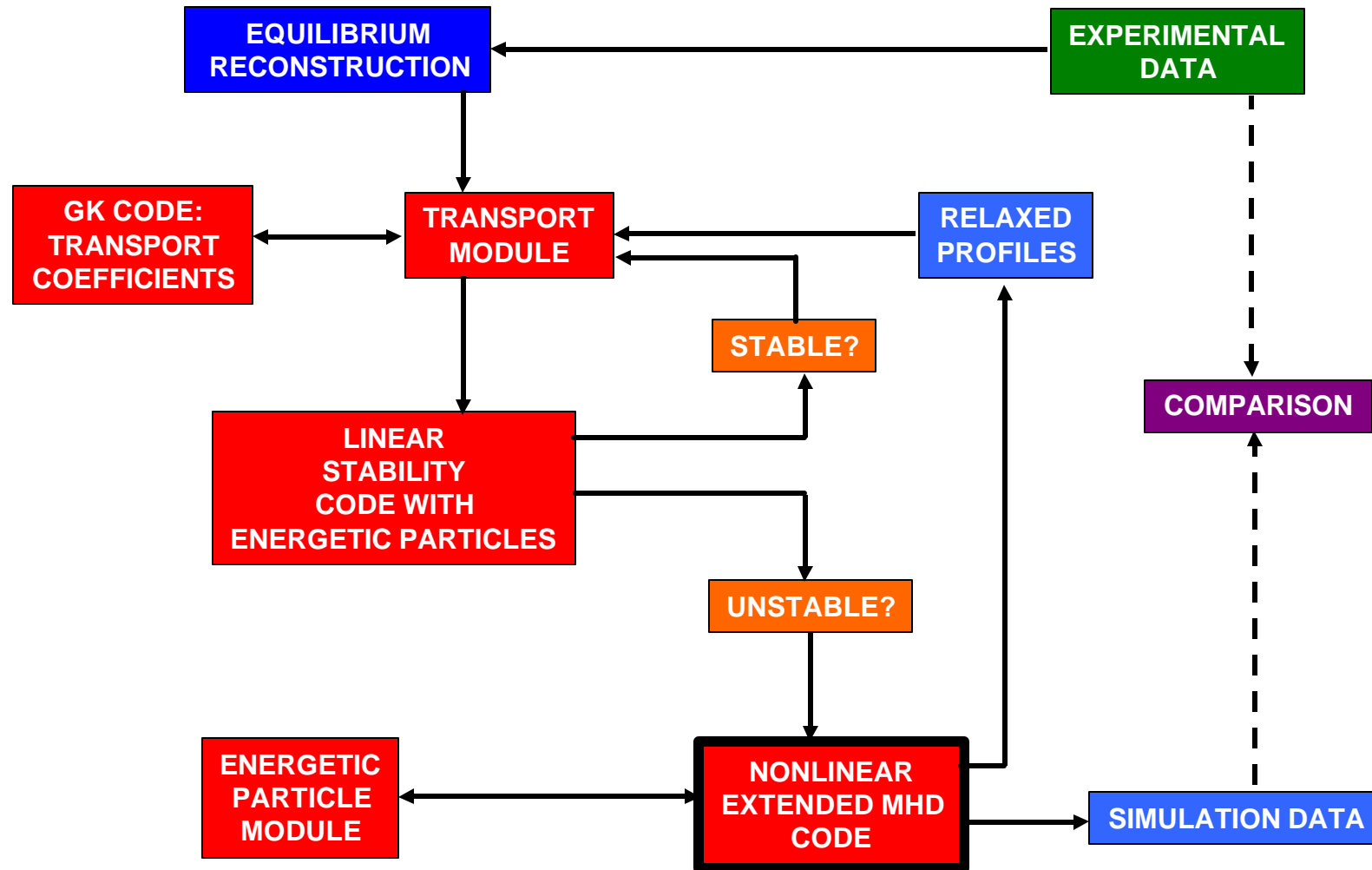
## NEXT STEP - INTEGRATED MODELING

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- ***Non-local kinetic physics, MHD, and profile evolution are all inter-related***
  - Kinetic physics determines transport coefficients
  - Transport coefficients affect profile evolution
  - Profile evolution can destabilize of MHD modes
  - Kinetic physics can affect nonlinear MHD evolution (NTMs, TAEs)
  - MHD relaxation affects profile evolution
  - Profiles affect kinetic physics
- ***Effects of kinetic (sub grid scale) physics must be synthesized into MHD models***
  - Extensions to Ohm's law (2-fluid models)
  - Subcycling/code coupling
  - Theoretical models (closures), possibly heuristic
- ***Effects of MHD must be synthesized into transport models***
- ***Predictions must be validated with experimental data***



# VISION: SAWTOOTH CYCLE



# ENABLING COMPUTER SCIENCE TECHNOLOGIES

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- ***Largest, fastest computers!***
  - But intermediate computational resources often neglected, and...
  - ***The computers will never be large or fast enough!***
- ***Algorithms***
  - Parallel linear algebra
  - Gridding, adaptive and otherwise
- ***Data structure and storage***
  - Adequate storage devices
  - Common treatment of experimental and simulation data
  - Common tools for data analysis
- ***Communication and networking***
  - Fast data transfer between simulation site and storage site
  - Efficient worldwide access to data
  - Collaborative tools
  - Dealing with firewalls
- ***Advanced graphics and animation***



# SUMMARY

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- ***Predictive simulation capability has 3 components***
    - Code and algorithm development
    - Tightly coupled theoretical effort
    - Validation of models by comparison with experiment
  - ***Integration required for:***
    - Coupling algorithms for disparate physical problems
    - Theoretical synthesis of results from different models
    - Efficient communication and data manipulation
  - ***Extended MHD is the only practical central element for integrated modeling***
    - Only model that can address realistic geometry and time scales with foreseeable resources
  - ***Progress is being made in Extended MHD***
    - Integration of energetic ion modules into 3-D MHD
    - Computationally tractable closures
- Need to bring a broader range of algorithms and codes to bear for overall fusion problem***

