

INTRODUCTION TO GYROKINETIC AND FLUID SIMULATIONS OF PLASMA TURBULENCE AND OPPORTUNITIES FOR ADVANCED FUSION SIMULATIONS

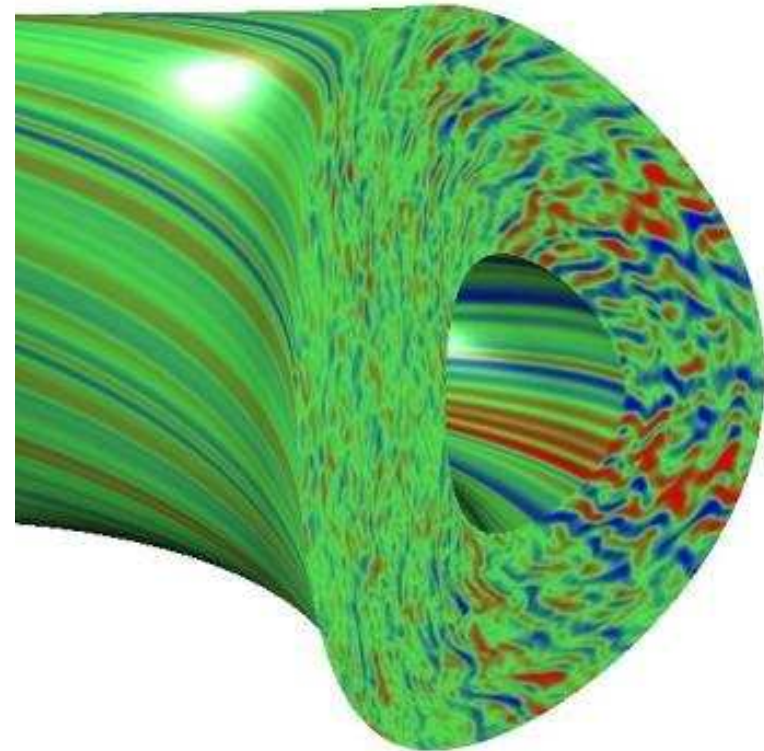
G.W. Hammett, Princeton Plasma Physics Lab
w3.pppl.gov/~hammett
Fusion Simulation Project Workshop
San Diego, Sept. 17, 2002

Thanks to Bill Nevins &
the Plasma Microturbulence Project
for many vugraphs. In particular see:

<http://www.isofs.info/nevins.pdf>

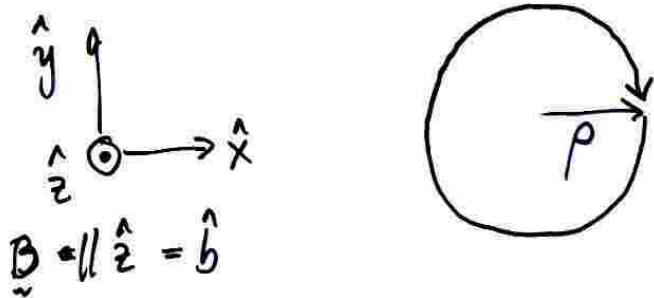
<http://fusion.gat.com/theory/pmp>

and others working on Braginskii
2-fluid simulations of edge turbulence.
(Collabs. at Univ. Alberta, UCLA,
UCI, Univ. Colorado, Dartmouth, Garching,
General Atomics, LLNL, Univ. Maryland,
MIT, Princeton PPPL, Univ. Texas)



Fundamental Particle Motion in Magnetic & Electric Fields

$$m \frac{d\mathbf{v}}{dt} = q \frac{\mathbf{v} \times \mathbf{B}}{c}$$



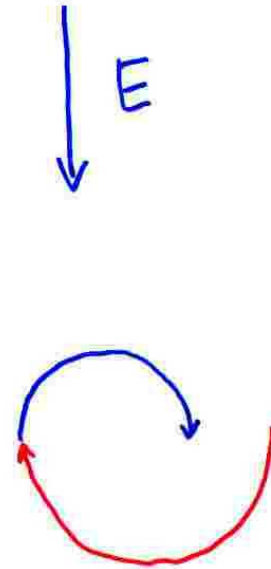
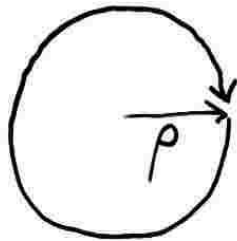
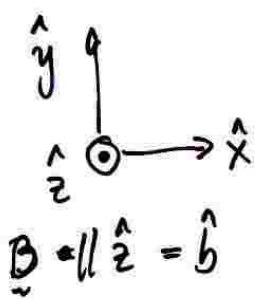
$$\text{Gyrofrequency } \Omega = \frac{qB}{mc}$$

$$\Omega_e \sim 10^{11} \text{ Hz}, \quad \Omega_i \sim 10^8 \text{ Hz}$$

$$\text{Gyroradius } \rho = \frac{v_{\perp}}{\Omega}$$

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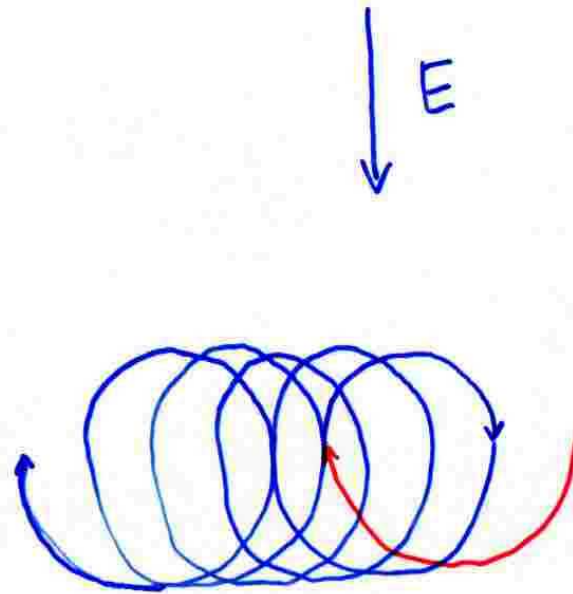
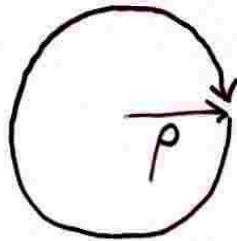
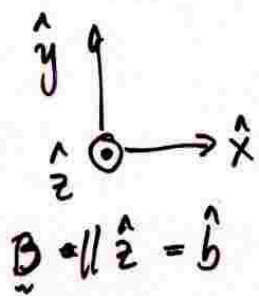
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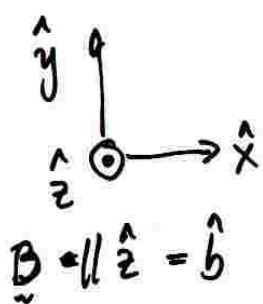
Gyroradius $\rho = \frac{v_{\perp}}{\Omega}$

Drift \underline{v}_d

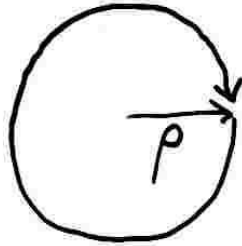
$$= \underline{v}_{E \times B} = \frac{c}{B} \underline{E} \times \hat{b}$$

Fundamental Particle Motion in Magnetic & Electric Fields

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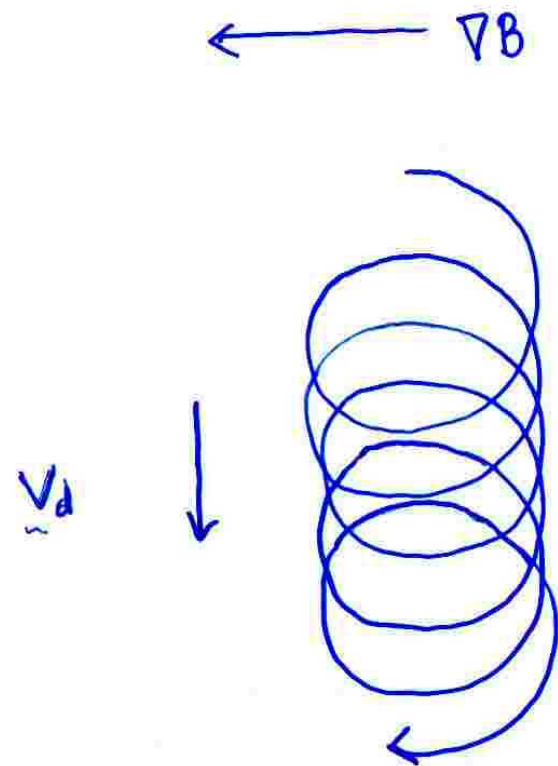


$$\mathbf{B} = B \hat{z} = b$$



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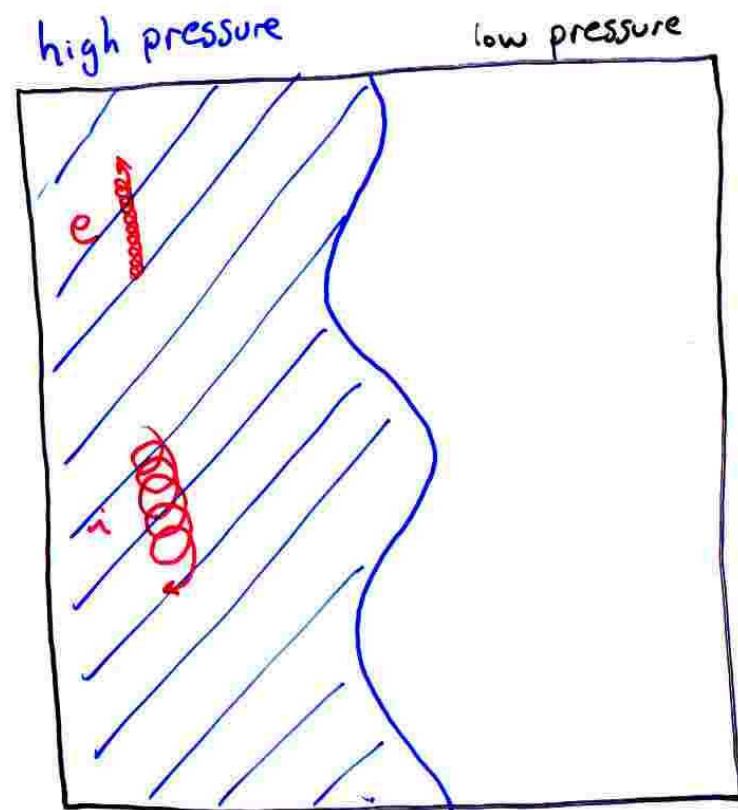
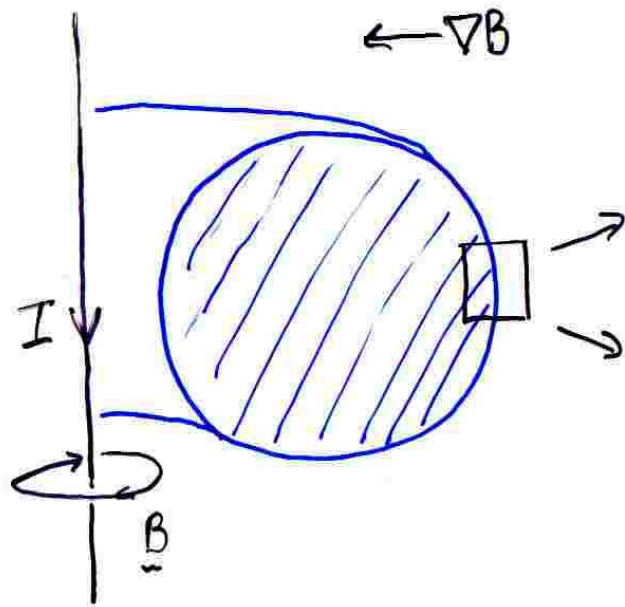


$$\mathbf{v}_d = \frac{v_{\perp}^2}{2\Omega} \hat{b} \times \nabla \ln B$$

"curvature drift" similar

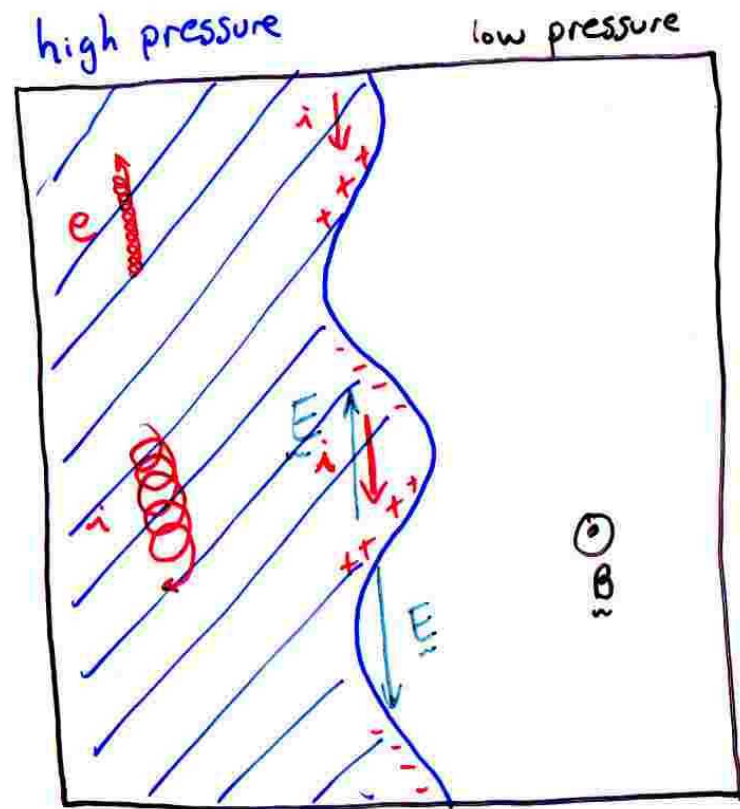
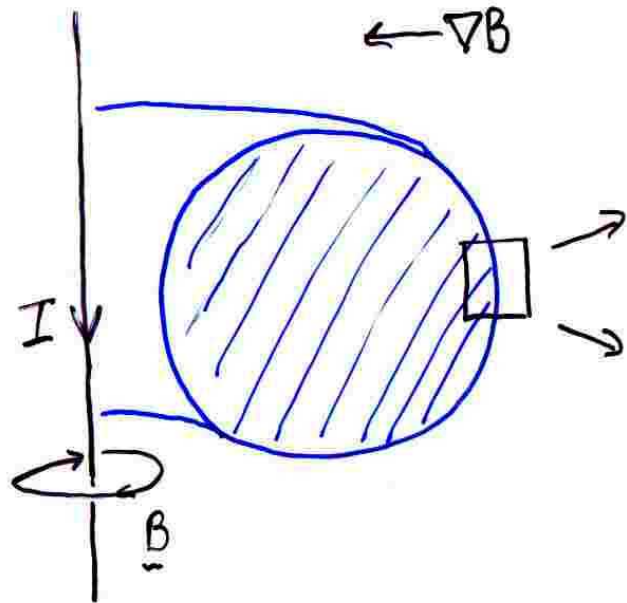
Qualitative Physical Picture of "Bad Curvature"

Instabilities (ITG, TEM, ETG, Drift waves, MHD ballooning...)



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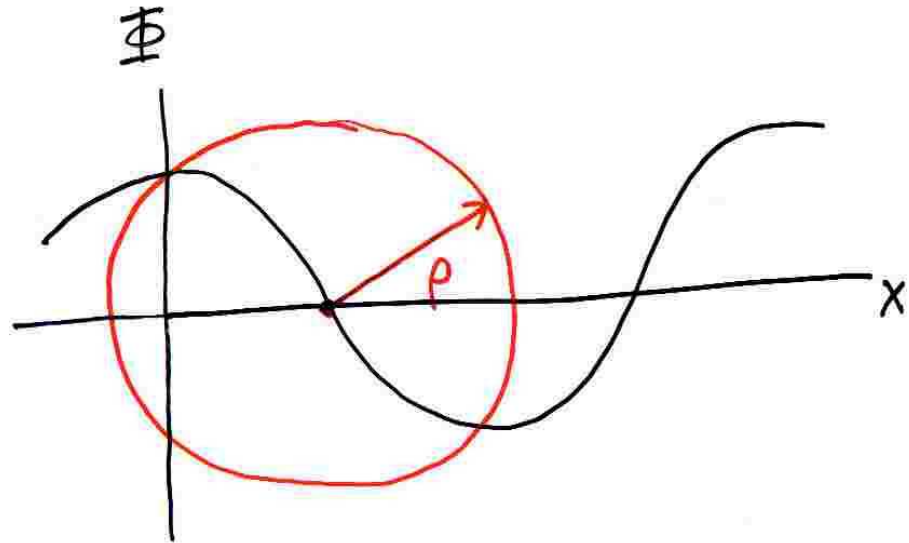


If Electric Field is not uniform, Gyroaverage

$$\underline{E} = -\nabla\Phi$$

$$\underline{v}_{EXB} = \frac{c}{B} \hat{b} \times \nabla \langle \Phi \rangle$$

$$\begin{aligned} \langle \Phi \rangle(x) &= \frac{1}{2\pi} \oint d\varphi \Phi(x+\varphi) \\ &= J_0(k_{\perp} \rho) \Phi \end{aligned}$$



A complete description of a plasma

is given by the particle distribution function $F_s(\vec{x}, \vec{v}, t)$, the density of particles at (near) position \vec{x} with velocity \vec{v} and time t , for species s (with charge q_s and mass m_s).

The charge density and current needed for Maxwell's equations to determine the electric and magnetic fields is then:

$$\sigma(\vec{x}, t) = \sum_s q_s \int d^3v F_s(\vec{x}, \vec{v}, t) \qquad \vec{j}(\vec{x}, t) = \sum_s q_s \int d^3v \vec{v} F_s(\vec{x}, \vec{v}, t)$$

F_s is determined by the Vlasov-Boltzmann equation

$$\frac{\partial F}{\partial t} + \vec{v} \cdot \frac{\partial F}{\partial \vec{x}} + \frac{q_s}{m_s} \left(\vec{E} + \frac{\vec{v} \times \vec{B}}{c} \right) \cdot \frac{\partial F}{\partial \vec{v}} = \text{Collisions} + \text{sources} + \text{sinks} \approx 0$$

where sources + sinks includes radiation cooling of electrons, ionization and recombination changes of ion charge state, etc.

Equivalent particle approach

Discrete particle density representation (combined with smoothing and “particle-in-cell” techniques):

$$F_s = \sum_{i=1,N} w_i(t) \delta(\vec{x} - \vec{x}_i(t)) \delta(\vec{v} - \vec{v}_i(t))$$

$$\frac{d\vec{x}_i}{dt} = \vec{v}_i \qquad \frac{d\vec{v}_i}{dt} = \frac{q_i}{m_i} \left(\vec{E}(\vec{x}_i, t) + \frac{\vec{v}_i \times \vec{B}(\vec{x}_i, t)}{c} \right)$$

plus Monte Carlo treatment of collisions, sources and sinks.

Both “continuum” F and particle descriptions are equivalent (in the limit of a large number of particles, typical fusion particle density $\sim 10^{14}/\text{cm}^3$) and are “Exact”, but both include an excessive range of time and space scales.

Most plasma phenomena of interest are slow compared to the electron and ion gyrofrequencies ($\sim 10^{11}$ Hz and $\sim 10^8$ Hz).

Vlasov, Boltzmann, Liouville Eq:

Particle Distribution

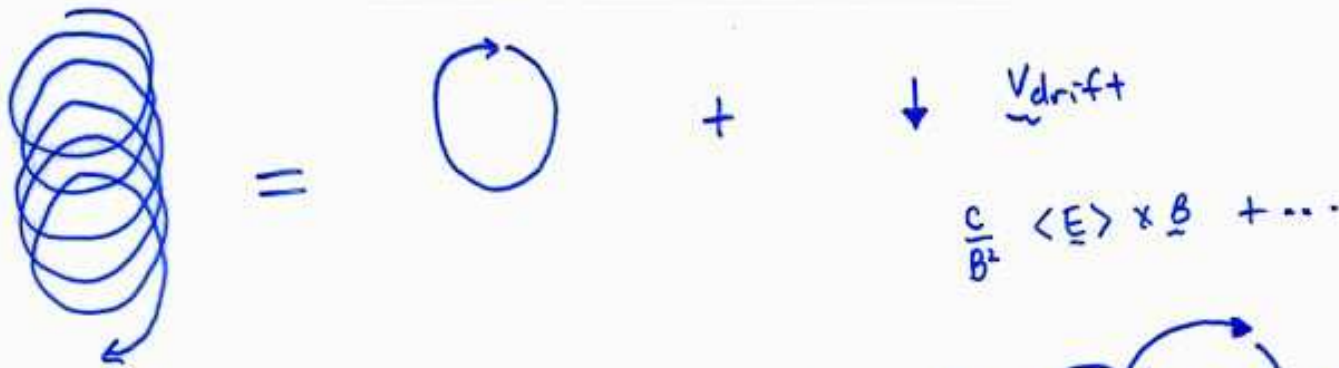
$$\frac{\partial f(\underline{x}, \underline{v}, t)}{\partial t} + \underline{v} \cdot \frac{\partial f}{\partial \underline{x}} + \frac{q}{m} \left(\underline{E} + \frac{\underline{v} \times \underline{B}}{c} \right) \cdot \frac{\partial f}{\partial \underline{v}} = C(f)$$

Nonlinear, \underline{E} & \underline{B} depend on f through Maxwell's Eqs.

Nonlinear Gyrokinetic Eq. 1982-88

(Frieman & Chen, W.W. Lee, Dubin, Krommes, Hahm, Brizard...)

linear gyrokinetics
1960's & 70's.



Possible to eliminate fast gyrofrequency Φ
time scales & retain nonlinear dynamics
& $k_{\perp} \rho_i \sim 1$



The Nonlinear Gyrokinetic Equation

Guiding center distribution function $F_s(\vec{x}, \vec{v}, t) = F_{0s}(\psi, W) + F_{0s}(\psi, W)q_s\tilde{\phi}/T_s + \tilde{h}_s(\vec{x}, W, \mu, t) = \text{equilibrium} + \text{fluctuating components, where the energy } W = mv_{\parallel}^2 + \mu B, \text{ the first adiabatic invariant } \mu = mv_{\perp}^2/B, \text{ and}$

$$\frac{\partial \tilde{h}_s}{\partial t} + (\tilde{v}_{\chi} + v_{\parallel} \hat{b} + \vec{v}_d) \cdot \nabla \tilde{h}_s = -\tilde{v}_{\chi} \cdot \nabla F_{0s} - q_s \frac{\partial F_{0s}}{\partial W} \frac{\partial \tilde{\chi}}{\partial t} + \text{Collisions} + \text{Sources} + \text{Sink}$$

where \hat{b} points in the direction of the equilibrium magnetic field, \vec{v}_d is the curvature and grad B drift, Ω_s is the gyrofrequency, and the ExB drift is combined with transport along perturbed magnetic fields lines and the perturbed ∇B drift as:

$$\tilde{v}_{\chi} = \frac{c}{B} \hat{b} \times \nabla \tilde{\chi} \quad \tilde{\chi} = J_0(\gamma) \left(\tilde{\phi} - \frac{v_{\parallel}}{c} \tilde{A}_{\parallel} \right) + \frac{J_1(\gamma)}{\gamma} \frac{mv_{\perp}^2}{e} \frac{\tilde{B}_{\parallel}}{B}$$

J_0 & J_1 are Bessel functions with $\gamma = k_{\perp} v_{\perp} / \Omega_s$, and the fields are from

$$0 \approx 4\pi \sum_s q_s \int d^3v \left[q_s \tilde{\phi} \frac{\partial F_{0s}}{\partial W} + J_0(\gamma) \tilde{h}_s \right]$$

$$\nabla^2 \tilde{A}_{\parallel} = -\frac{4\pi}{c} \sum_s q_s \int d^3v v_{\parallel} J_0(\gamma) \tilde{h}_s$$

$$\frac{\tilde{B}_{\parallel}}{B} = -\frac{4\pi}{B^2} \sum_s \int d^3v m v_{\perp}^2 \frac{J_1(\gamma)}{\gamma} \tilde{h}_s$$

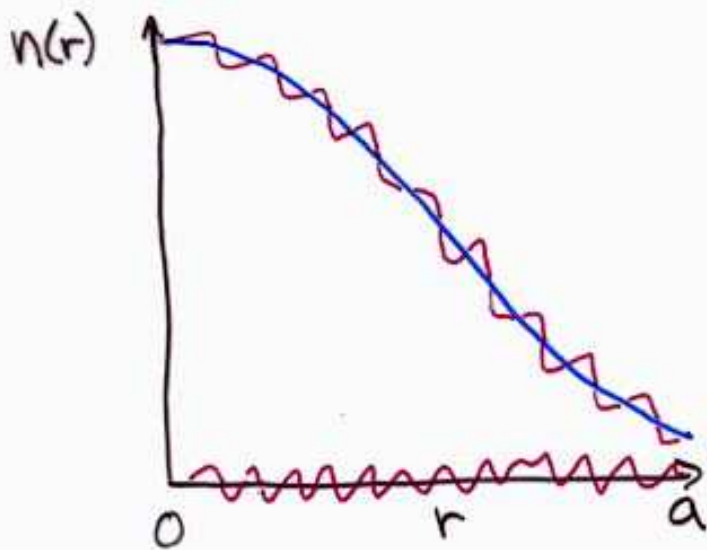
$$\vec{\tilde{E}} = -\nabla\tilde{\phi} - \frac{1}{c}\frac{\partial\tilde{A}_{\parallel}}{\partial t}\hat{b}$$

$$\vec{B} = \vec{B}_0 + \nabla\tilde{A}_{\parallel} \times \hat{b} + \tilde{B}_{\parallel}\hat{b}$$

In a full-torus simulation where plasma variations must be kept

$$J_0(k_{\perp}v_{\perp}/\Omega_s)\phi \rightarrow \langle\phi\rangle(\vec{x}) = \frac{1}{2\pi} \int d\vec{\rho}\phi(\vec{x} + \vec{\rho})$$

Microinstabilities are small-amplitude but still nonlinear



$$n = n_0(r) + \tilde{n}(\underline{x}, t)$$

$$n_0 \gg \tilde{n}$$

$$\text{but } \nabla n_0 \sim \nabla \tilde{n}$$

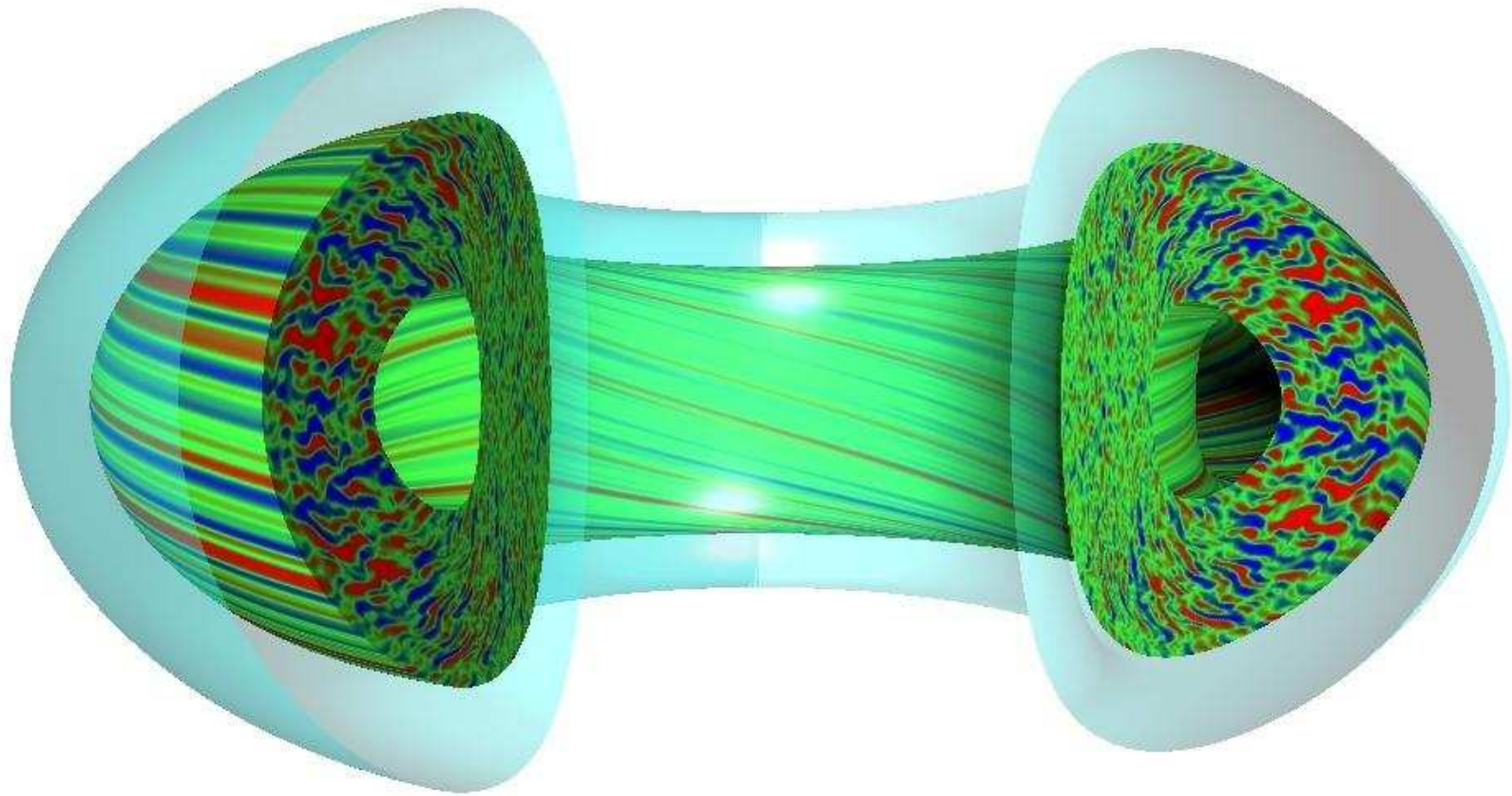


Can locally flatten
or reverse total gradient
that was driving instability.

* Turbulence causes loss of plasma to the wall,
but confinement still $\times 10^5$ better than without \underline{B} .

$$\text{If no } \underline{B}, \text{ loss time } \sim \frac{a}{v_t} \sim 1 \text{ } \mu\text{sec}$$

$$\text{with } \underline{B}, \text{ expts. measure } \sim 0.1 - 1.0 \text{ sec.}$$

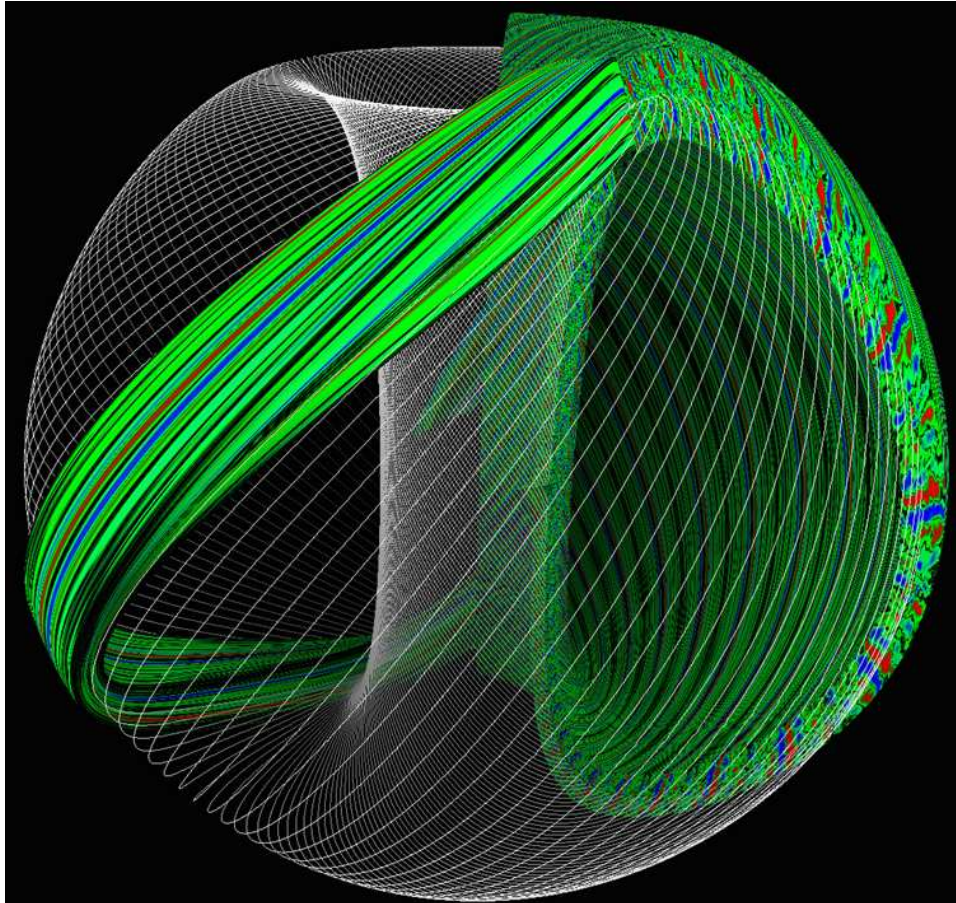


Candy/Waltz movies available at:

http://web.gat.com/comp/parallel/gyro_gallery.html

and other movies can be found from various links starting at:

<http://fusion.gat.com/theory/pmp>



The Plasma Microturbulence Project supports a 2x2 matrix of codes (geometry x algorithm), each type of code is tuned to optimize in various regimes and so are optimized to study certain types of problems.

Codes using flux-tube geometry (shown here) take advantage of short decorrelation lengths of the turbulence perpendicular to magnetic field lines. Multiple copies of a flux-tube pasted together represent a toroidal annulus.

We Support a 2x2 Matrix of Plasma Turbulence Simulation Codes

	Continuum	PIC
Flux Tube	GS2	SUMMIT
Global	GYRO	GTC

- Why both Continuum and Particle-in-Cell (PIC)?
 - Cross-check on algorithms
 - Continuum currently most developed (already has kinetic e 's , δB_{\perp})
 - PIC may ultimately be more efficient
- If we can do Global simulations, why bother with Flux Tubes?
 - Electron-scale (ρ_e , $\delta_e = c/\omega_{pe}$) physics (ETG modes, etc.)
 - Turbulence on multiple space scales (ITG+TEM, TEM+ETG, ITG+TEM+ETG, ...)
 - Efficient parameter scans

Current 'state-of-the-art'

(similar performance achieved in Continuum codes)

Spatial Resolution

- Plasma turbulence is quasi-2-D
 - Resolution requirement along B-field determined by equilibrium structure
 - Resolution across B-field determined by microstructure of the turbulence.
 - ⇒ $\sim 64 \times (a/\rho_i)^2 \sim 2 \times 10^8$ grid points to simulate ion-scale turbulence at burning-plasma scale in a global code
 - Require ~ 8 particles / spatial grid point
 - ⇒ $\sim 1.6 \times 10^9$ particles for global ion-turbulence simulation at ignition scale
 - ~ 600 bytes/particle
 - ⇒ 1 terabyte of RAM
- ⇒ This resolution is achievable

(Such simulations have been performed, see T.S. Hahm, Z. Lin, APS/DPP 2001)

- Simulations including electrons and δB (short space & time scales) are not yet practical at the burning-plasma scale with a global code

Temporal Resolution

- Studies of turbulent fluctuations
 - Characteristic turbulence time-scale
⇒ $c_s/a \sim 1 \mu\text{s}$ (10 time steps)
 - Correlation time \gg oscillation period
⇒ $\tau_c \sim 100 \times c_s/a \sim 100 \mu\text{s}$
(10^3 time steps)
 - Many τ_c 's required
⇒ $T_{\text{simulation}} \sim \text{few ms}$
(5×10^4 time steps)
 - 4×10^{-9} sec/particle-timestep
(this has been achieved)
 - ⇒ ~ 90 hours of IBM-SP time/run
- ☛ Heroic (but within our time allocation)

Major Computational and Applied Mathematical Challenges

- **Continuum kernels** solve an advection/diffusion equation on a 5-D grid
 - Linear algebra and sparse matrix solves (LAPAC, UMFPAC, BLAS)
 - Distributed array redistribution algorithms (we have developed or own)
- **Particle-in-Cell kernels** advance particles in a 5-D phase space
 - Efficient “gather/scatter” algorithms which avoid cache conflicts and provide random access to field quantities on 3-D grid
- **Continuum and Particle-in-Cell kernels** perform elliptic solves on 3-D grids (often mixing Fourier techniques with direct numerical solves)
- **Other Issues:**
 - Portability between computational platforms
 - Characterizing and improving computational efficiency
 - Distributed code development
 - Expanding our user base

Continuum / Eulerian Codes		Particle-in-Cell/Lagrangian Codes	
Flux-tube / thin-annulus	Full-torus or thin annulus	Flux-tube	Full-torus
All now use field-line following coordinate systems, $\Delta x_{\perp}/\Delta x_{\parallel} \sim \rho_i/L \sim 10^{-1}-10^{-3}$			
GS2 (Dorland, U. Md., Kotschenreuther)	Gyro (Candy-Waltz GA)	Summit (LLNL, U. Co, UCLA)	GTC (Z. Lin et.al. PPPL, UCI)
\perp Pseudo-spectral linear & nonlinear. \parallel 2^{cd} order finite-diff. (slight upwind)	Toroidal pseudo-spectral 5th-6th order upwind τ grid to avoid $1/v_{\parallel}$ collisions w/ direct sparse solver (UMFPACK)	Delta-f algorithm reduces particle noise. Recent hybrid electron algorithm: fluid with kinetic electron closure.	
Linear: fully implicit (elegant algorithm) Nonlinear: 2^{cd} order Adams-Bashforth	High accuracy explicit 4th order Runge-Kutta	Leap-frog / Predictor-corrector	
Elliptic solvers easy in Fourier space	Elliptic solvers with non-uniform coefficients solved by combination of Fourier, iterative, and direct matrix solution		

Fast time scales hiding in E & B fields: is there a partially-implicit iterative algorithm that can help?

Recommendations (I)

Strengthening PMP Support to Integrated Modeling

- (1) Improve the fidelity and performance of Plasma Microturbulence Project codes
- (2) Validate these codes against experiment
- (3) Expand the user base of the PMP codes
- (4) Initiate the development of a kinetic edge turbulence simulation code.

CORE TURBULENT TRANSPORT STILL IMPORTANT

- Provides most of temperature gradient: 20 keV center → 1-4 keV near-edge. Effects of shaping, density peakedness, rotation, impurities, T_i/T_e ?
- Detailed experimental comparisons possible, fluctuation diagnostics.
- Are internal transport barriers possible at reactor scales? $P_{threshold}$? Torque? Controllable?
- Electron-scale transport controls advanced reactor performance?

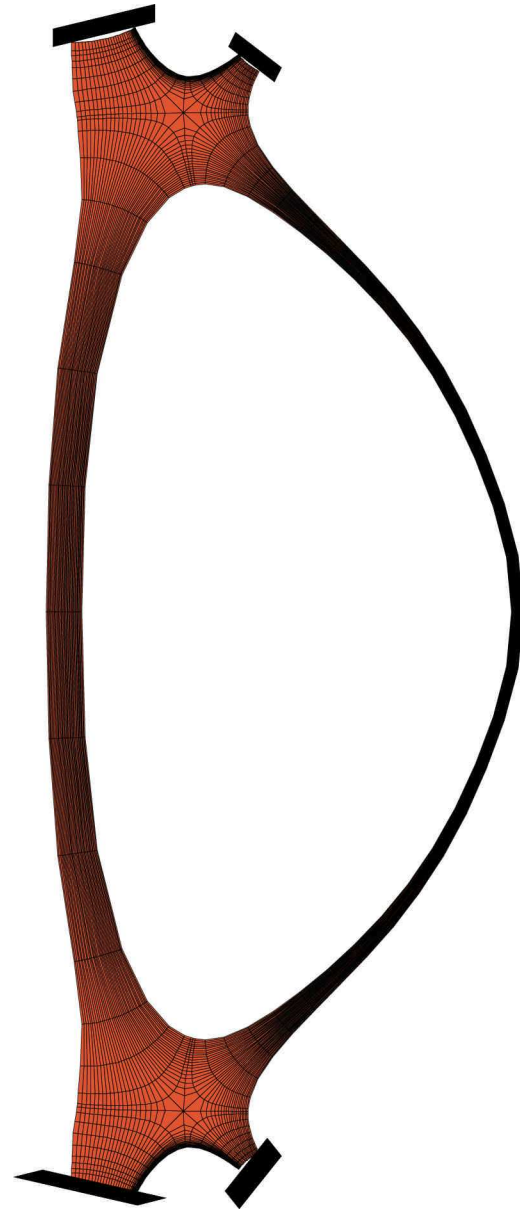
BUT EDGE TURBULENCE CRITICAL

- H-mode pedestal (edge transport barrier) greatest source of uncertainty for reactor predictions.
- Will divertor melt/erode? Need ELM simulation.
- Edge very complicated: Separatrix & divertor geometry matters. Bootstrap current important, second stability regime. Half of power radiated, intense neutral recycling.
- High and low collisionality regimes. Present edge codes are collisional fluids, need kinetic extensions.

3-D Fluid Simulations of Plasma Edge Turbulence

BOUT (X.Q. Xu,)

- Braginskii — collisional, two fluid electromagnetic equations
 - Realistic \times -point geometry (open and closed flux surfaces)
 - BOUT is being applied to DIII-D, C-Mod, NSTX, ...
 - There is LOTS of edge fluctuation data!
- ⇒ An Excellent opportunity for code validation



More info:

Plasma Microturbulence Project (PMP):

<http://fusion.gat.com/theory/pmp>

Nevins presentation on PMP to ISOFS May 2002:

<http://www.isofo.info/nevins.pdf>

GS2 (Dorland Univ. Md.):

<http://gk.umd.edu/GS2/info.html>

Useful 2-page gyrokinetic summary:

http://gk.umd.edu/GS2/gs2_back.ps

GTC (Lin PPPL UCI):

<http://w3.pppl.gov/~zlin/visualization/>

Gyro (Candy/Waltz GA):

<http://web.gat.com/comp/parallel/gyro.html>

Summit (LLNL/UCLA/U. Co.):

<http://www.neresc.gov/scidac/summit>