

Equilibria and Stability in Partially Relaxed Plasma-Vacuum Systems

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ABSTRACT

- The variational principle for relaxed toroidal plasmavacuum systems with pressure is applied to axially periodic cylinders.
- Plasma comprises multiple Taylor-relaxed regions, with each region separated by an ideal MHD barrier of zero width.
- Extends the plasma-vacuum analysis of Kaiser and Uecker, Quartly Jnl of Mech. Appl. Math. 57(1-17), 2004.
- First stage of an attempt to describe a stepped-pressure profile in full 3D.
- May describe formation of internal transport barriers in magnetic confinement fusion experiments.

1 Introduction

1.1 Transport Barriers in Tokamaks

• At sufficiently high heating power, fusion plasmas selforganise to produce internal transport barriers.

Example: MAST discharges showing ITB formation. (a)-(c) show 7085, a high performance D-D discharge [1], (d) shows TRANSP reconstructions of a NBI heated discharge [2].



- While descriptive theories for these barriers exist : *e.g.*
 - shear flow suppression of turbulence [3],
 - chaotic magnetic field line dynamics [4],

they don't explain why the plasma self-organises into this state.

• A possible explanation is that these are constrained minimum energy states.

1.2 Taylor Relaxation

• In a turbulent, resistive plasma, flux tubes do not have independant existence [5]. Infinity of constraints replaced by single constraint

$$K_0 = \int_V \mathbf{A} \cdot \mathbf{B} d\tau \tag{1}$$

(2)

• Minimum magnetic energy solutions, which are constrained by the total helcity are Beltrami fields

$$\nabla\times {\bf B}=\mu {\bf B}$$

2 Multiple Interface Plasma Vacuum Model

- Model built upon Kaiser and Uecker [6], Spies [7] and Spies [8]. System comprises:
 - N plasma regions \mathcal{P}_i in relaxed states.
 - Regions separated by ideal MHD barrier \mathcal{I}_i .
 - Enclosed by a vacuum \mathcal{V} ,
 - Encased in a perfectly conducting wall W.



• Energy functional can be written:

$$W = U - \sum_{i=1}^{N} \mu_i H_i / 2 - \sum_{i=1}^{N} \nu_i M_i$$
(3)

with

$$U_{i} = \int_{\mathcal{R}_{i}} d\tau^{3} \left(\frac{P_{i}}{\gamma - 1} + \frac{B_{i}^{2}}{2} \right), M_{i} = \int_{\mathcal{R}_{i}} d\tau^{3} P_{i}^{1/\gamma}, \quad (4)$$

$$H_{i} = \int_{\mathcal{R}_{i}} d\tau^{3} \mathbf{A} \cdot \nabla \times \mathbf{A} + \qquad (5)$$

$$\oint_{C_{pi}^{<}} \mathbf{dl} \cdot \mathbf{A} \oint_{C_{ti}^{<}} \mathbf{dl} \cdot \mathbf{A} - \oint_{C_{pi}^{>}} \mathbf{dl} \cdot \mathbf{A} \oint_{C_{ti}^{>}} \mathbf{dl} \cdot \mathbf{A} (6)$$

• First variation : Set $\delta W = 0$, yields *partially* Taylor relaxed equilibria:

$\mathcal{I}_i; \mathbf{n} \cdot \mathbf{B} = 0, < P_i + 1/2B^2 >= 0,$	(7)
	(8)
$\mathcal{V}; \nabla \times \mathbf{B} = 0, \nabla \cdot \mathbf{B} = 0$	(9)
$W; \mathbf{n} \cdot \mathbf{B} = 0$	(10)

– μ_i , ν_i are Lagrange multipliers,

- n, a unit vector normal to \mathcal{I}_i ,
- $-\langle x \rangle = x_{i+1} x_i$ is the change in x across \mathcal{I}_i .
- poloidal, toroidal flux constant during relaxation
- Second variation : Examine stability to interface displacements ξ_i by minimize $\delta^2 W$ wrt constant N_B ,

$$N_B = \sum_{i=1}^N \int_{\mathcal{I}_i} d\sigma^2 |\xi_i|^2$$

To solve, vary functional $L = \delta^2 W - \lambda N_B$. For $\mathcal{P}_i, \mathcal{I}_i, \mathcal{V}_i$ solutions to $\delta L = 0$ are:

 \mathcal{P}_i ; $\nabla \times \mathbf{b} = \mu_i \mathbf{b}$, (12) $\mathcal{I}_{i} \quad ; \quad \xi_{i}^{*} \langle \mathbf{B} \cdot \mathbf{b} \rangle + \xi_{i}^{*} \xi_{i} \langle B(\mathbf{n} \cdot \nabla) B \rangle - \lambda \xi_{i}^{*} \xi_{i} = 0,$ (13) $\mathbf{n} \cdot \mathbf{b}_{i,i+1} = \mathbf{B}_{i,i+1} \cdot \nabla \xi_i + \xi_i \mathbf{n} \cdot \nabla \times (\mathbf{n} \times \mathbf{B}_{i,i+1}), (14)$ \mathcal{V} ; $\nabla \times \mathbf{b} = 0$, $\nabla \cdot \mathbf{b} = 0,$ (15) \mathcal{W} ; $\mathbf{n} \cdot \mathbf{b} = 0$. (16)

where $\mathbf{b} = \delta B$ is the perturbed field. Solutions of $\delta L = 0$ with L = 0 are stable providing $\lambda > 0$.

3 Cylindrical Stepped Pressure Equilibria

• Assume plasma is cylindrically symmetric, with axial periodicity L, vacuum boundary at r = 1, wall at r = r_w .

 \mathcal{P}_1 : {0, $k_1 J_1(\mu_1 r),$ $k_1 J_0(\mu_1 r)$ \mathcal{P}_i : {0, $k_i J_1(\mu_i r) + d_i Y_1(\mu_i r)$, $k_i J_1(\mu_i r) + d_i Y_1(\mu_i r)$ B_{θ}^V/r , B^V_{z} ν : {0, (17)

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where :
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- ideal MHD barriers located at radii r_i.
- $-B^V_{\theta}, B^V_z, k_i, d_i \in \Re,$
- J_0, J_1 and Y_0, Y_1 are Bessel functions.
- equilibrium prescribed: EITHER by B and r_i

$$\{k_1, ..., k_N, d_2, ..., d_N, \mu_1, ..., \mu_N, r_1, ...r_{N-1}, r_w, B_{\theta}^V, B_z^V\}$$
(18)

OR by safety factors and fluxes

- $\{\Psi_1^t, ..., \Psi_N^t, \Psi_1^p, ..., \Psi_N^p, \Psi_V^t, \Psi_V^p, q_1^i, ..., q_N^i, q_1^o, ..., q_N^o\}$ (19)
- $-q_i^i$ and q_i^o are safety factors on inside/outside of each interface.
- 4N + 2 parameters in total.

Example of a stepped pressure plasma profile, with five ideal MHD barriers, showing : (a) a contour plot of the polodial flux, (b) the pressure profile, and (c) the safety factor, given by $q_i = \frac{2\pi}{L} \frac{B_z(r)}{B_\theta(r)}$ NOTE: Only the core necessarily has reverse shear.

6 Conclusions

R [m]

Ξ

p [kPa]

σ

(11)

- Developed multiple ideal barrier variational model.
- Shown existence of tokamak-like q profiles
- Generalized analysis for stability of multiple barriers
- Benchmarked analysis
- Begun ITB configurations scans

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4 Stability

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• Fourier decompose variations b and \xi:
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$$\mathbf{b} = \widetilde{\mathbf{b}} e^{i(m\theta + \kappa z)} \qquad \xi_i = X_i e^{i(m\theta + \kappa z)} \tag{20}$$

 $-\widetilde{\mathbf{b}}, X_i$ are complex Fourier amplitudes

– $m \in \mathbb{Z}, \kappa \in \mathbb{Z}$ are poloidal, axial wave numbers

• In general, the plasma and vacuum regions, Eqs. (12) (15) can be re-arranged as a second order differential equation for \tilde{b}_z . That is,

$$\mathcal{P}_{i}; \quad L_{\pm}(m)[\tilde{b}_{z}(Fr)] = 0, \quad F = |\kappa^{2} - \mu^{2}| > 0$$
(21)

$$\mathcal{V}; \quad L_{+}(m)[\tilde{b}_{z}(|\kappa|r)] = 0, \quad \kappa \neq 0,$$
(22)

where
$$L_+(m)$$
 is the modified Bessel ODE for $\kappa^2 > \mu^2$
and $L_-(m)$ the Bessel ODE for $\kappa^2 < \mu^2$.

• Equation (13) reduced to the eigenvalue equation, η

$$\mathbf{X} = \lambda \mathbf{X} \tag{23}$$

(24)

with η a $N \times N$ tridiagnonal matrix. The *i*'th row of η is the *i*'th interface calculation of

 $(\langle \mathbf{B} \cdot \mathbf{b} \rangle + \xi_i \langle B(\mathbf{n} \cdot \nabla) B \rangle) e^{-i(m\theta + \kappa z)}$

- Eq. (23) solved for the set of N eigenvalues $\lambda_1, ..., \lambda_N$, and eigenvectors $\mathbf{X}_1, ..., \mathbf{X}_N$.
 - η_{ij} coded into a case-selection algorithm.
 - QR algorithm used to resolve λ_i [17]
 - solutions stable providing all $\lambda_i < 0$
- **Benchmark A:** For N = 1, Eq. (23) reduces to eigenvalue λ , and results compared to Kaiser and Uecker [12].
 - Marginal stability parameter spans, sweeping κ over range $-K \leq \kappa \leq K$,
 - δ a measure of increase in pitch angle of **B**

 $B_{\theta,V} = J_1(\mu_1)\cos\delta + J_0(\mu_1)\sin\delta$ (25)

$$B_{z,V} = J_0(\mu_1)\cos\delta - J_0(\mu_1)\sin\delta$$
 (26)

- Pressure described by $\beta = \frac{2||P_i||}{R^2}$

• **Benchmark B:** For N = 2, introduce artificial ITB with $r_1 = r_2 - \epsilon$, and no change in equilibrium. As $r_1 \rightarrow r_2$, $\lambda_2 \rightarrow 2\lambda (N=1)$, and $\lambda_1 \rightarrow \infty$ at most unstable point.

Figure (a) shows marginal stability boundaries for m = 1 in $\mu_1 - \delta$ space, and for different plasma β values. The plasma has $r_w = 1.1$ and L = 1. The stable region is interior to each locus. The crosshairs denote the equilibrium configuration used for the dispersion curves presented in Fig. (b), which is a dispersion curve for N = 2and m = 1, and for different internal barrier positions r_1

