

Ideal MHD in the nested flux surface limit

Samuel Lazerson¹

J. Loizu², S. Hudson¹, S. Hirshman³

[1] Princeton Plasma Physics Laboratory

[2] Max-Planck-Institut für Plasmaphysik

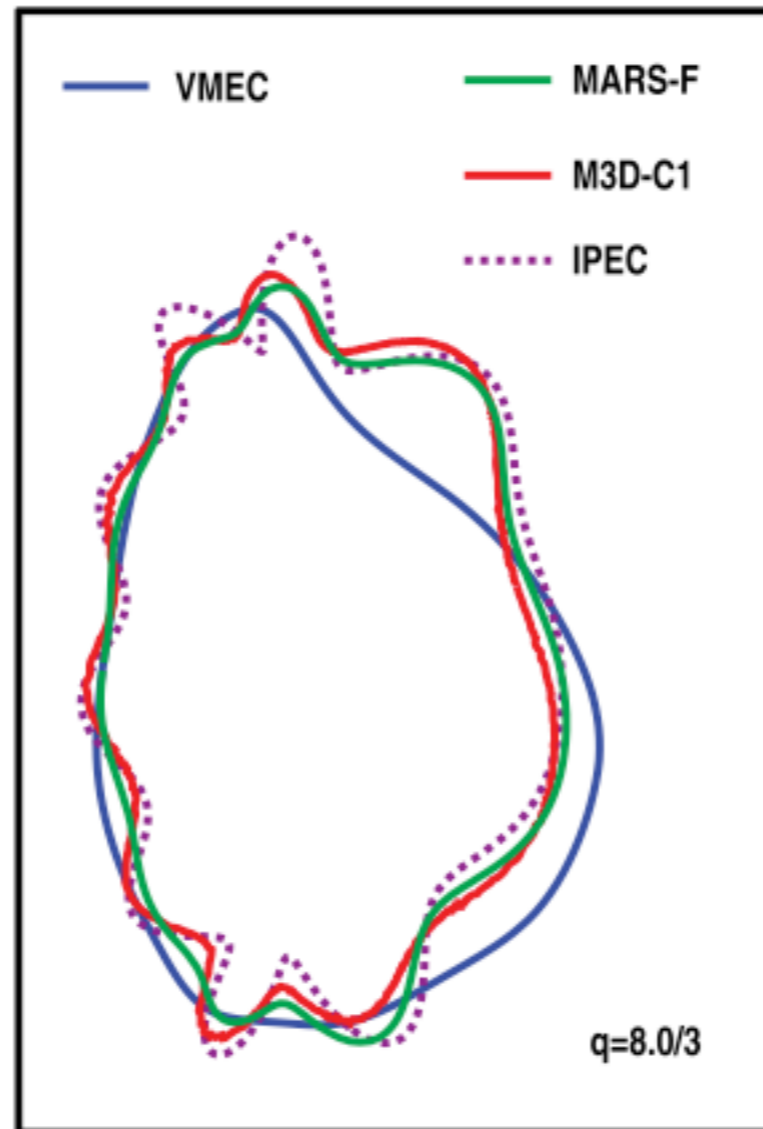
[3] Oak Ridge National Laboratory



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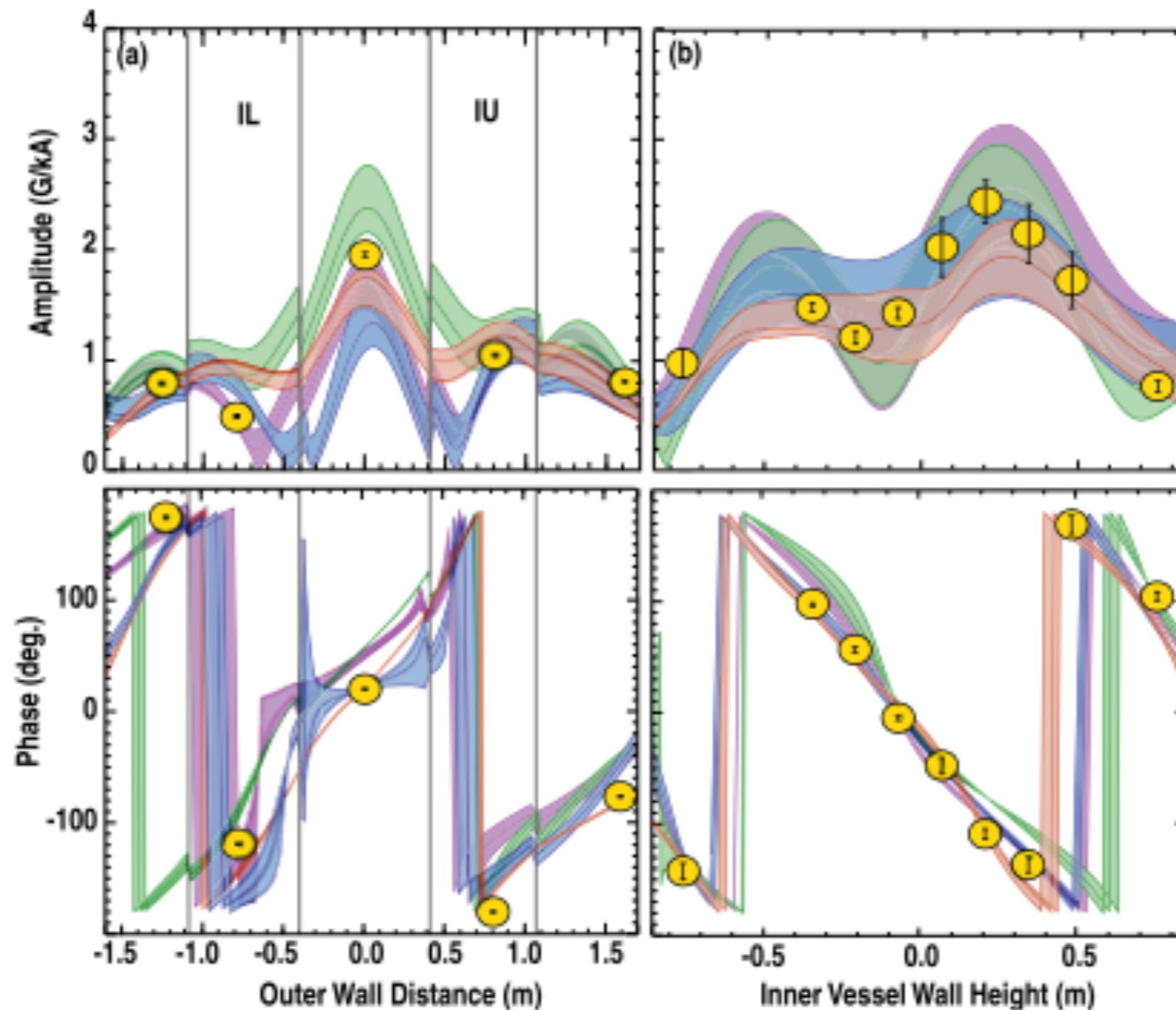
Motivation

Differences were found between VMEC and linear code responses at rational surfaces (Turnbull et al. 2013)



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DIII-D 3D magnetic diagnostics did not discriminate plasma models (King, 2015)



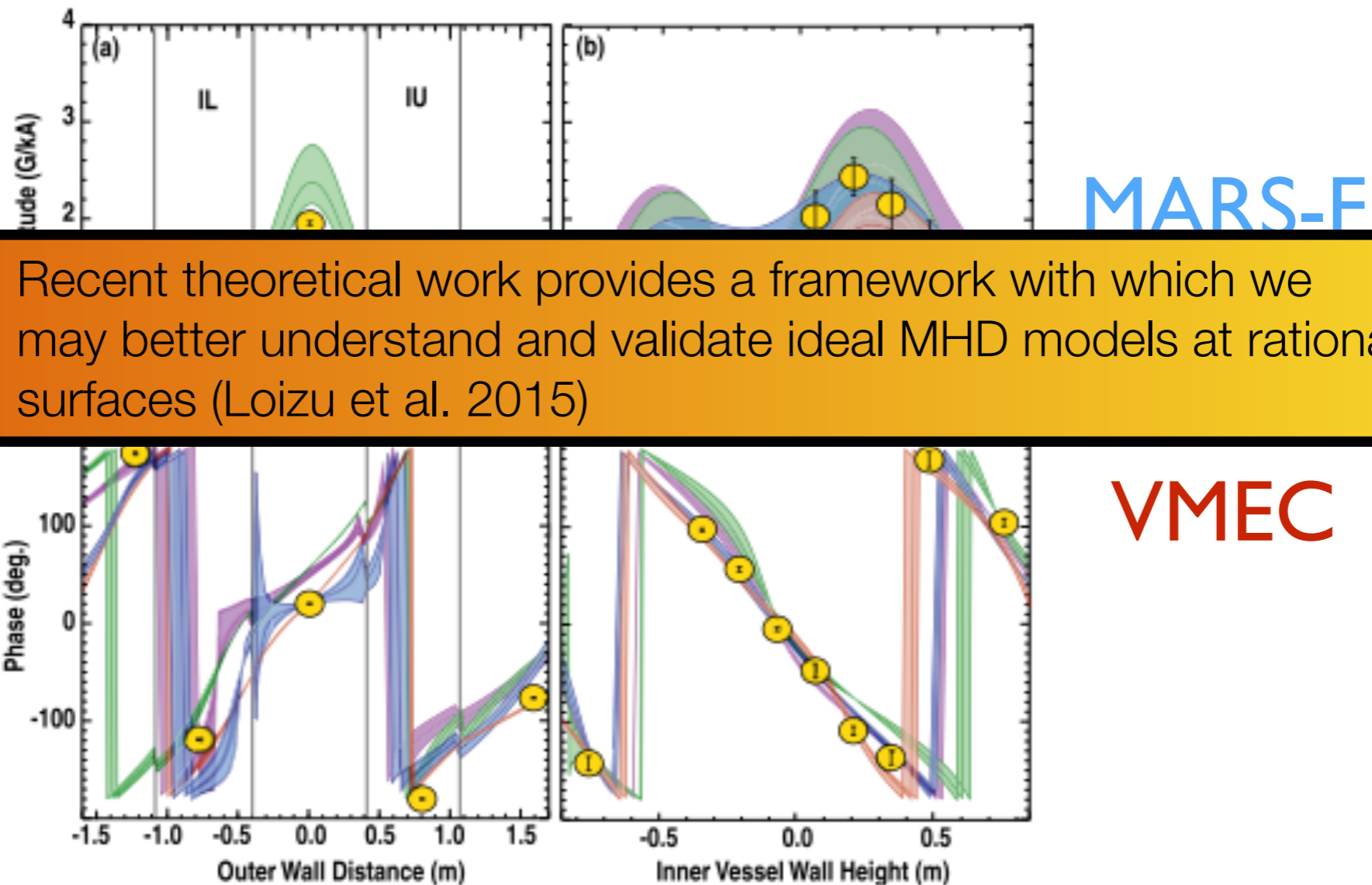
MARS-F
M3D-C1
IPEC
VMEC



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Outline of talk

- A new solution to Newcomb's equation
- The VMEC solution to a screw-pinch
- Finite beta effects
- Current sheets in real equilibria
- Concluding remarks

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Expanding the parallel current in Fourier modes we then find

$$u_{mn} = \frac{h_{mn}(x)}{x} + \Delta_{mn}\delta(x)$$

$$x = tm - n$$

$$h_{mn}(x) \equiv i \left(j \nabla \cdot \vec{j}_{\perp} \right)_{mn}$$

$$\vec{j} \times \vec{B} = \nabla p \Rightarrow \vec{j}_{\perp} = \frac{\vec{B} \times \nabla p}{B^2}$$

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0 for $p=0$

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This reduces to Newcomb's equation

$$\frac{d}{dr} \left(f \frac{d\xi}{dr} \right) - g\xi = 0$$

$$f = B_z^2 (\iota - \iota_s)^2 \frac{r^3}{R^2 + r^2 \iota^2}$$

$$g = B_z^2 \left[(\iota - \iota_s) (k^2 r^2 + m^2 - 1) \bar{k} + (\iota - \iota_s) 2\bar{k}^2 r \right]$$

$$k = -\frac{n}{R} \quad \iota_s = \frac{n}{m} \quad \bar{k} = \frac{r}{R^2 + r^2 \iota_s^2}$$

Now consider a screw pinch

Newcomb's equation is singular where

$$\iota(r_s) = n / m$$

Resulting in a discontinuous plasma displacement, resulting in overlap of surfaces

$$|d\xi / dr| > 1$$

$$\frac{d}{dr} \left(f \frac{d\xi}{dr} \right) - g\xi = 0$$

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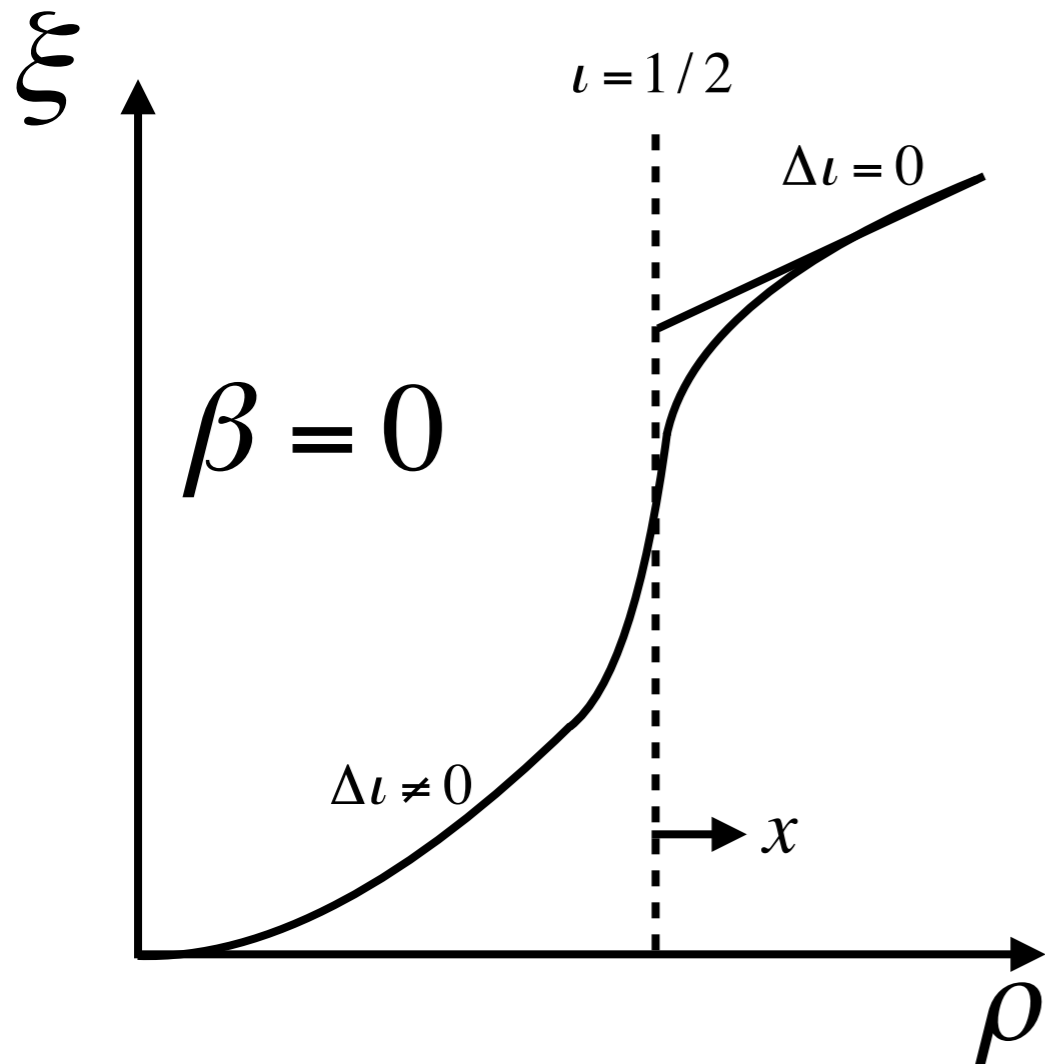
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A resolution to this inconsistency has been formulated

- Ideal MHD equilibria with resonant surfaces are not analytic functions of the 3D boundary.
- An equilibrium model with fractal radial grid is unattractive.
- It has been recognised that infinite shear prevents surfaces from overlapping at rational surfaces*.
- The resolution is to include a discontinuity in the rotational transform at the resonant surface (no longer rational).



The perturbed screw-pinch



Reconsider the screw pinch, including a discontinuity in the rotational transform

$$\Delta\iota \equiv \iota(r_s^+) - \iota(r_s^-) > 0$$

Near the resonant surface we define

$$x = \left| \frac{\iota - \iota_s}{\partial\iota / \partial r} \right|$$

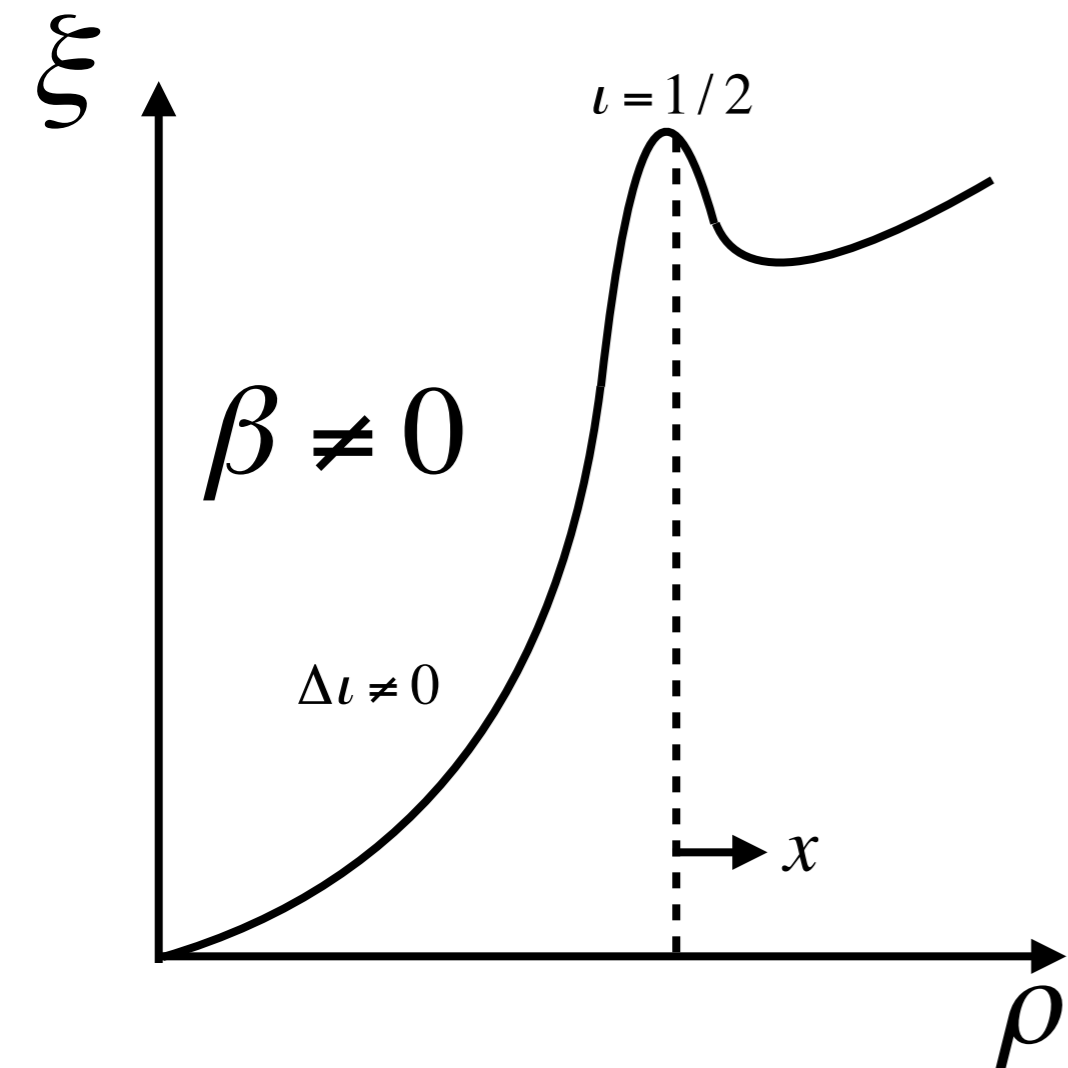
Expanding about the surface we find

$$\xi \sim x^\alpha \quad \alpha = -1, 0$$

The maximum gradient of the displacement may then be written

$$|\xi'| = 2 \frac{\partial\iota_s}{\partial r} \frac{\xi}{\Delta\iota} \xrightarrow{|\xi'| < 1} \Delta\iota > \Delta\iota_{min} = 2\xi_s \iota'_s$$

The finite beta behaviour has been explored



Inclusion of pressure in the screw pinch problem modifies Newcomb's equation so that

$$\frac{d}{dr} \left(f \frac{d\xi}{dr} \right) - g\xi = 0$$

$$f = f_{\beta=0}$$

$$g = g_{\beta=0} + \bar{k} \iota_s^2 r^3 p'$$

Expanding about the surface we now find

$$\xi \propto x^\alpha \quad \alpha = -\frac{1}{2} \pm \sqrt{\frac{1}{4} - D_s} \quad D_s = -\left(\frac{2p' \iota_s^2}{r B_z^2 \iota'^2} \right)_s < \frac{1}{4}$$

At finite beta this Suydam criterion returns

$$\xi \sim \lambda_1 x^{\alpha_1} + \lambda_2 x^{\alpha_2} \quad -1 < \alpha_1 < -\frac{1}{2} < \alpha_2 < 0$$

Can these results be used to validate VMEC?

- VMEC assumes nested flux surface by construction.

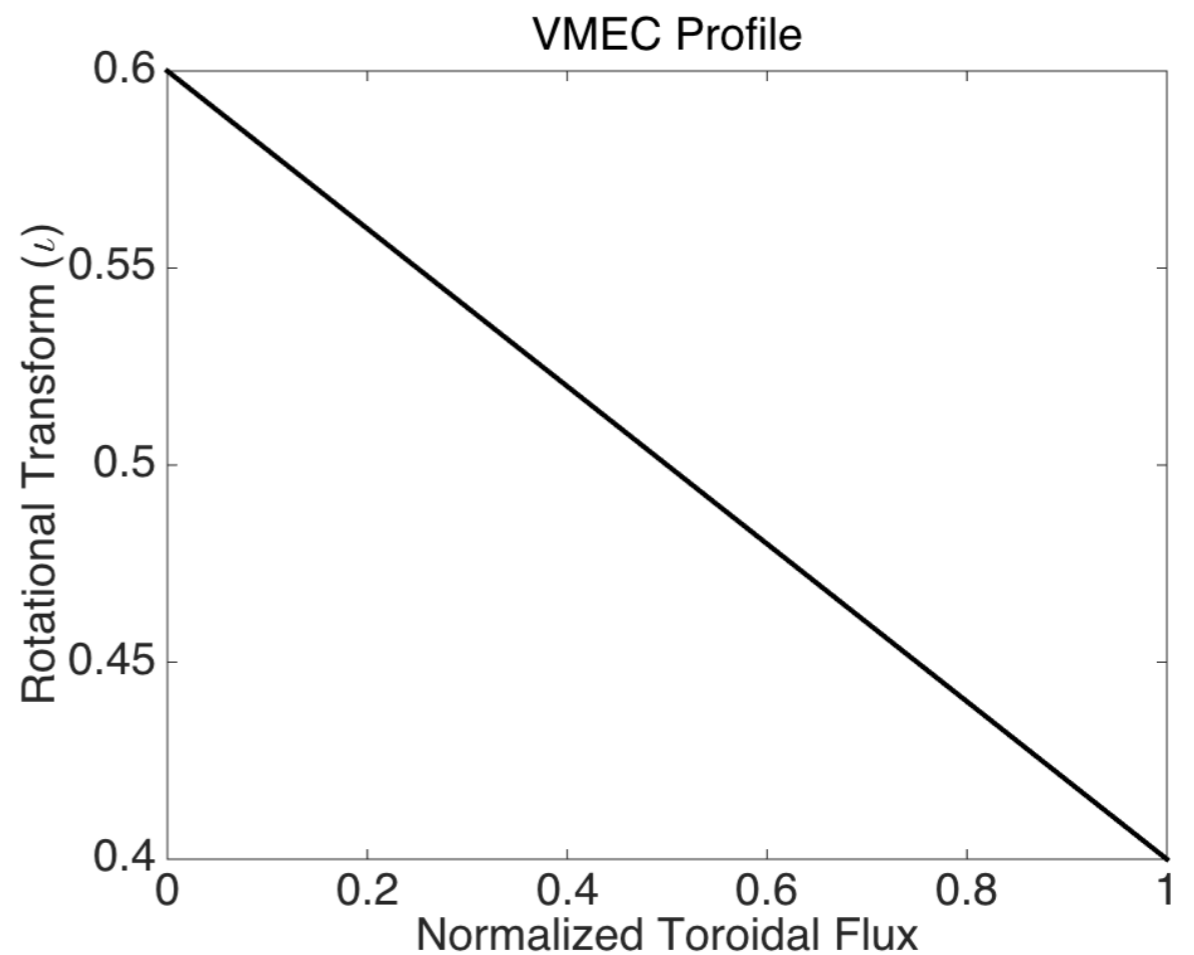
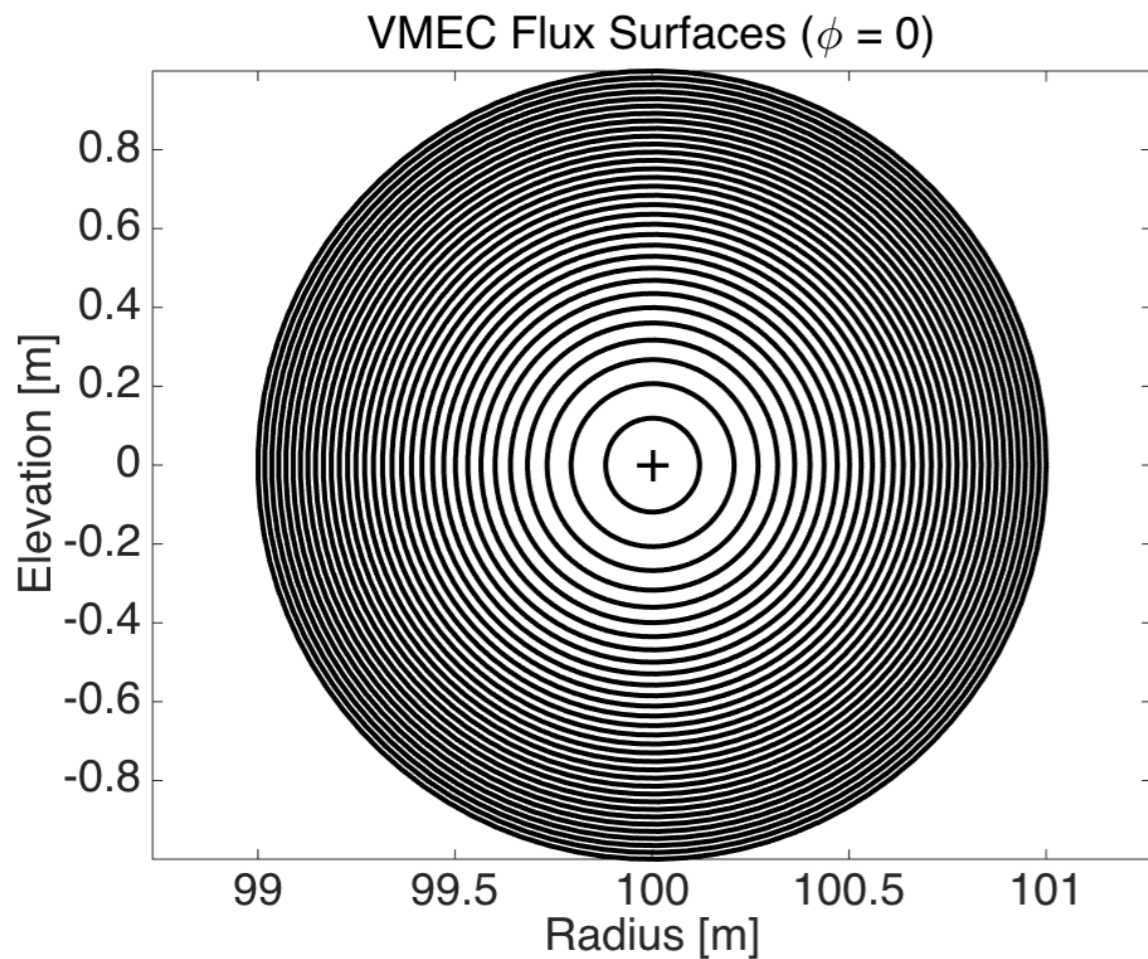
$$\vec{B} = \nabla \zeta \times \nabla \chi + \nabla \Phi \times \nabla \theta^*$$

- Can approximate a cylindrical model.

$$\frac{R}{a} \rightarrow \infty \quad N_{fp} \rightarrow \infty$$

- Continuous iota profiles.

The VMEC screw-pinch

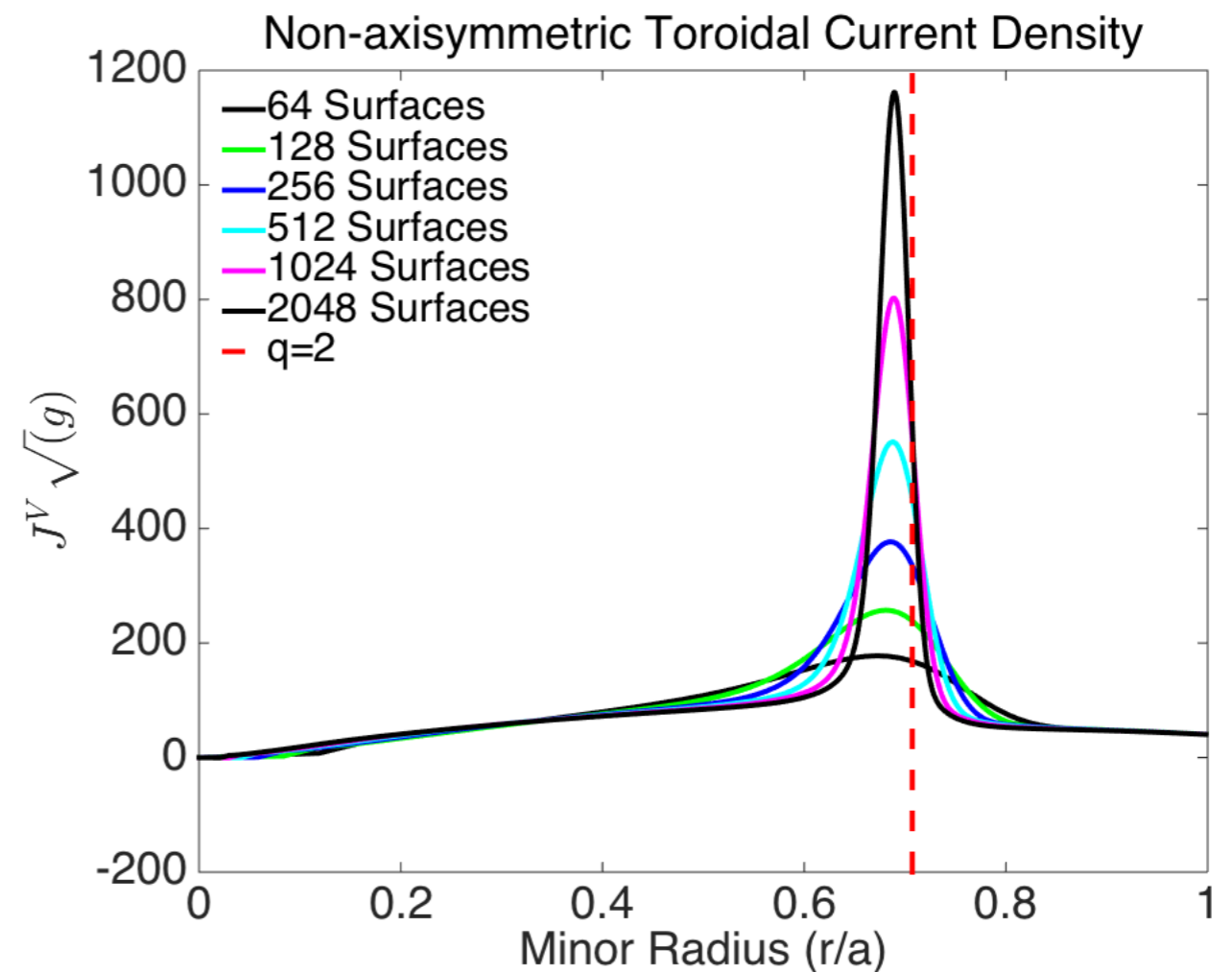
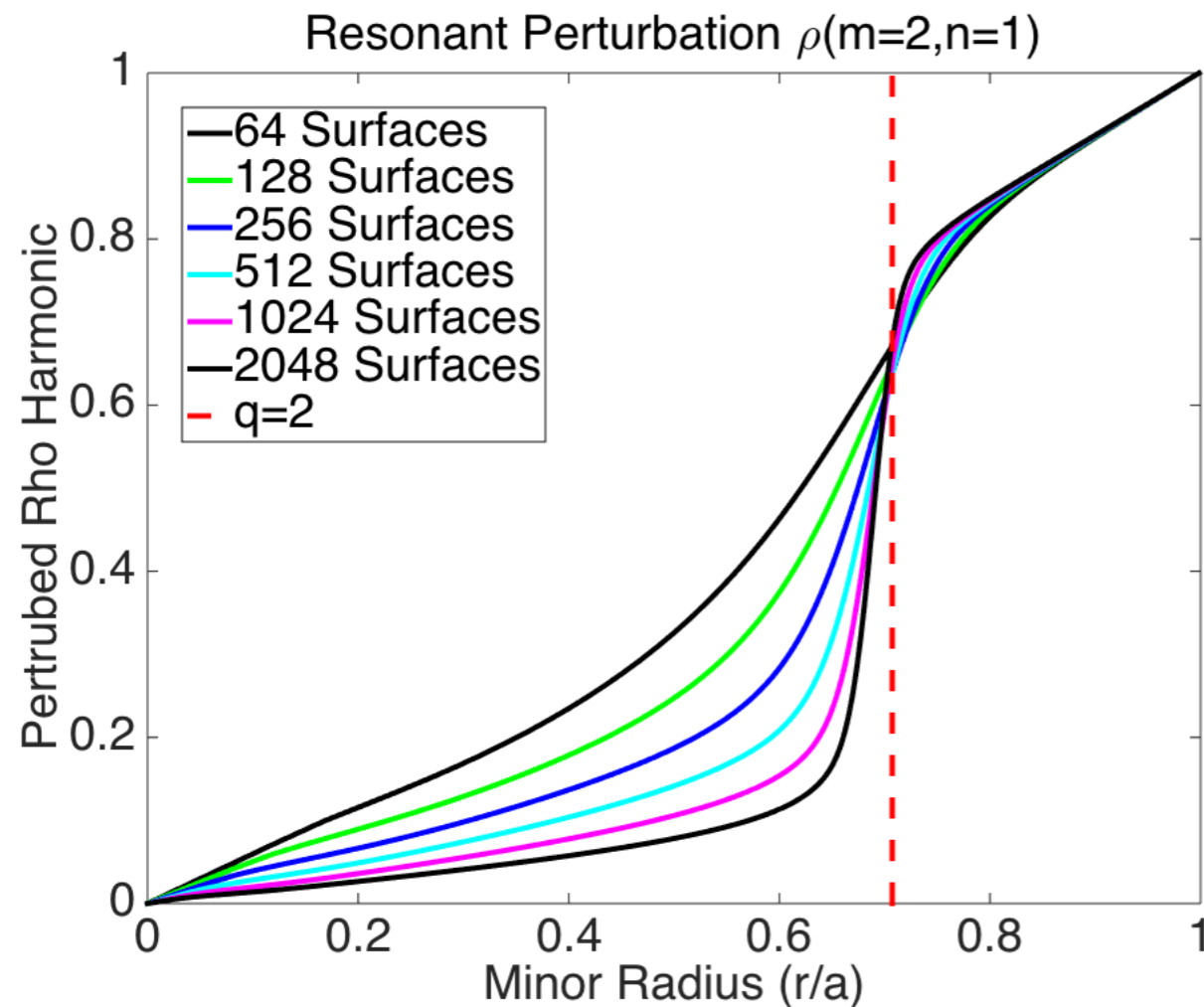


$$R = R_{00} + a \cos \theta + \frac{\delta \rho_{n_1, m_1}}{2} \cos [(m_1 + 1) \theta - n_1 \zeta] + \frac{\delta \rho_{n_1, m_1}}{2} \cos [(m_1 - 1) \theta - n_1 \zeta]$$

$$Z = a \sin \theta + \frac{\delta \rho_{n_1, m_1}}{2} \sin [(m_1 + 1) \theta - n_1 \zeta] - \frac{\delta \rho_{n_1, m_1}}{2} \sin [(m_1 - 1) \theta - n_1 \zeta]$$

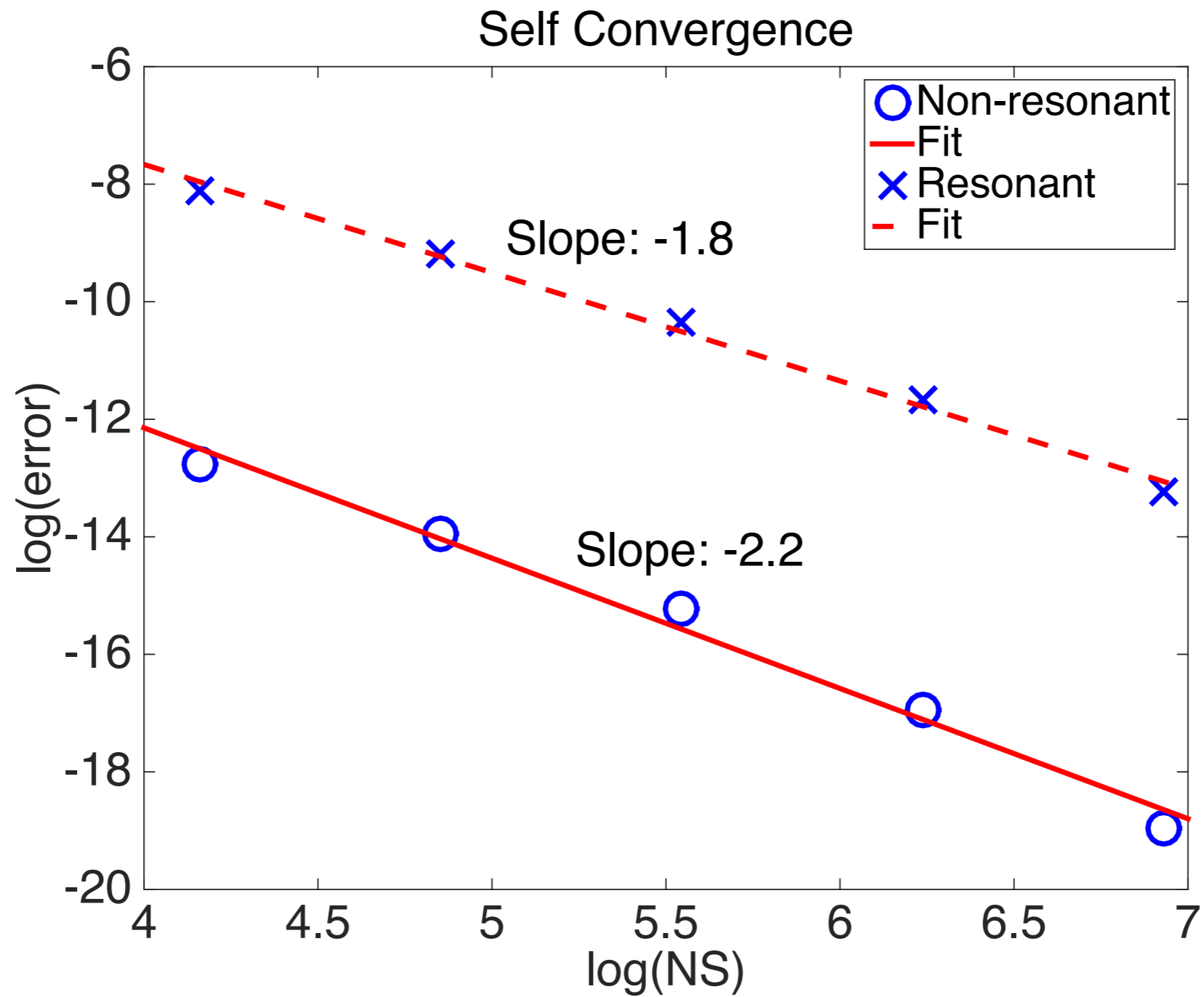
| | |
|-------------------|-----|
| Aspect Ratio | 100 |
| Field Periodicity | 100 |

Resonant response

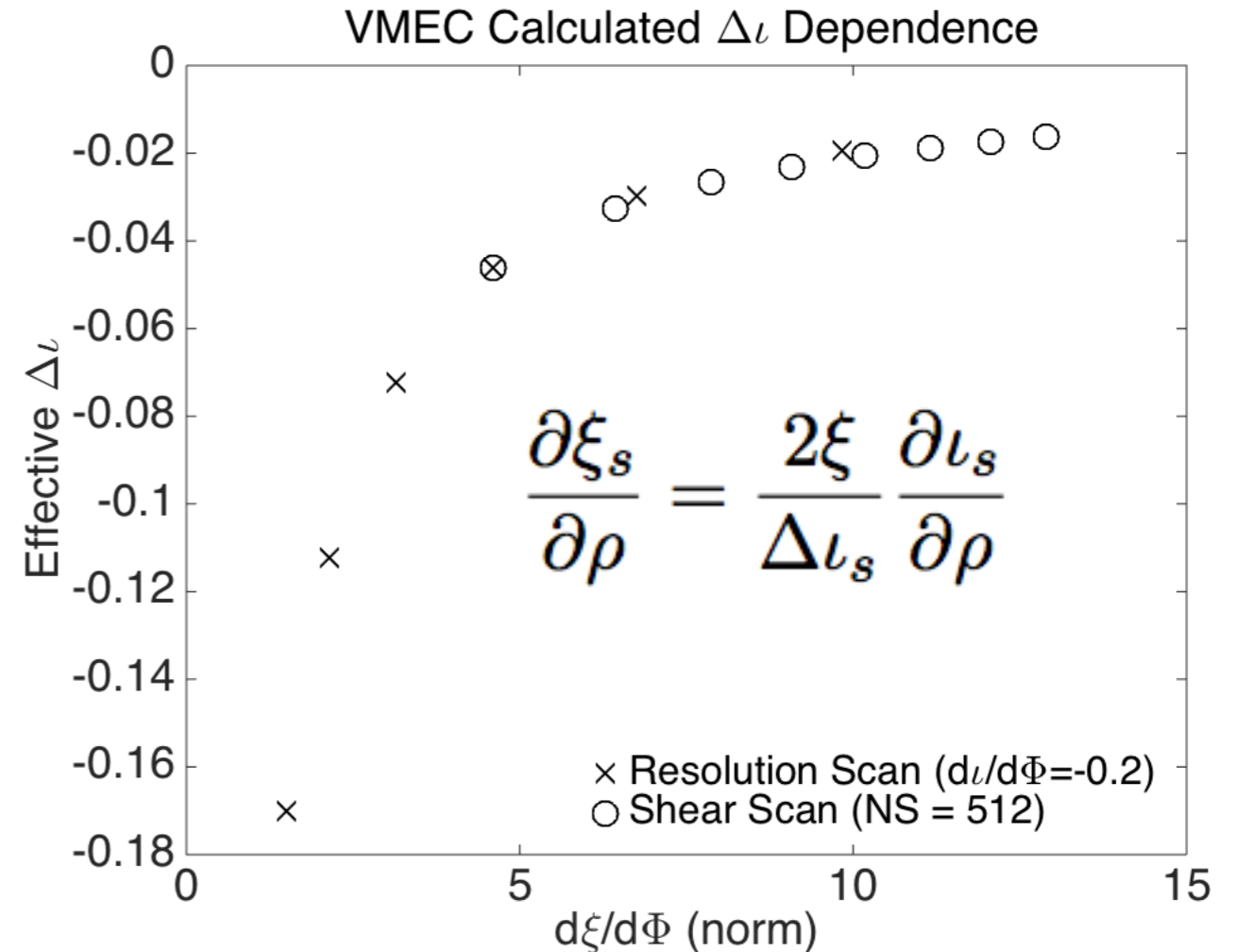
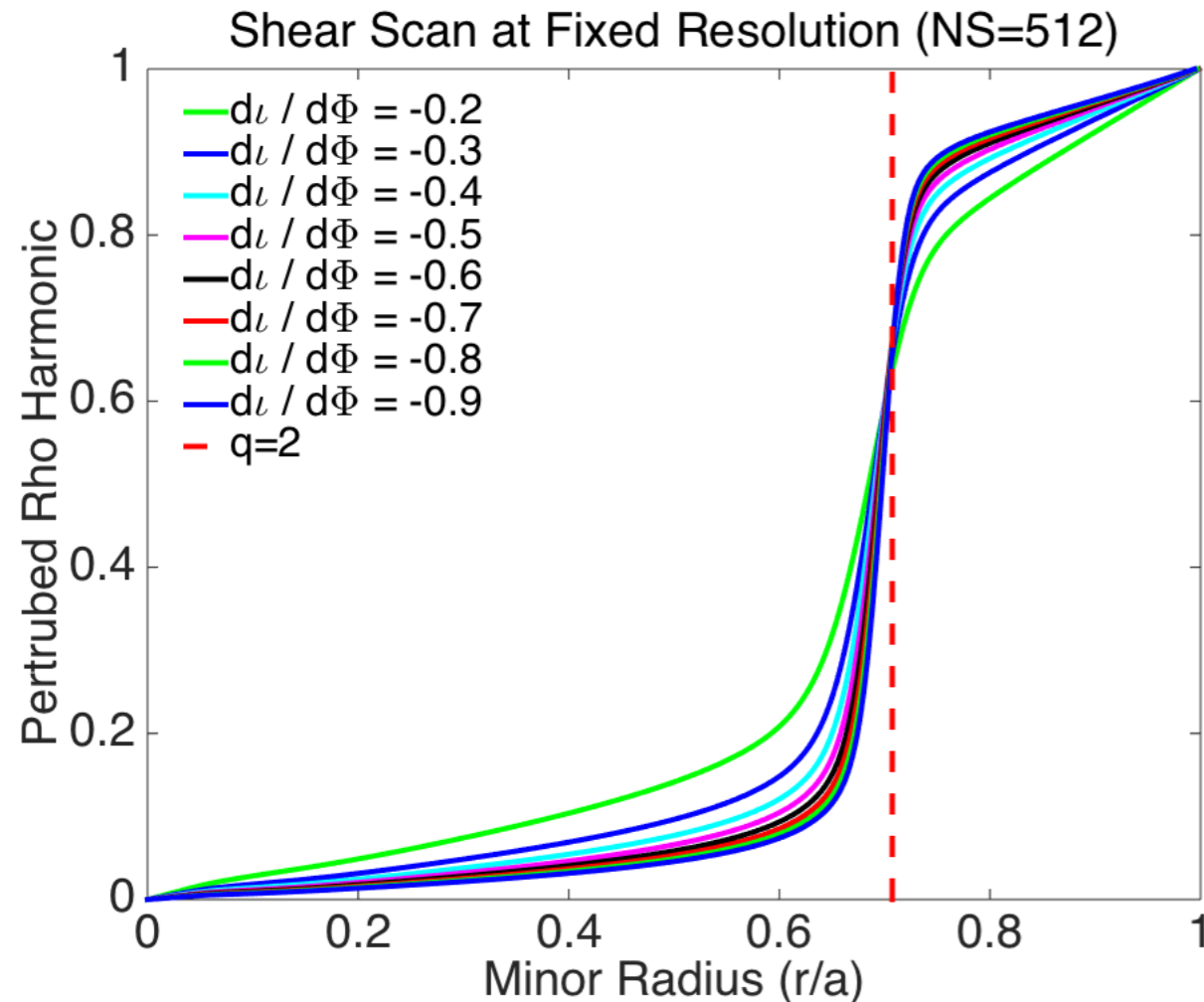


The displacement shows a response across the rational surface which scales with radial resolution.

Self-convergence consistent with finite difference

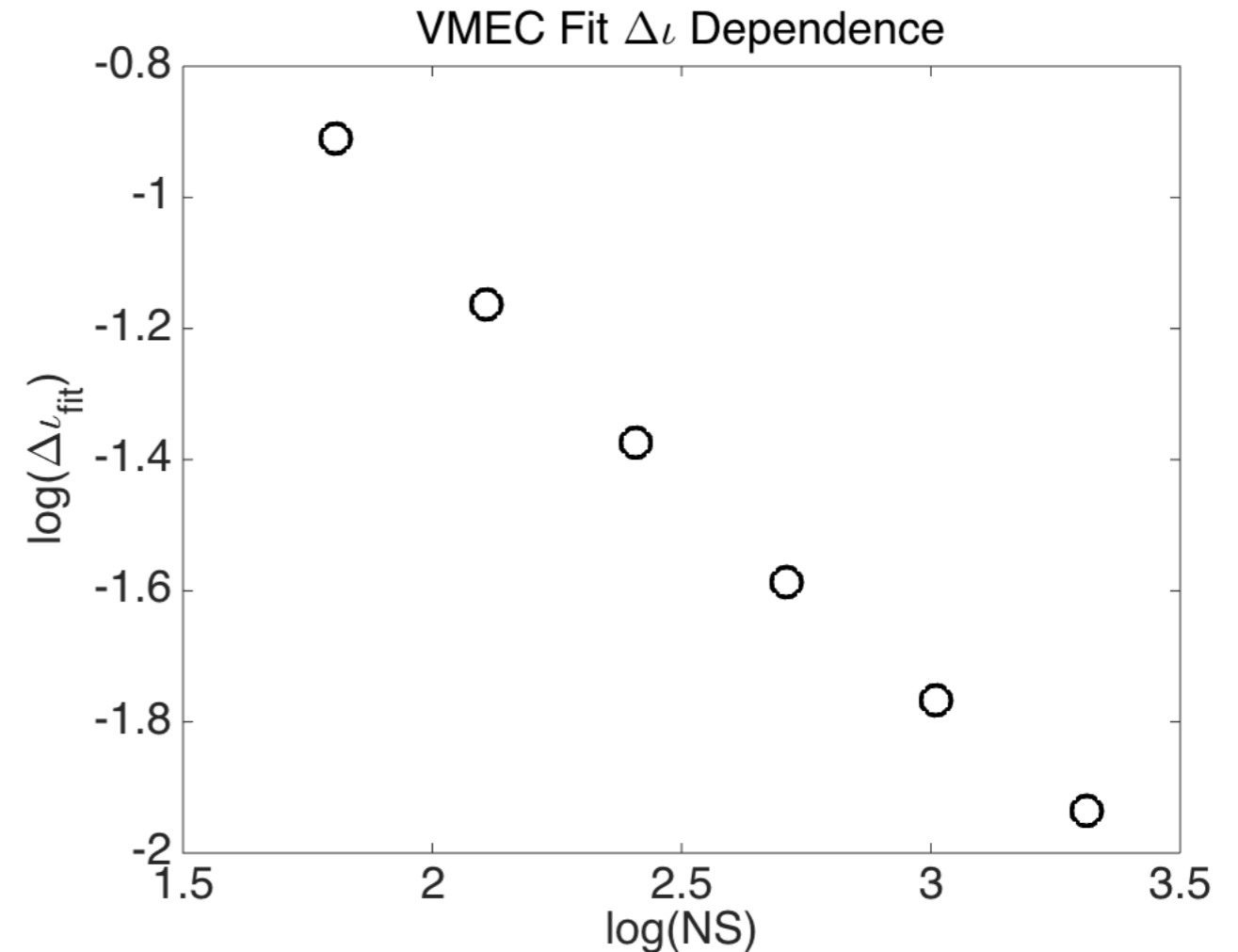
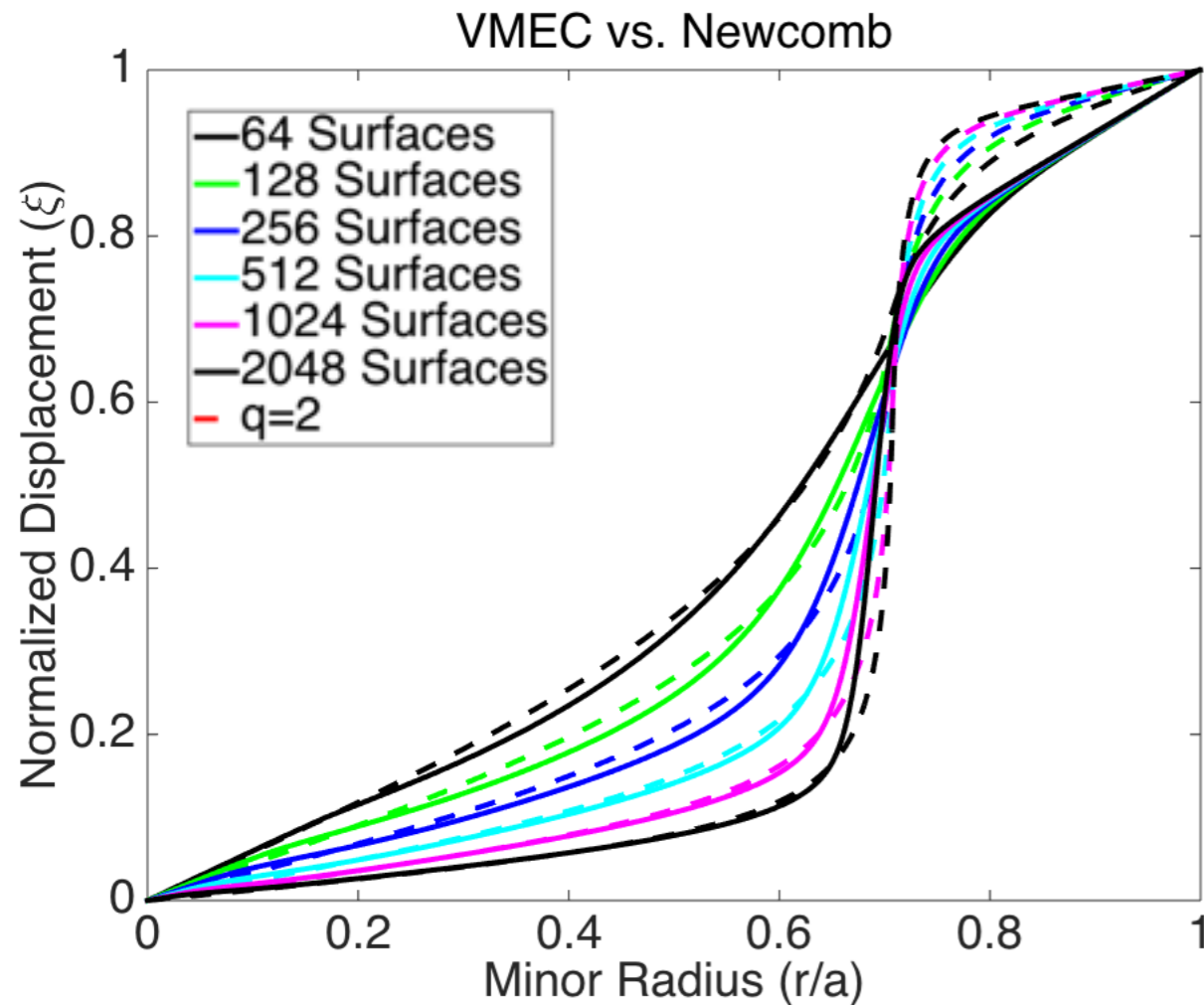


Response shows some shear dependence



Shear and radial resolution play a role. However the effective discontinuity is greater than the minimum necessary for nested flux surfaces and that which can be attributed to the radial finite difference.

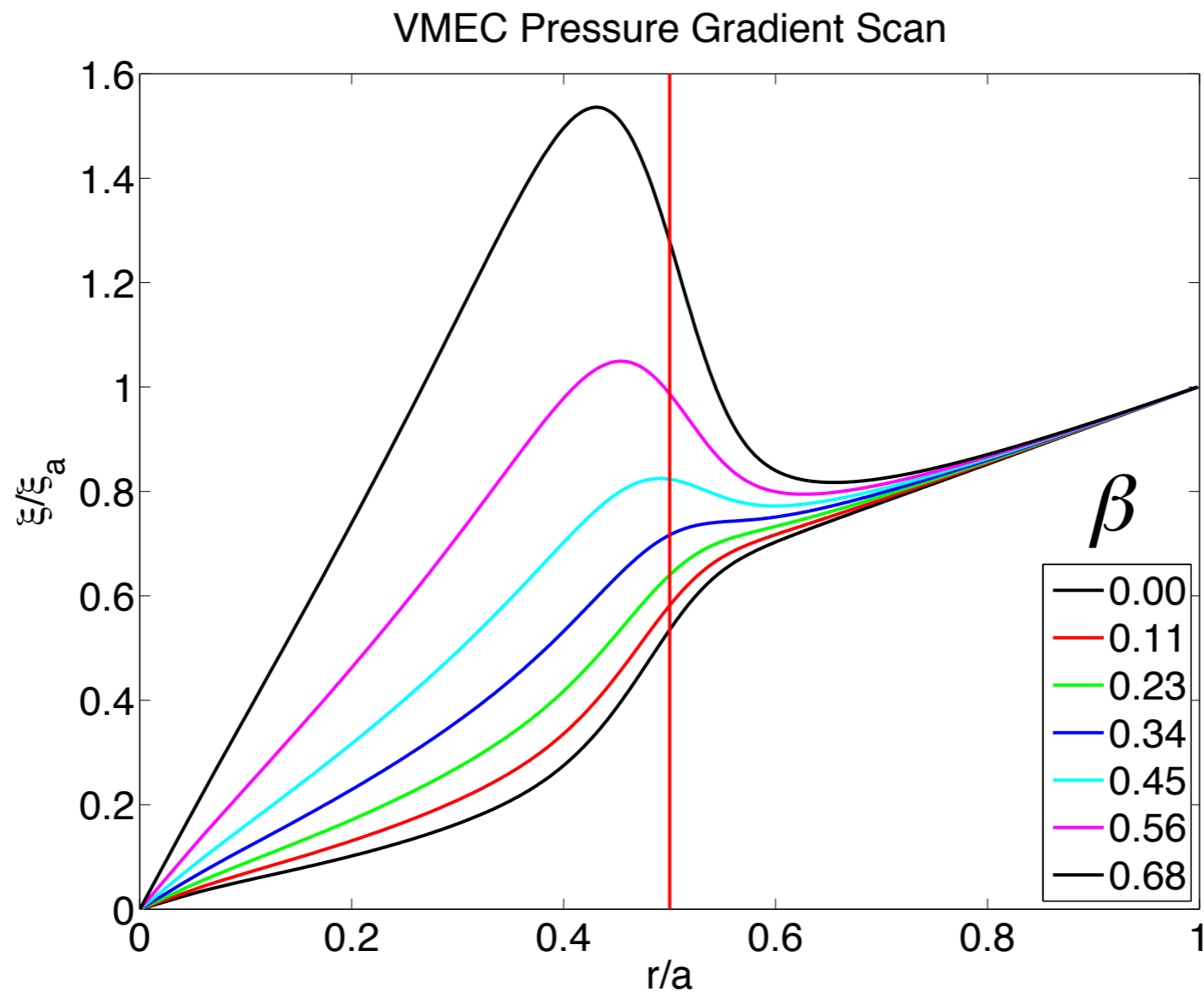
Qualitative agreement with theory



Comparison with the linear model suggests that despite the absence of a discontinuous iota profile, VMEC is obtaining qualitatively similar solutions.

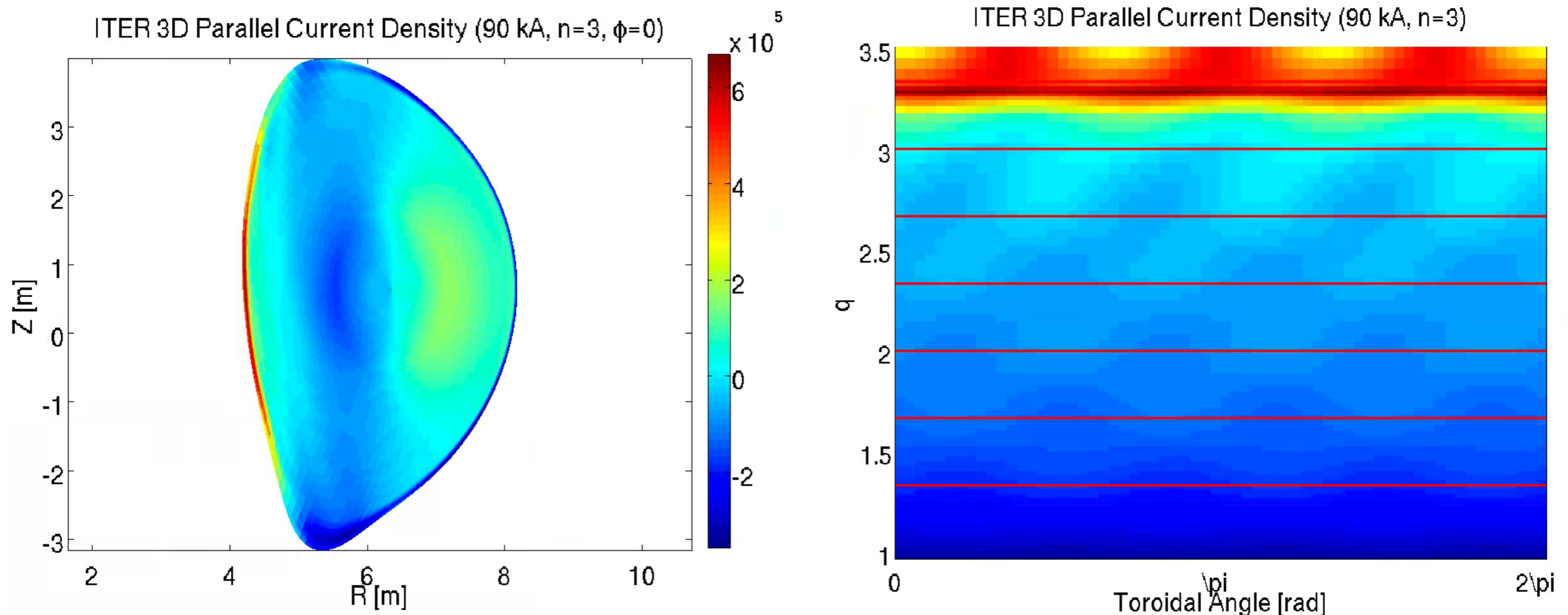
VMEC exhibits the finite beta response as well

In this model pressure gradients can amplify resonant perturbations.



Effects present in real tokamak equilibria

The structure of the current density in the more realistic geometry of a 'perturbed' tokamak shows that this type of response is not limited to the screw-pinch case.



Conclusions

- The newly developed solutions to Newcomb's problem provide a means to validate the VMEC plasma response across rational surfaces.
- This new theoretical formulation suggests that VMEC is lacking transform discontinuities in its formulation.
- Despite this shortcoming the VMEC code qualitatively reproduces the non-local response across a resonant surface.
- This response is also present in tokamak equilibria with applied RMP fields.