ma02aa

Constructs Beltrami field in given volume consistent with flux, helicity, rotational-transform and/or parallel-current constraints.

[called by: dforce.] [calls: packab, df00ab, mp00ac.]

contents

1.1 seqeuntial quadratic programming

1. Only relevant if `LBsequad=T`. See `LBeltrami` for details.
2. Documentation on the implementation of NAG: E04UFF is under construction.

1.2 Newton method

1. Only relevant if `LBnewton=T`. See `LBeltrami` for details.

1.3 "linear" method

1. Only relevant if `LBlinear=T`. See `LBeltrami` for details.
2. The quantity μ is not not treated as a "magnetic" degree-of-freedom equivalent to in the degrees-of-freedom in the magnetic vector potential (as it strictly should be, because it is a Lagrange multiplier introduced to enforce the helicity constraint).
3. In this case, the Beltrami equation, $\nabla \times \mathbf{B} = \mu \mathbf{B}$, is linear in the magnetic degrees-of-freedom.
4. The algorithm proceeds as follows:

1.3.1 plasma volumes

(a) In addition to the enclosed toroidal flux, $\Delta\psi_t$, which is held constant in the plasma volumes, the Beltrami field in a given volume is assumed to be parameterized by μ and $\Delta\psi_p$. (Note that $\Delta\psi_p$ is not defined in a torus.)

(b) These are "packed" into an array, e.g. $\boldsymbol{\mu} \equiv (\mu, \Delta\psi_p)^T$, so that standard library routines , e.g. NAG: C05PCF, can be used to (iteratively) find the appropriately-constrained Beltrami solution, i.e. $\mathbf{f}(\boldsymbol{\mu}) = 0$.

(c) The function $\mathbf{f}(\boldsymbol{\mu})$, which is computed by mp00ac, is defined by the input parameter `Lconstraint`:

i. If `Lconstraint = -1, 0`, then $\boldsymbol{\mu}$ is not varied and `Nxdof=0`.

ii. If `Lconstraint = 1`, then $\boldsymbol{\mu}$ is varied to satisfy the transform constraints; and `Nxdof=1` in the simple torus and `Nxdof=2` in the annular regions. (Note that in the "simple-torus" region, the enclosed poloidal flux $\Delta\psi_p$ is not well-defined, and only $\mu = \boldsymbol{\mu}_1$ is varied in order to satisfy the transform constraint on the "outer" interface of that volume.)

iii. If `Lconstraint = 2`, then $\mu = \boldsymbol{\mu}_1$ is varied in order to satisfy the helicity constraint, and $\Delta\psi_p = \boldsymbol{\mu}_2$ is not varied, and `Nxdof=1`. **(under re-construction)**

1.3.2 vacuum volume

(a) In the vacuum, $\mu = 0$, and the enclosed fluxes, $\Delta\psi_t$ and $\Delta\psi_p$, are considered to parameterize the family of solutions. (These quantities may not be well-defined if $\mathbf{B} \cdot \mathbf{n} \neq 0$ on the computational boundary.)

(b) These are "packed" into an array, $\boldsymbol{\mu} \equiv (\Delta\psi_t, \Delta\psi_p)^T$, so that, as above, standard routines can be used to iteratively find the appropriately constrained solution, i.e. $\mathbf{f}(\boldsymbol{\mu}) = 0$.

(c) The function $\mathbf{f}(\boldsymbol{\mu})$, which is computed by mp00ac, is defined by the input parameter `Lconstraint`:

i. If `Lconstraint = -1`, then $\boldsymbol{\mu}$ is not varied and `Nxdof=0`.

ii. If `Lconstraint = 0,2`, then $\boldsymbol{\mu}$ is varied to satisfy the enclosed current constraints, and `Nxdof=2`.

iii. If `Lconstraint = 1`, then $\boldsymbol{\mu}$ is varied to satisfy the constraint on the transform on the inner boundary $\equiv$ plasma boundary and the "linking" current, and `Nxdof=2`.

5. The Beltrami fields, and the rotational-transform and helicity etc. as required to determine the function $\mathbf{f}(\boldsymbol{\mu})$ are calculated in mp00ac.

6. This routine, mp00ac, is called iteratively if `Nxdof > 1` via NAG: C05PCF to determine the appropriately constrained Beltrami field, $\mathbf{B}_{\boldsymbol{\mu}}$, so that $\mathbf{f}(\boldsymbol{\mu}) = 0$.

7. The input variables `mupftol` and `mupfits` control the required accuracy and maximum number of iterations.

8. If `Nxdof = 1`, then mp00ac is called only once to provide the Beltrami fields with the given value of $\boldsymbol{\mu}$.

1.4 debugging: finite-difference confirmation of the derivatives of the rotational-transform

1. Note that the rotational-transform (if required) is calculated by tr00ab, which is called by mp00ac.

2. If `Lconstraint=1`, then mp00ac will ask tr00ab to compute the derivatives of the transform with respect to variations in the helicity-multiplier, μ, and the enclosed poloidal-flux, $\Delta\psi_p$, so that NAG: C05PCF may more efficiently find the solution.

3. The required derivatives are

$$\frac{\partial \iota\!\!\!-}{\partial \mu} \tag{1}$$

$$\frac{\partial \iota\!\!\!-}{\partial \Delta\psi_p} \tag{2}$$

   to improve the efficiency of the iterative search. A finite difference estimate of these derivatives is available; need `DEBUG`, `Lcheck=2` and `Lconstraint=1`.