

# Progress in Linear and Nonlinear Two-Fluid Resistive Plasma Response to Non-Axisymmetric Fields

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**General Atomics**

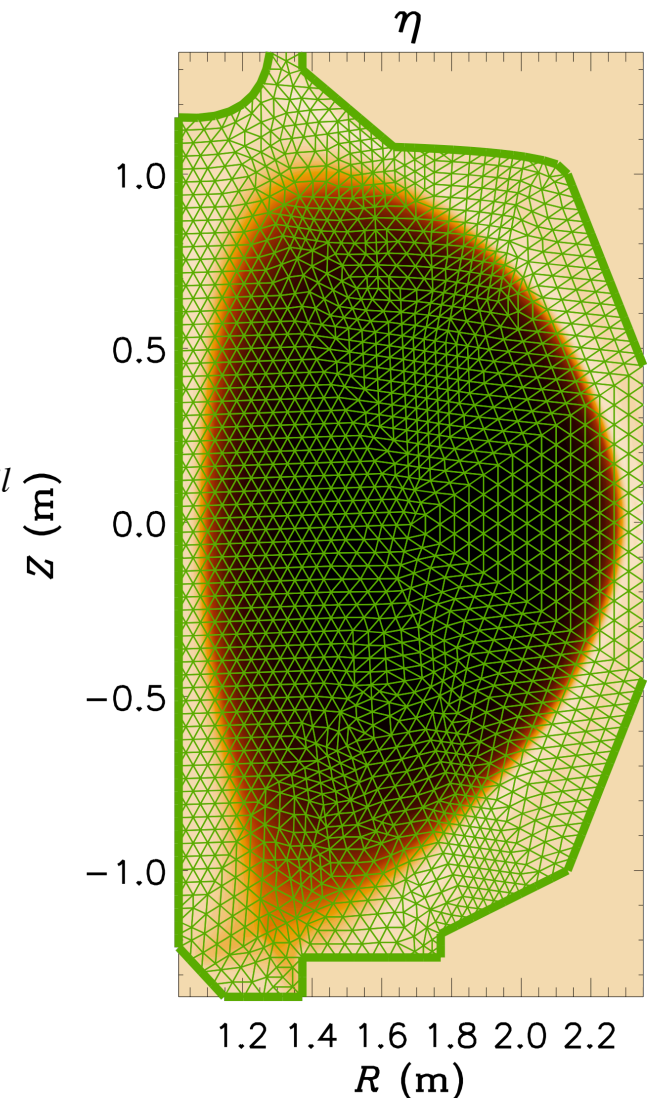
**CEMM**  
**Salt Lake City, UT**  
**Nov. 13, 2011**

# Outline

- **Miscellaneous Progress in M3D-C1**
- **Linear Results**
  - Influence of rotation
  - Ion rotation vs. Electron rotation
- **Linear vs. Nonlinear**

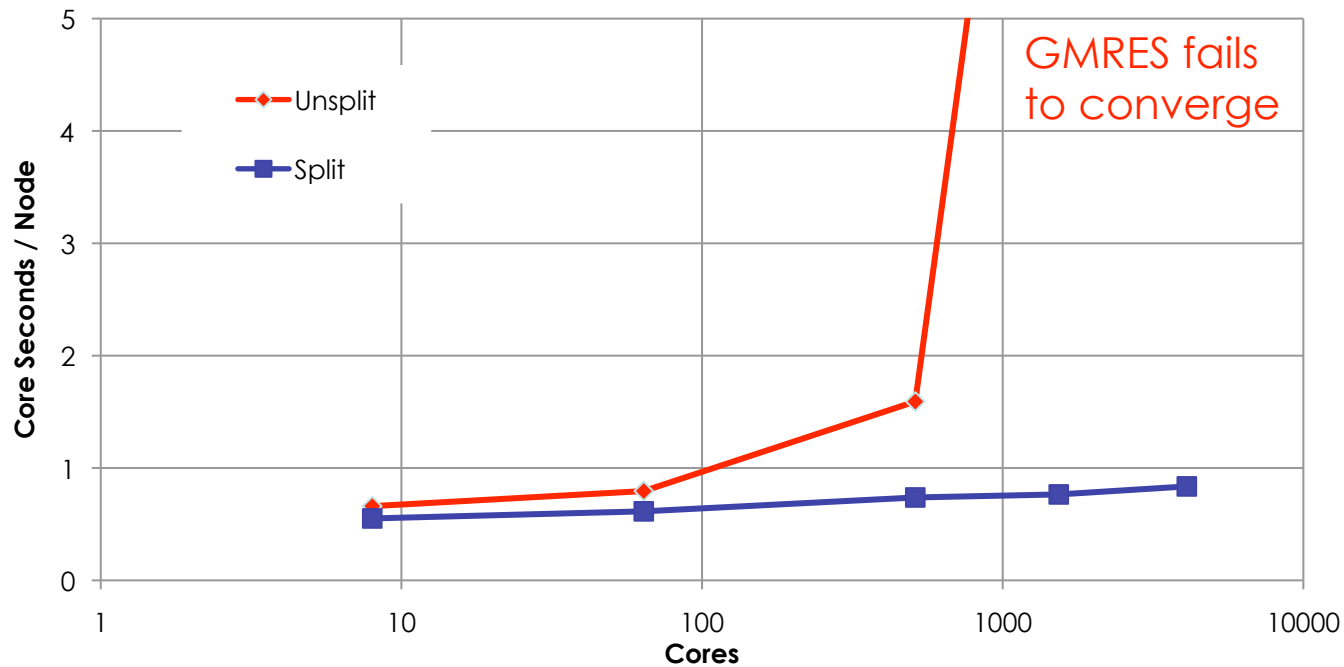
# Miscellaneous Progress in M3D-C1

- Ability to generate realistic mesh boundaries
- Ability to include non-axisymmetric coils inside of computational domain
  - Fields are decomposed:  $\mathbf{B} = \mathbf{B}_{eq} + \mathbf{B}_{plas} + \mathbf{B}_{coil}$
  - Terms involving  $\mathbf{J}_{coil}$  are removed from eqns.
- VisIt visualization (Sanderson)
- Transitioning focus from Linear → Nonlinear



# Split Method Scales Much Better Than Unsplit

## Weak Scaling in 3D



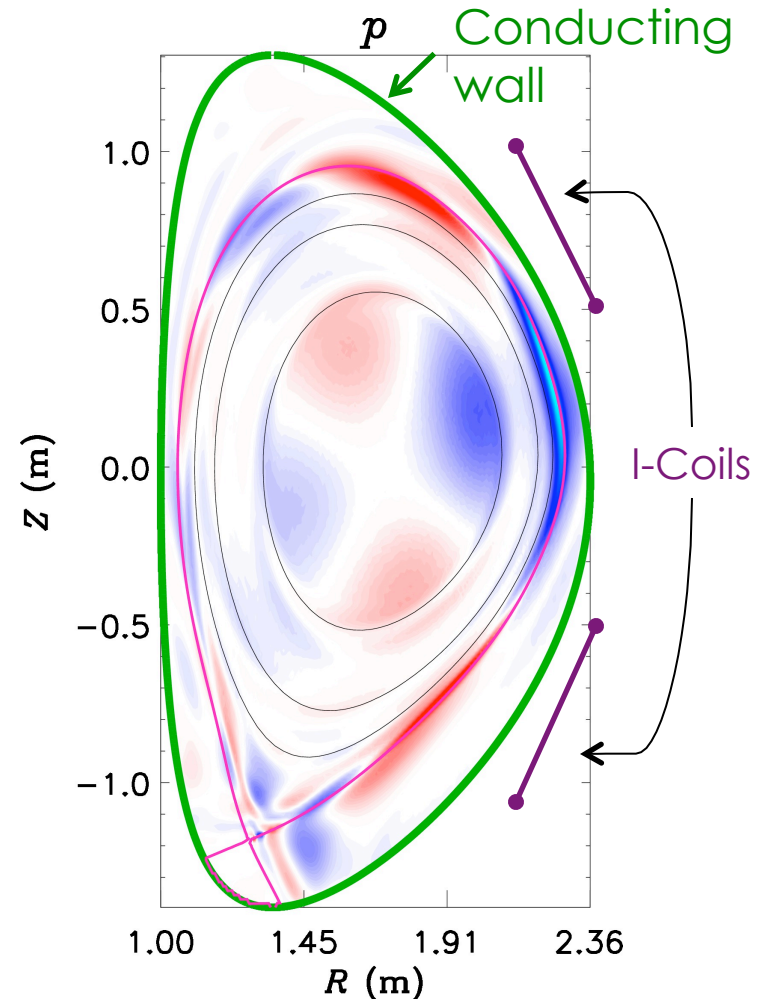
- **Unsplit method fails at large core counts**
  - (GMRES fails to converge)



# 3D Response

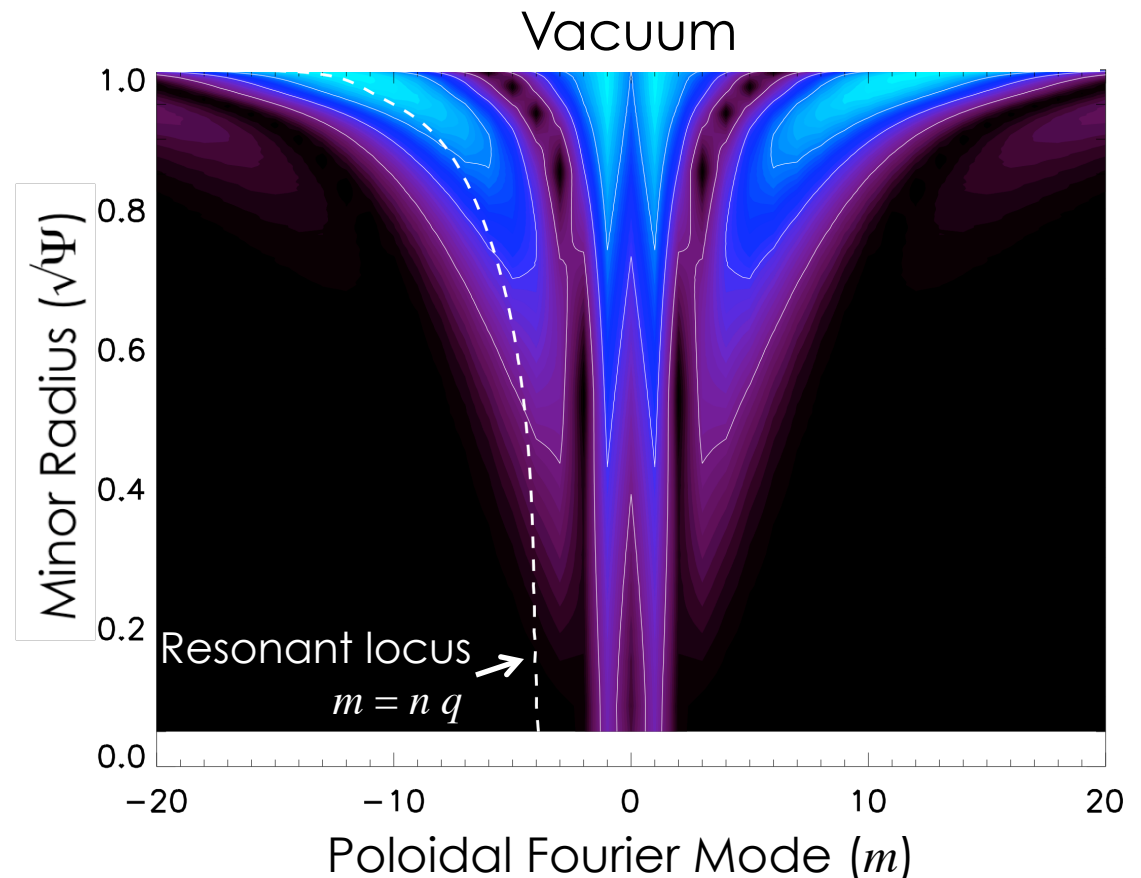
# Analysis Considers Reconstructed DIII-D Equilibria

- **Vacuum fields generated by DIII-D I-coils**
- **Boundary conditions:**
  - Vacuum  $B_n$  is held constant at the boundary
  - No-slip ( $\mathbf{v}=0$ )
- **Realistic transport parameters**
  - Lundquist number  $\sim 10^9$
- **Toroidal rotation**
  - Rotation is added self-consistently:  $p \neq p(\psi)$



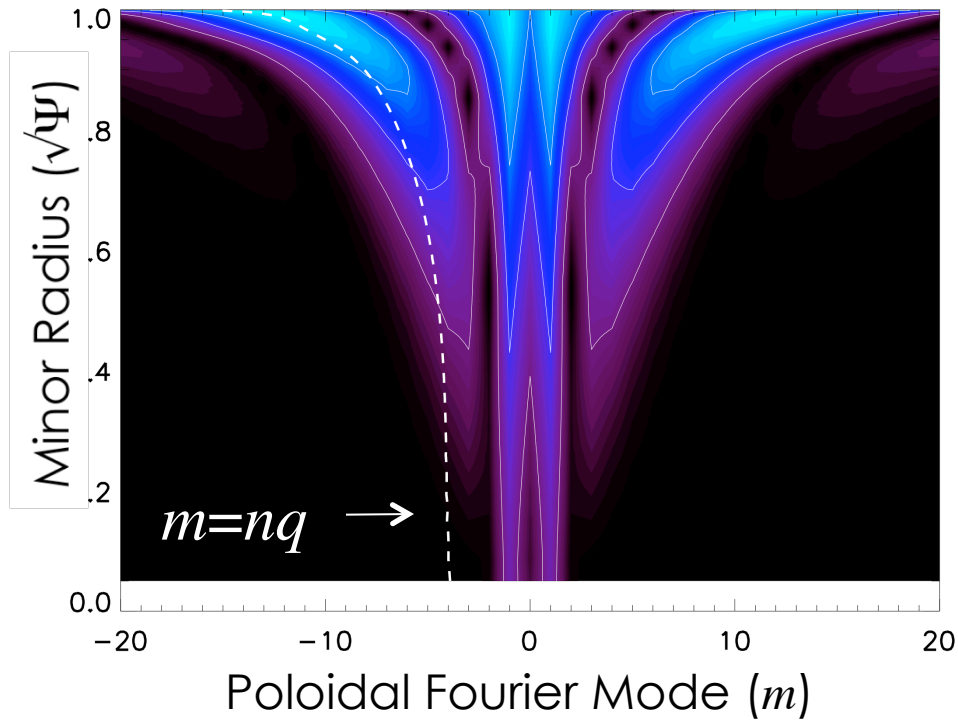
# Non-Resonant Fields Bend Surfaces; Resonant Fields Tear Surfaces

- Plot shows Fourier spectrum of  $B_n$
- $B_n$  = component of applied field normal to equilibrium magnetic surfaces
- Resonant components (along dashed line) cause islands
- Non-resonant components cause bending of surfaces
- Poloidal spectrum of  $B_n$  depends on  $\Psi$

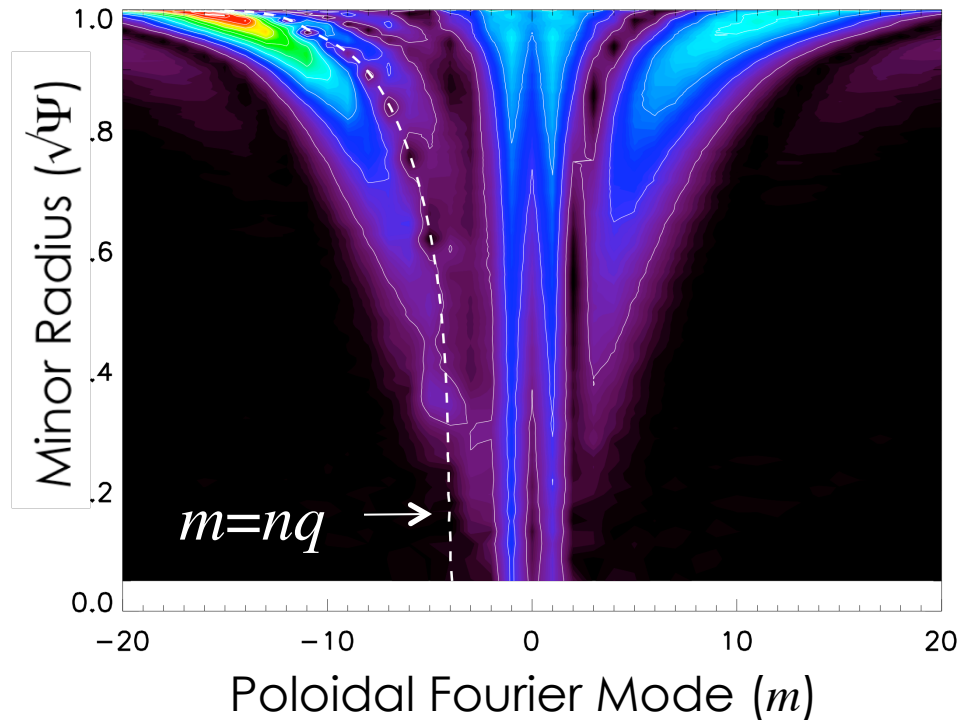


# Plasma Response Modifies Spectrum

Vacuum



Plasma



- **Ideal response  $\rightarrow$  no islands  $\rightarrow$  reduction in resonant components**
- **Excited ideal modes  $\rightarrow$  enhancement of non-resonant components**

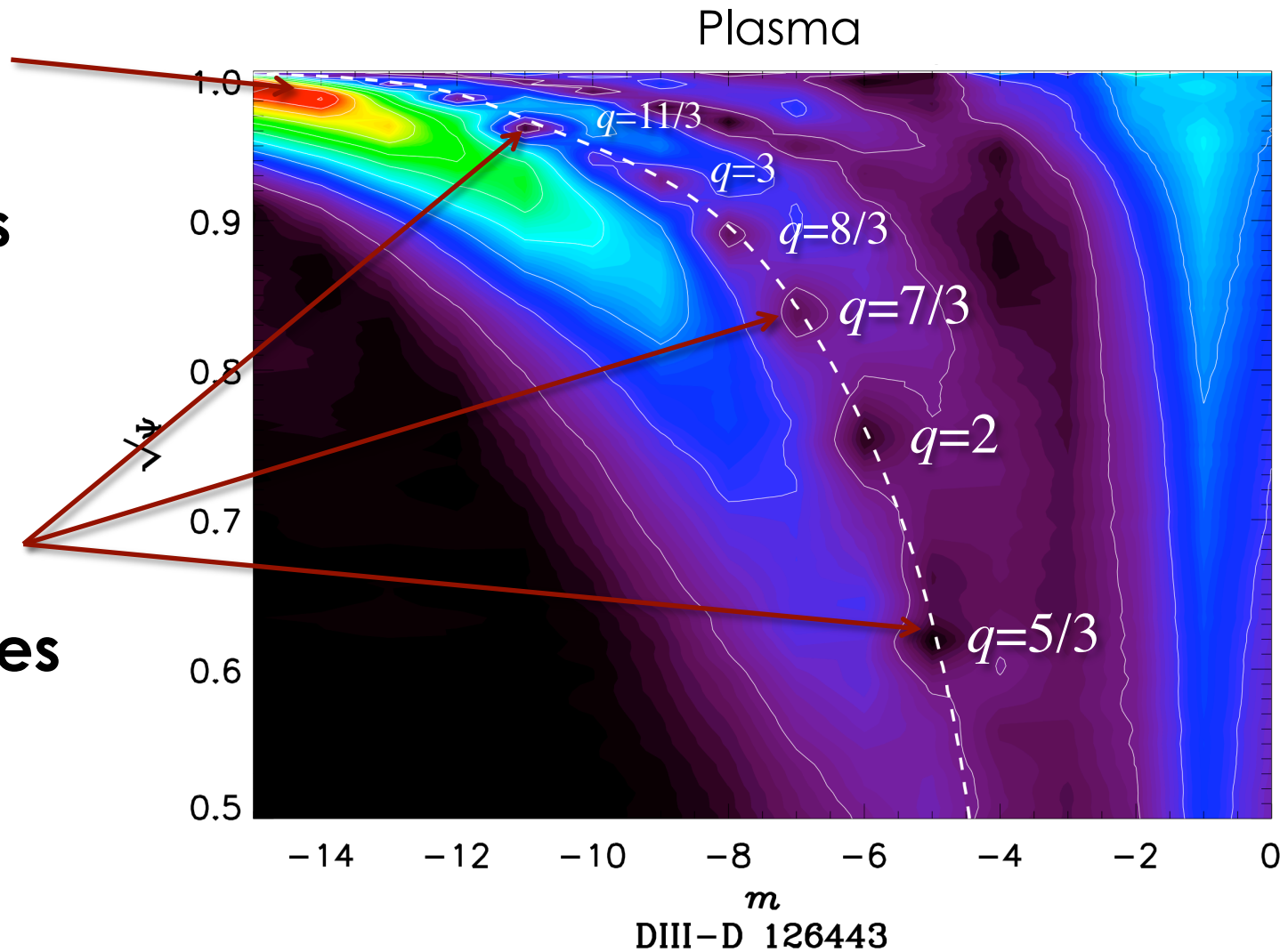
# Plasma Can Kink and Screen

“Kinking”

- **Distorts surfaces**

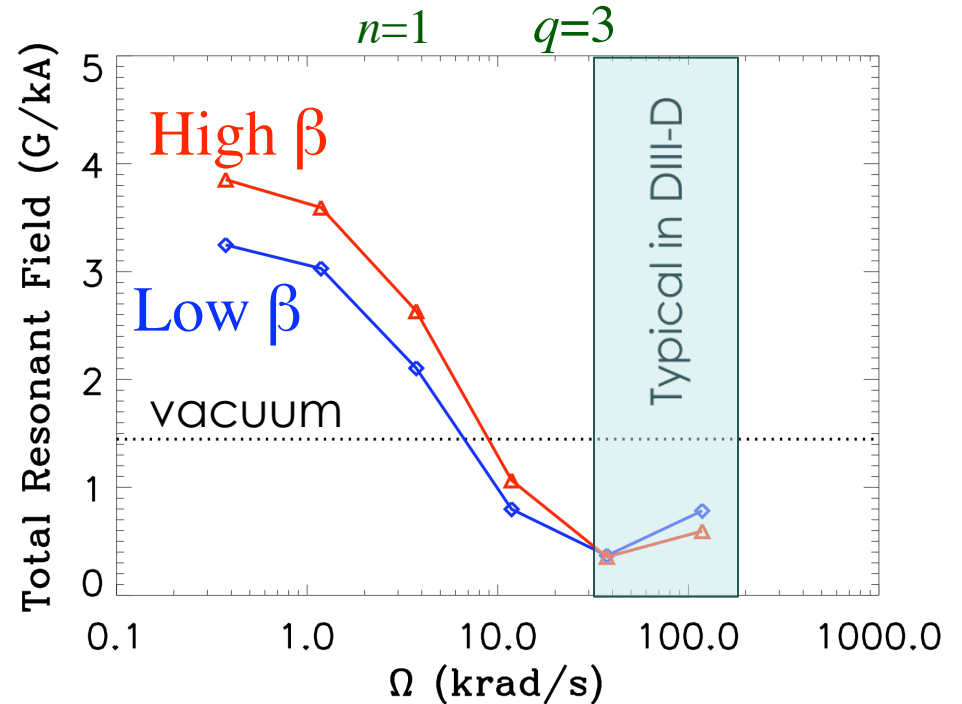
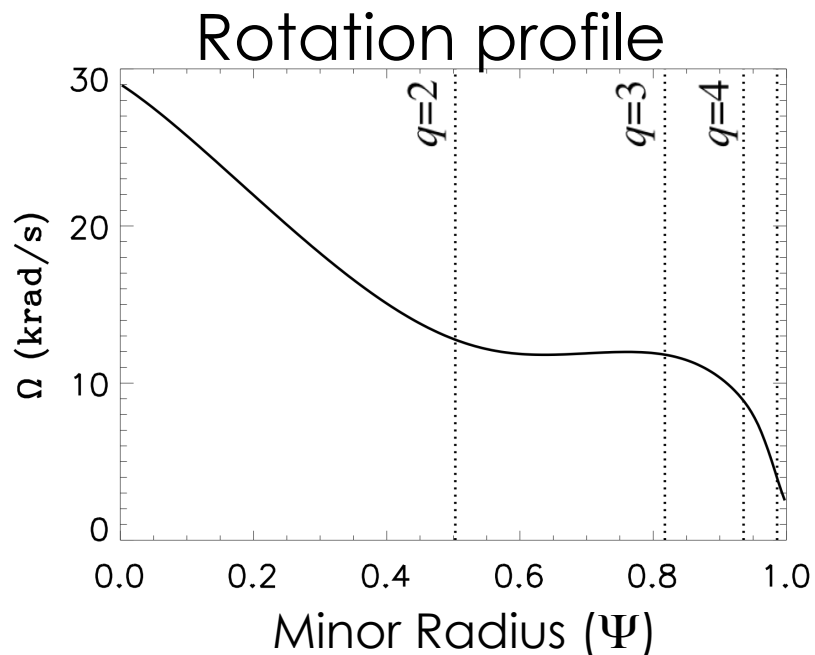
Screening

- **Eliminates islands**



# Single-Fluid Results

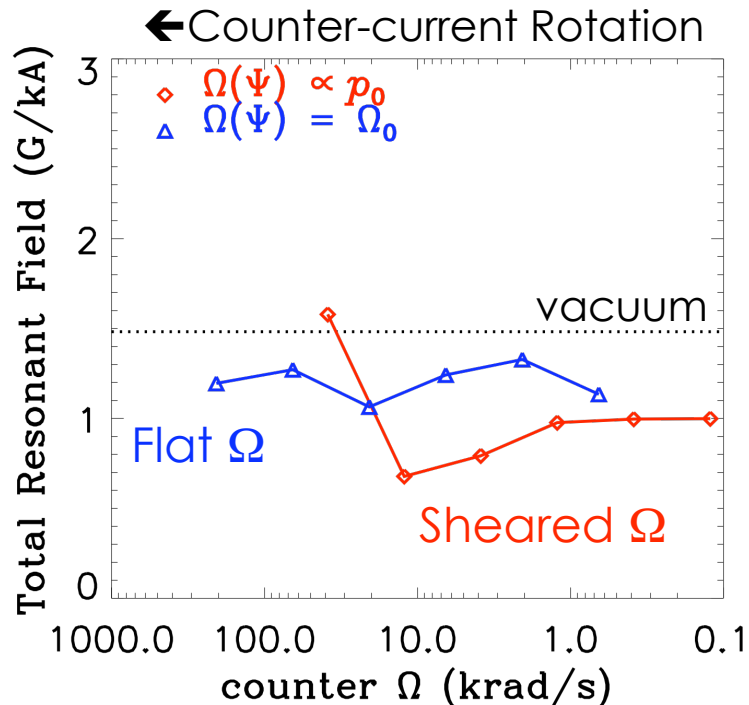
# Single-Fluid Result: Rotation (Usually) Improves Screening



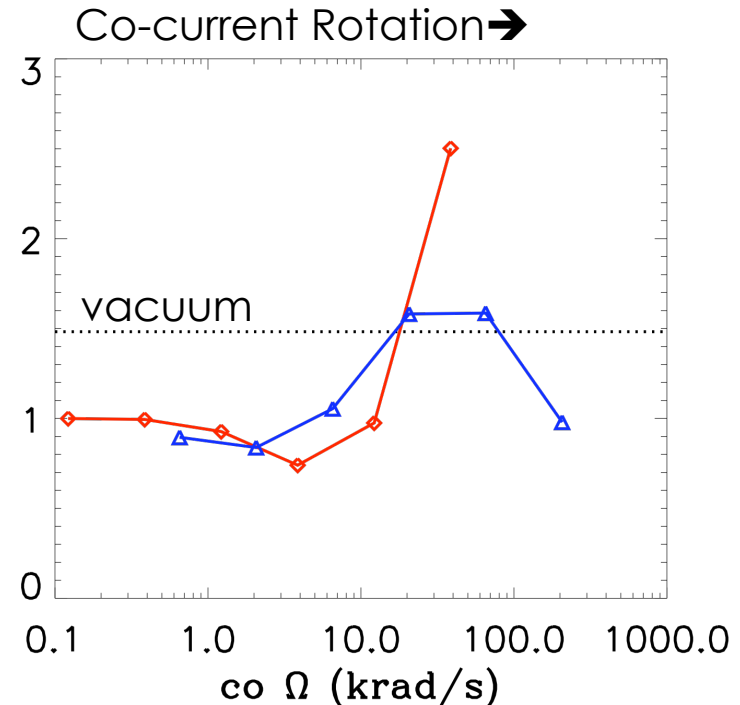
- Plasma may enhance resonant fields at low rotation
- Large rotation screens resonant fields
- Response depends on beta

# Single-Fluid Result: Rotation Shear Increases Edge Response

DIII-D 135762



$q=5$



- Large rotation shear seems to increase edge response
- **Why?** Theory predicts  $\Omega'$  is destabilizing to low- $n$  peeling-ballooning modes\*

\* Snyder, et al. *Nucl. Fusion* **47** (2007)

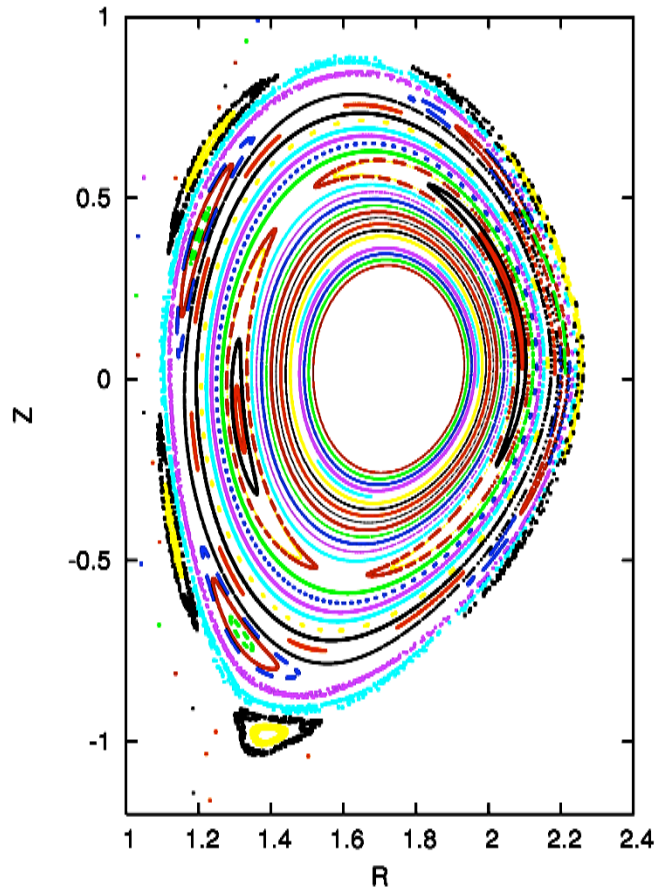
Aiba, et al. *Nucl. Fusion* **50** (2010)

Ferraro, et al. *Phys. Plasmas* **17** (2010)

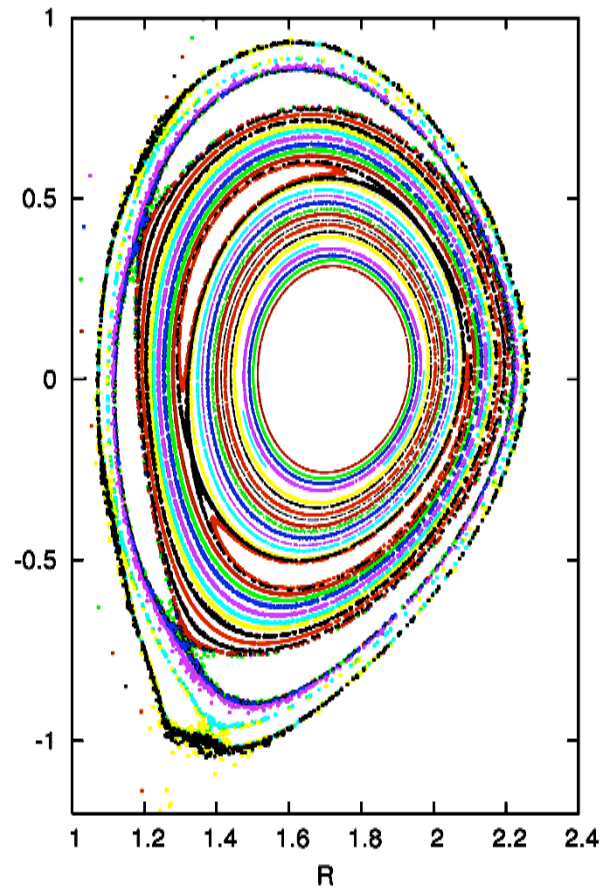


# Rotation Improves Core Screening; But Sheared Rotation Stochasticizes Edge

Vacuum

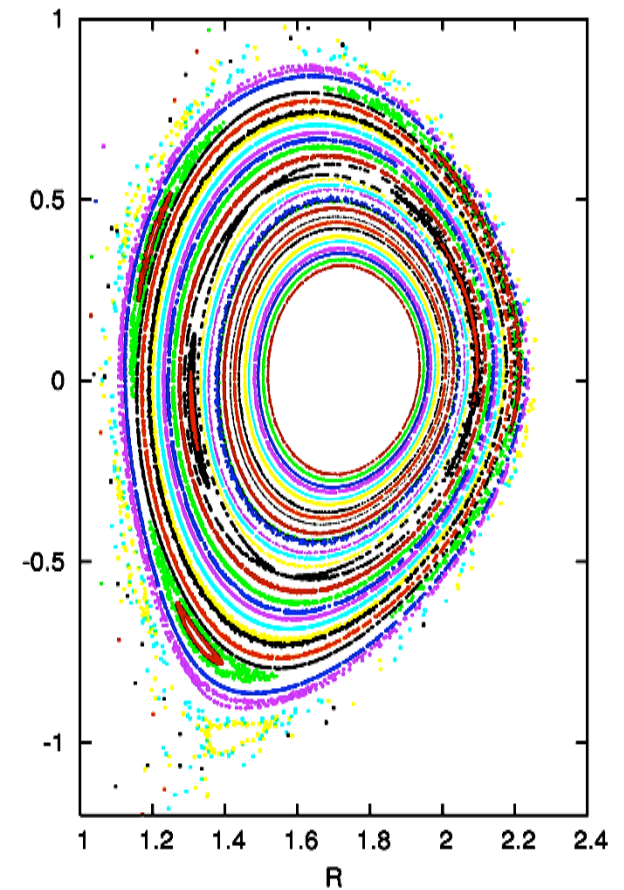


Plasma, Static



$$\Omega_0=0$$

Plasma, Rotating

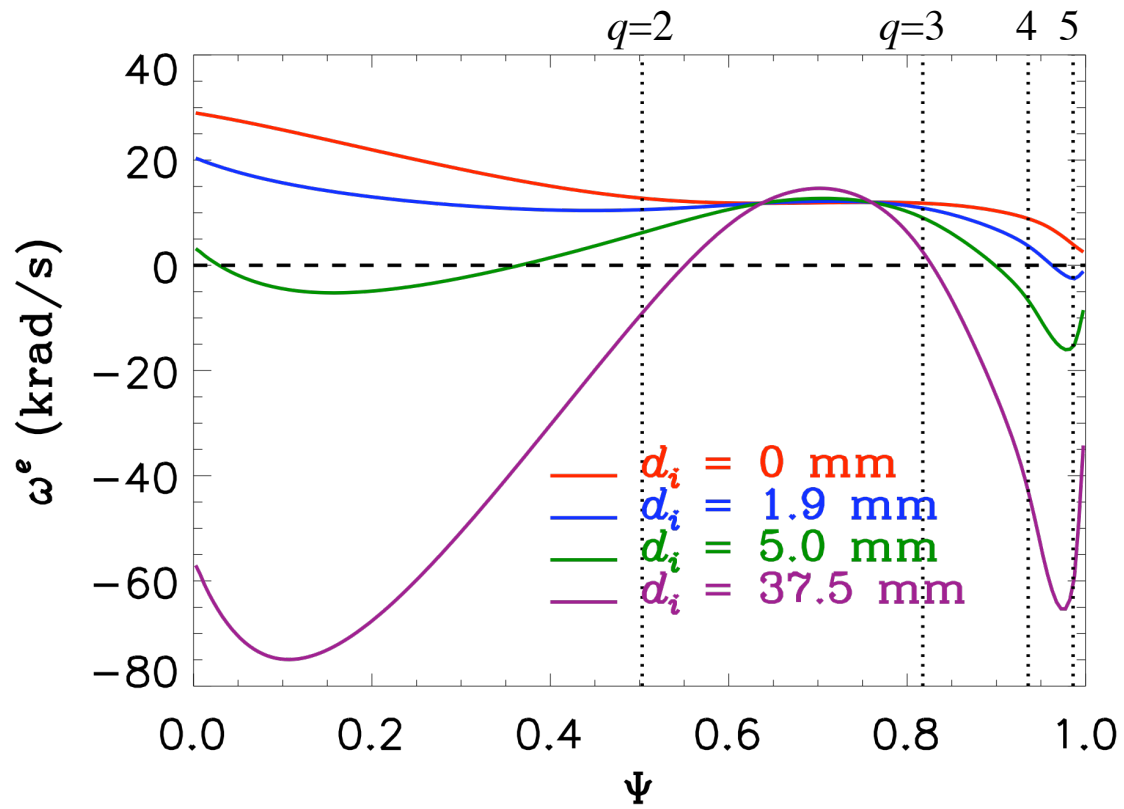


$$\Omega_0=300 \text{ krad/s}$$

# Two-Fluid Results

# Two-Fluid Results: Ion and Electron Rotations are Distinct

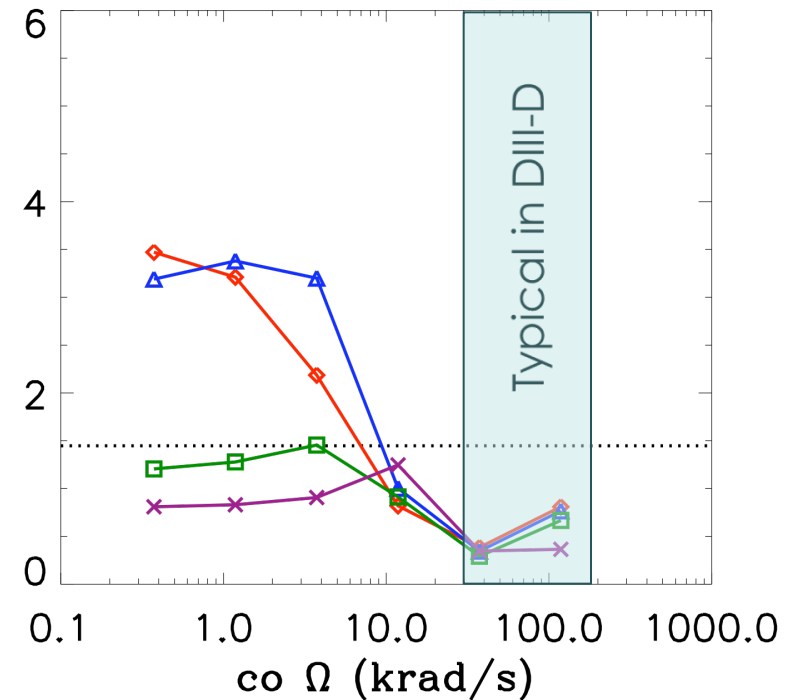
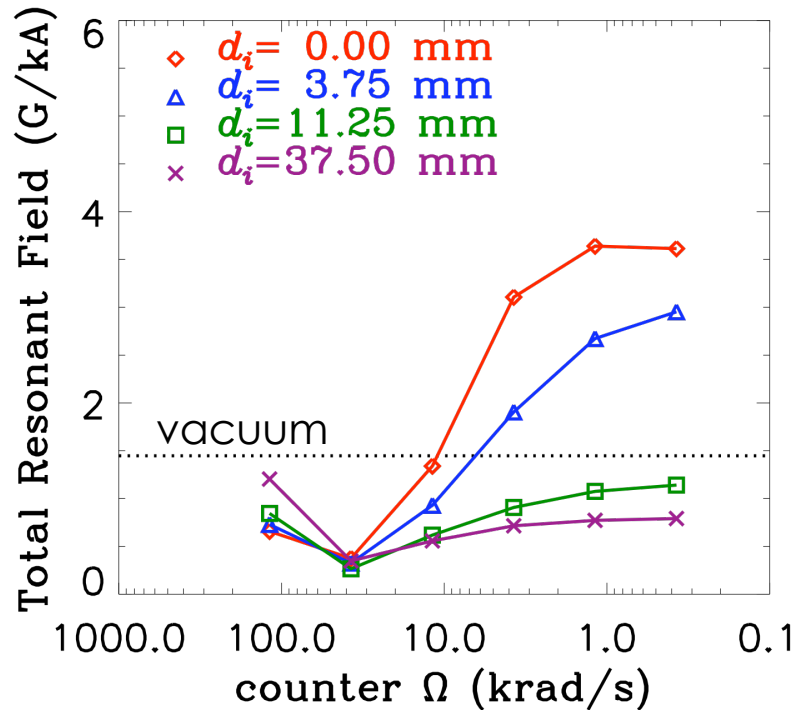
- Given  $\Omega$ , we can change  $\Omega^e = \Omega + \omega_*$  by adjusting  $\omega_* = d_i p' / n$



For this equilibrium,  $d_i = 37.5$  mm is the physical value

# Two-Fluid Effects Shift Resonance

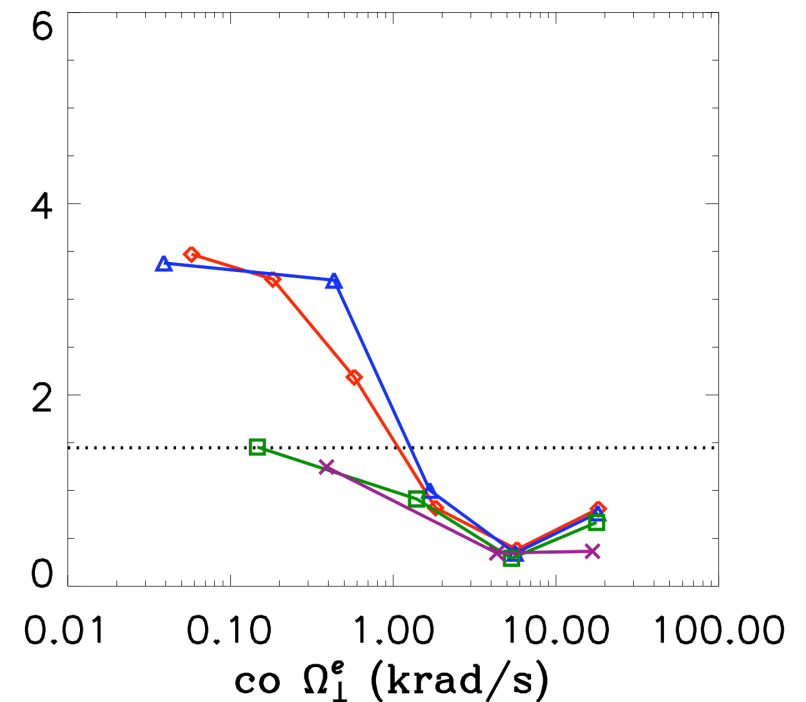
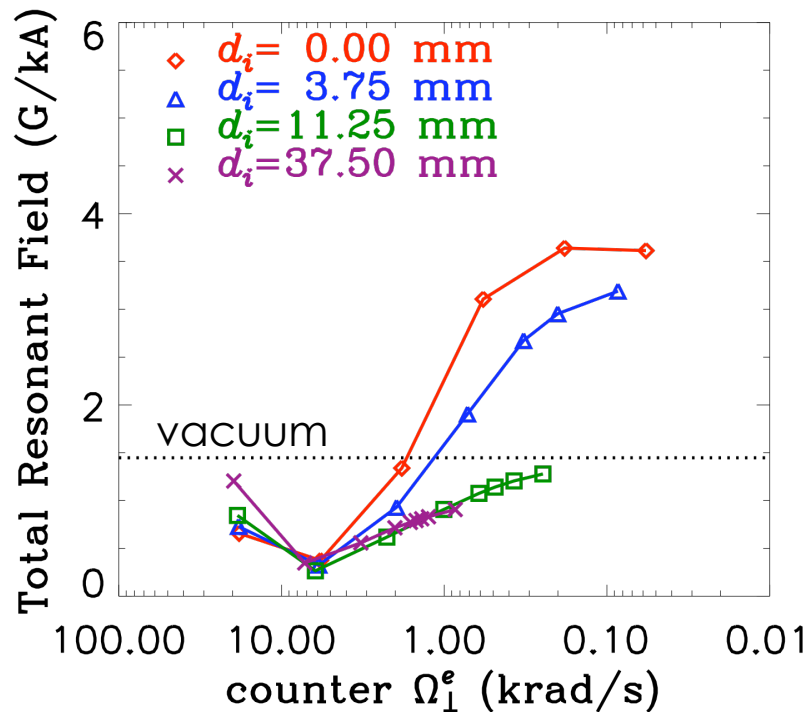
(Mass) rotation at  $q=3$



- Strongest tearing no longer occurs at  $\Omega = 0$

# Penetration In Core Depends on Electron Rotation

Perpendicular electron rotation at  $q = 3$

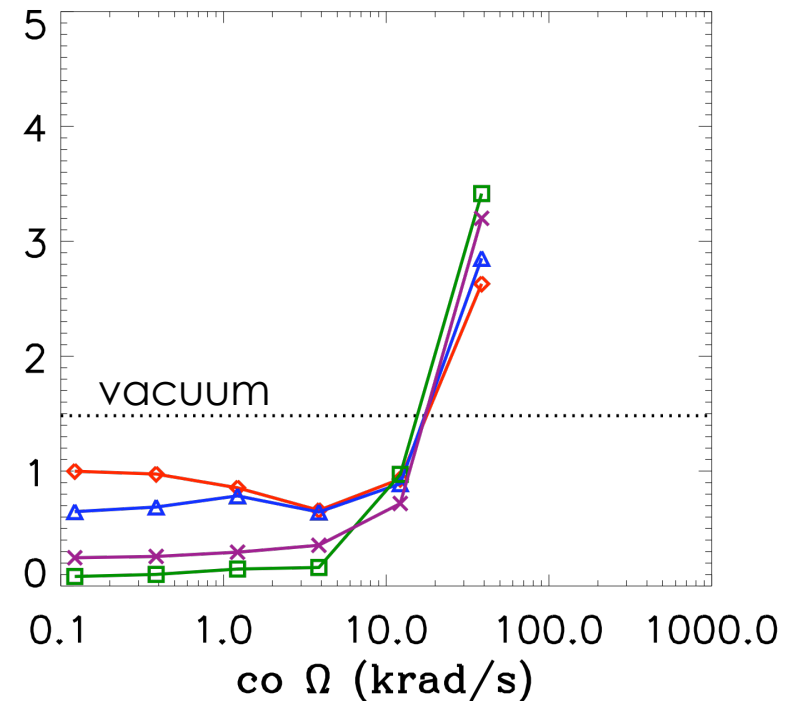
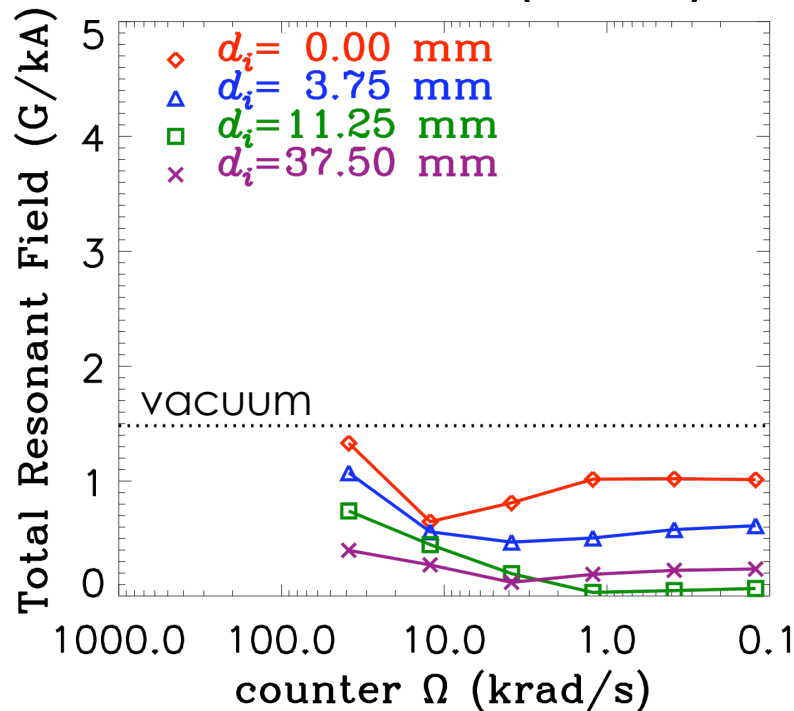


- Screening of  $q=3$  island clearly depends more on  $\Omega^e$  than  $\Omega$

# Edge Response Depends on Mass Rotation Shear

- Tearing of edge modes is dependent on ion, not electron, rotation shear

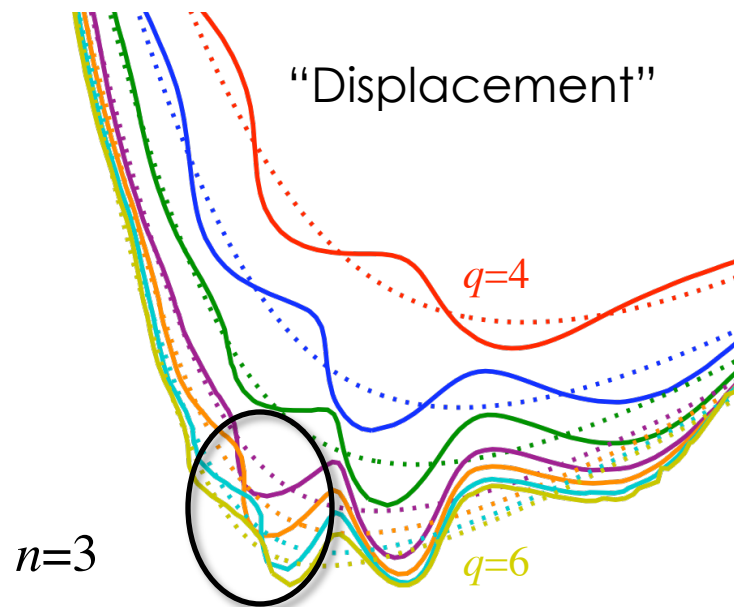
(Mass) rotation at  $q=5$



# Linear vs. Nonlinear

# Is Linear Response Appropriate?

- For typical experimental parameters, linear response may not be strictly valid in some regions
  - Large current density near rational surfaces
  - Back-reaction on rotation is important



5 kAt even-parity I-Coil

- “Displacement” shows overlapping surfaces near separatrix!

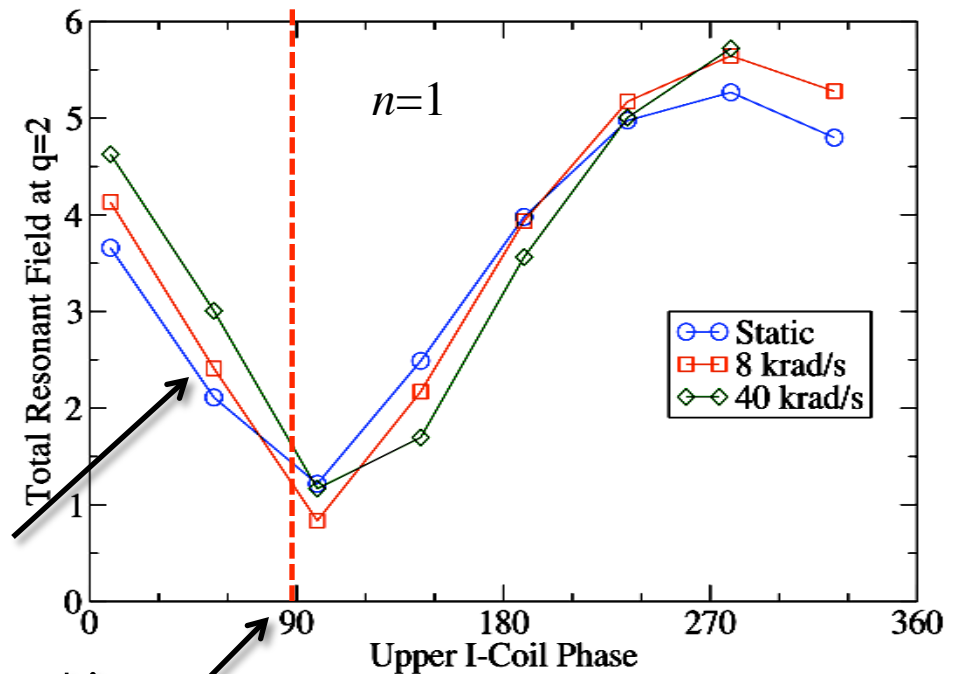
- Quantitative predictions of island size, stochasticity from linear calculations are suspect



# Linear Response Gets Some Things Right

- Which modes are most sensitive
- How parameters (rotation, viscosity, etc.) affect sensitivity
- **How to optimize coil design**

Calculated resonant field  
(proxy for resonant torque)

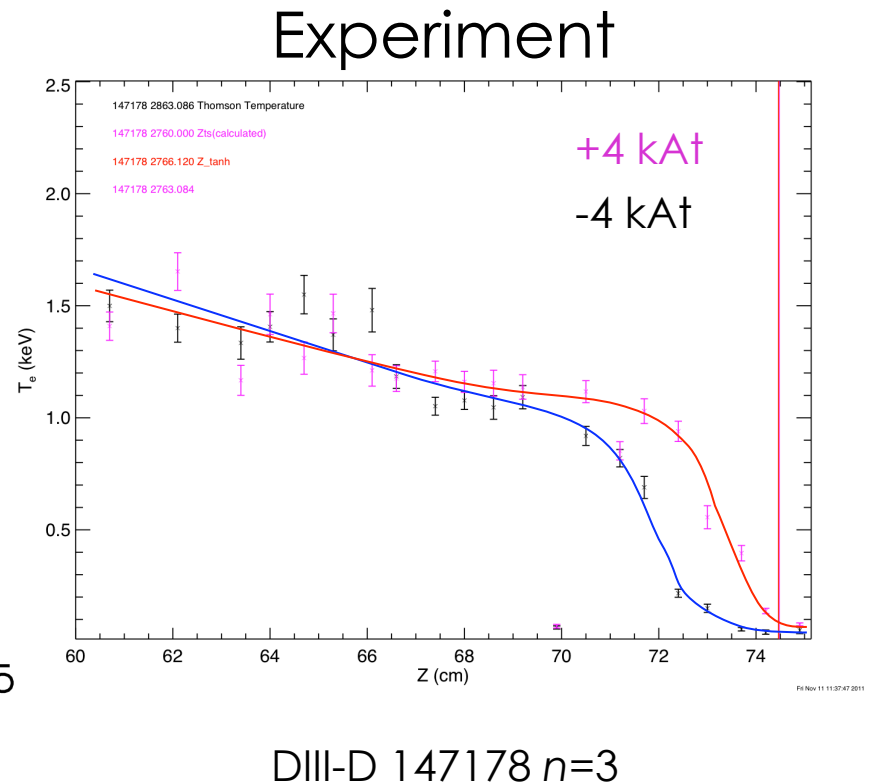
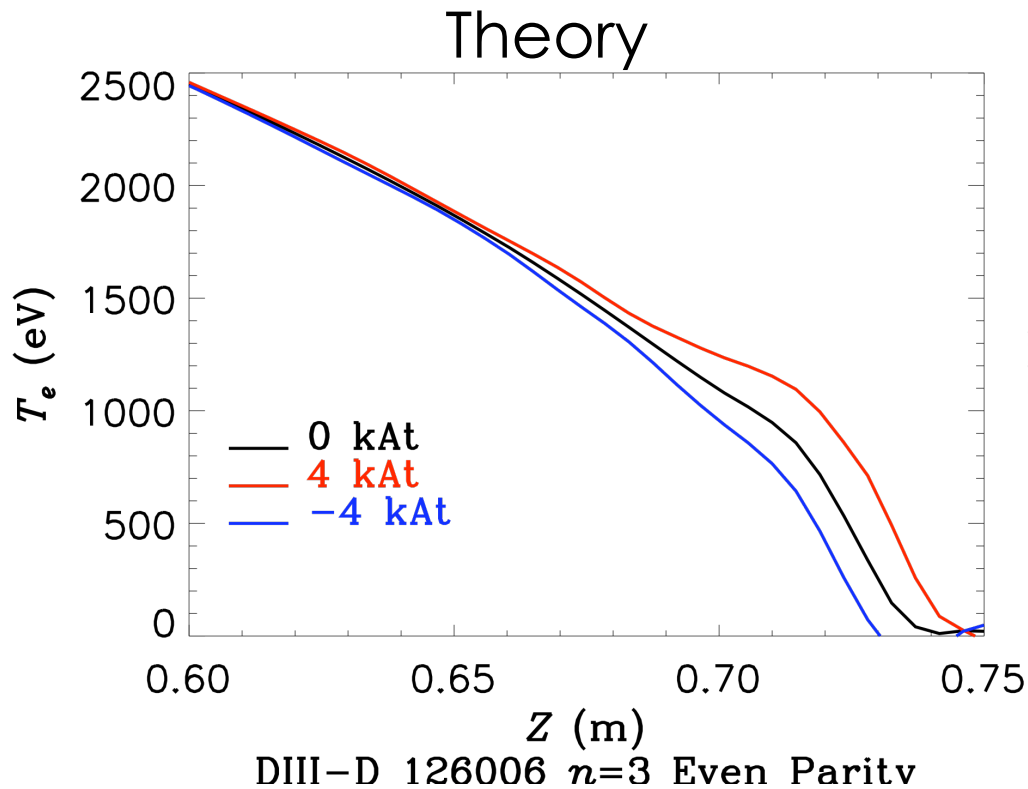


Empirical phase least prone to locking

DIII-D 144182

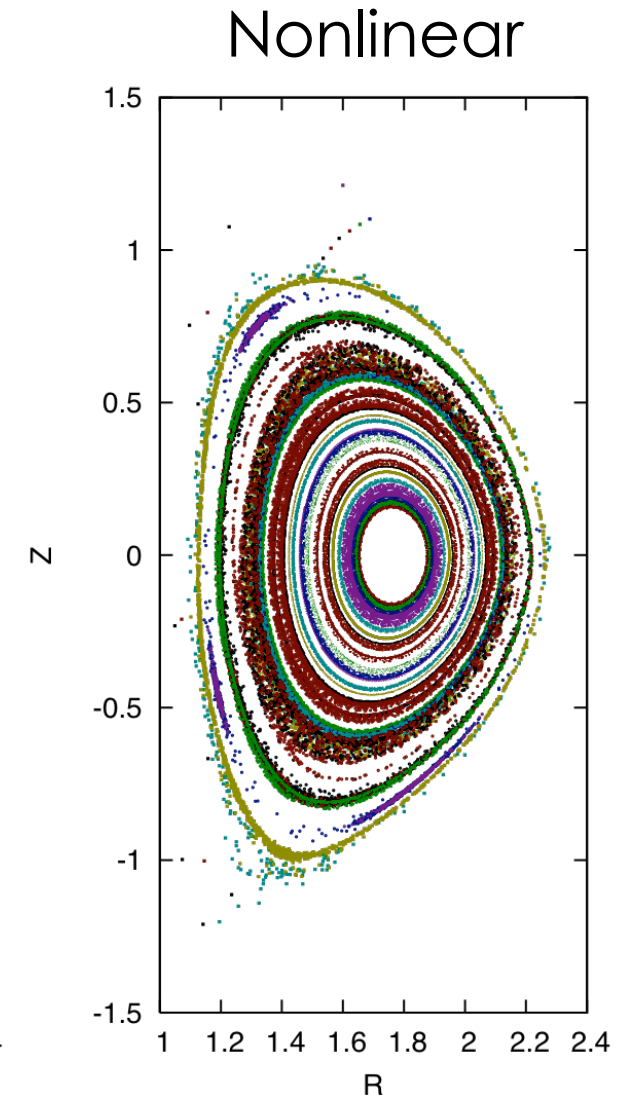
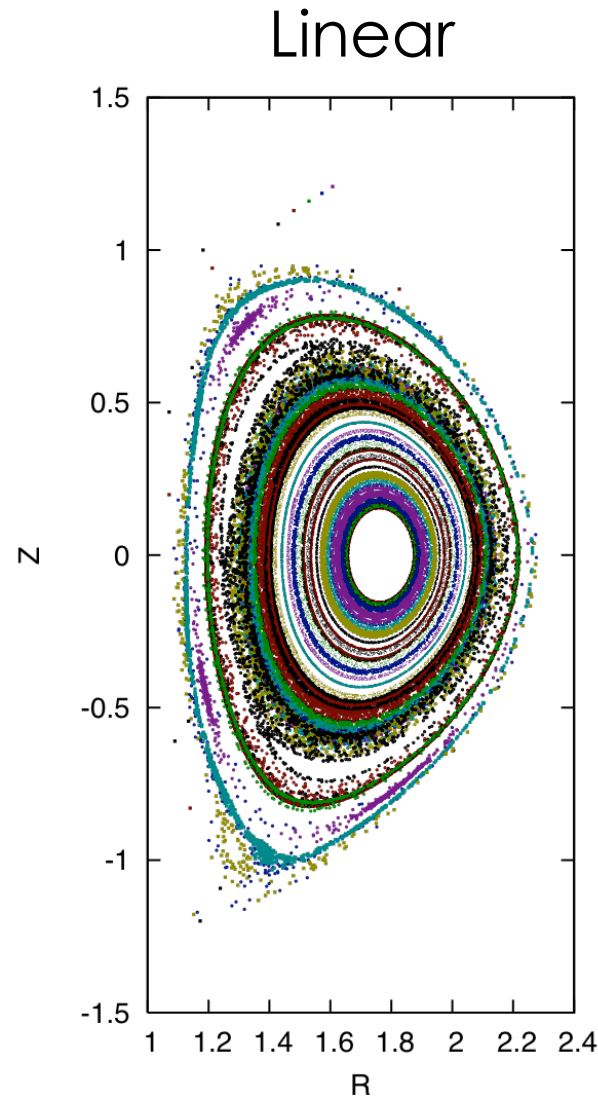
# 3D Fields Shift Edge $T_e$ Profile

- Linear calculations seem to capture  $T_e$  profile shift seen in experiment



# Nonlinear Calculations are Underway

- **Nonlinear calculations are necessary for some things**
  - Rotation/locking
  - Transport
  - Large islands
- **Preliminary non-linear results agree with linear results for non-rotating plasma**



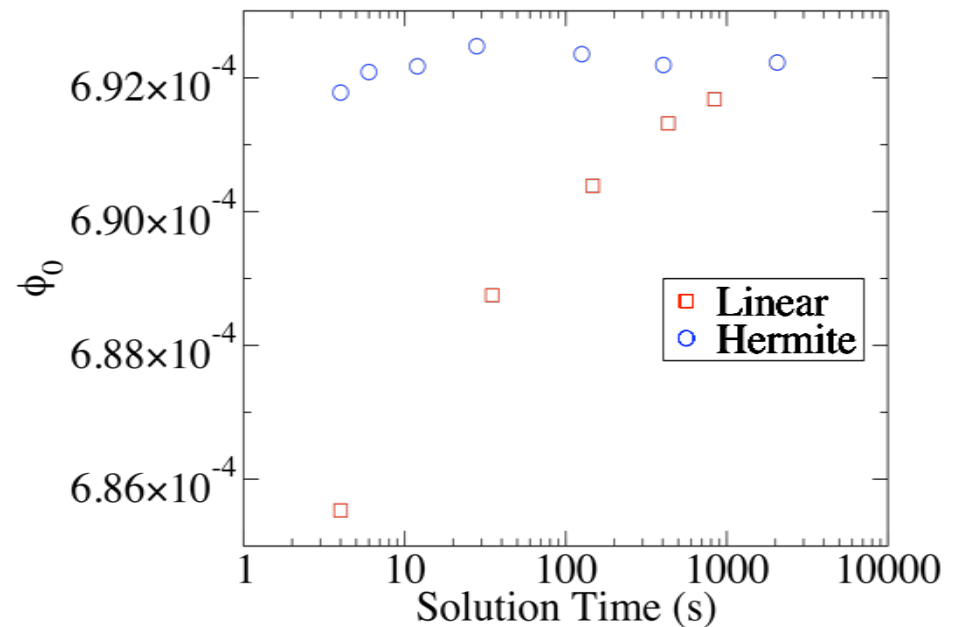
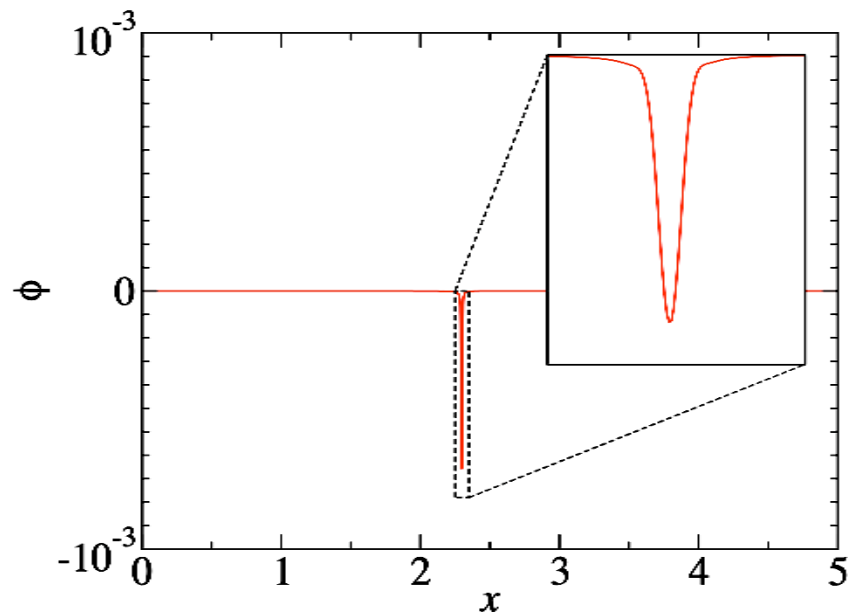
# Opportunities For CEMM

- **3D equilibrium properly requires nonlinear calculation**
  - $n = 0$  rotation and  $n \neq 0$  response are strongly coupled
  - Island saturation is nonlinear
  - There is healthy debate how to do this efficiently!
- **Can we simulate a rotation bifurcation (locking)?**
- **M3D, M3D-C1, and NIMROD are well positioned to address these challenges**

# Extra Slides

# Hermite Elements Are More Efficient Than Linear Elements For Resolving A Boundary Layer in 1D

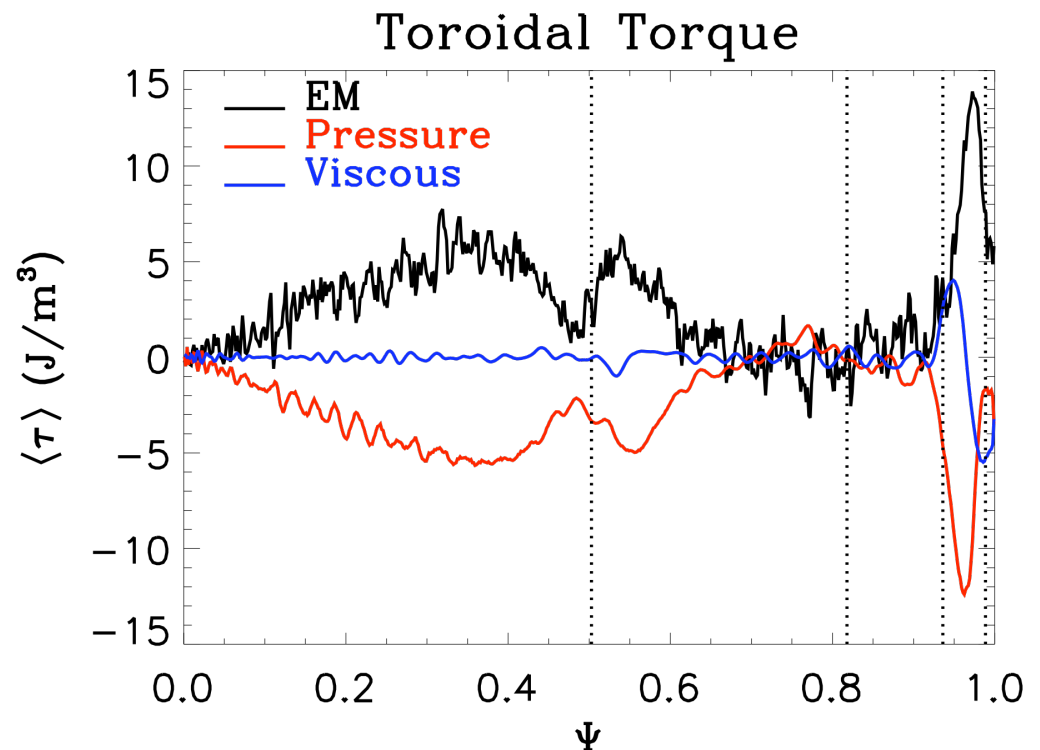
- Simple equilibrium with one mode-rational surface
- Width of boundary layer determined by resistivity
  - $\eta = 10^{-9}$ ,  $\Delta\phi \sim \eta^{1/3}$



# Dominant Balance is Between EM and Pressure Torques (At First Order)

- **(Poloidal) surface average of first-order torques shows balance between EM and pressure torque densities**

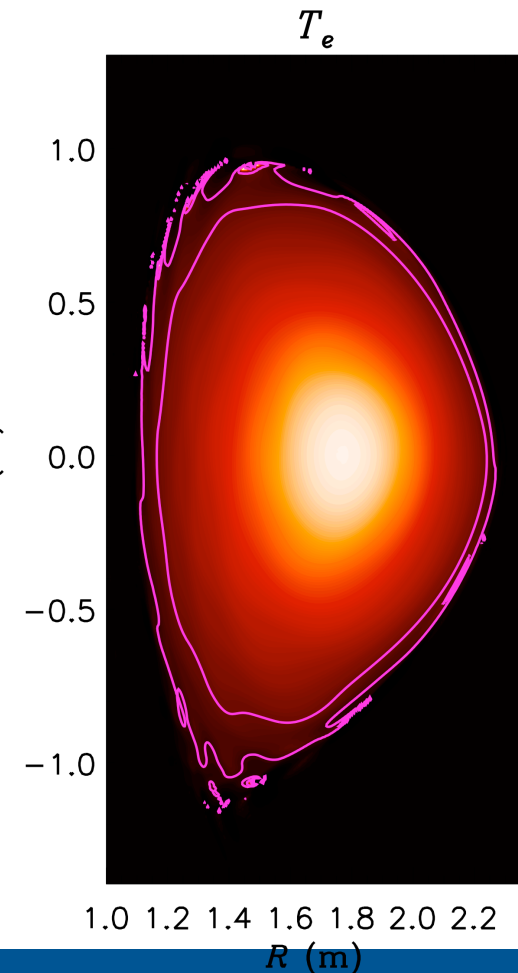
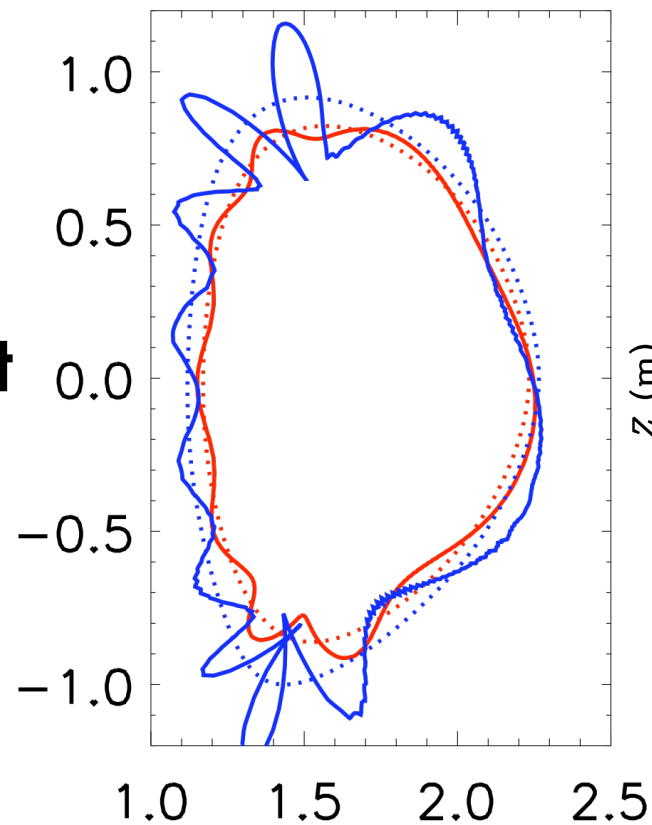
- This is for a low beta ( $\beta_N=1.14$ ), high viscosity ( $3.6 \text{ m}^2/\text{s}$ ) case!
- Full flux-surface averages would yield 0 at this order (due to  $e^{in\phi}$  dependence)



- **Second-order balance requires nonlinear calculation**

# “Displacement” is Not Always an Accurate Measure of Surface Displacement

- The ideal “displacement” can give a poor indication of perturbed surfaces
- $T_e$  isosurfaces can deviate significantly from displacement





# What is “Perpendicular” Electron Velocity?

- The perpendicular angular velocity is defined as

$$\Omega_{\perp}^{e,i} = \frac{\mathbf{v}^{e,i}}{R} \cdot \frac{\mathbf{B} \times \nabla \psi}{|\mathbf{B} \times \nabla \psi|}$$

- To lowest order,  $\mathbf{v}^{e,i} = R^2 \omega^{e,i}(\psi) \nabla \varphi + \lambda^{e,i} \mathbf{B}$ . Thus:

$$\Omega_{\perp}^{e,i} = \frac{|\nabla \psi \times \nabla \varphi|}{|B|} \omega^{e,i}(\psi)$$

- From radial force balance:  $\omega^{e,i}(\psi) = \phi'(\psi) + \frac{p_{e,i}'(\psi)}{n_{e,i} q_{e,i}}$
- $\Omega_{\perp}^e$  vanishes wherever  $\omega^e$  vanishes, but also at  $\mathbf{B}_{pol}$  nulls

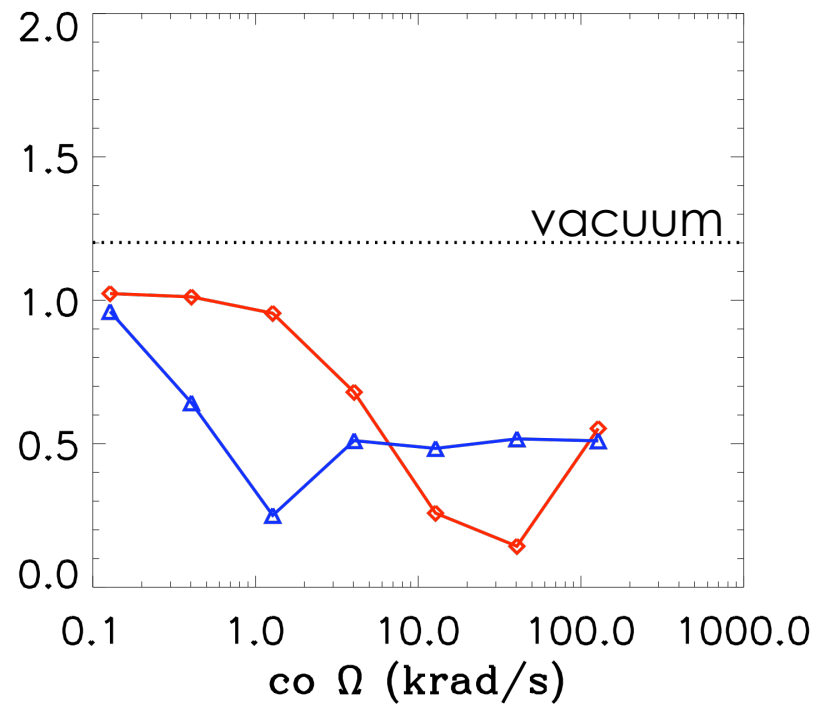
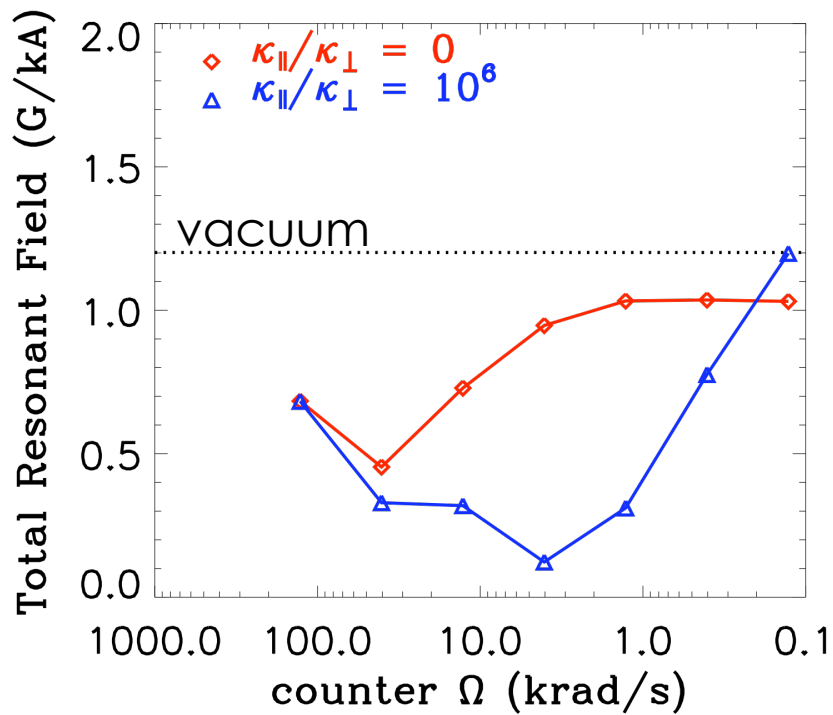
# Diamagnetic Drift

- The diamagnetic drift may be represented in the standard  $\mathbf{v} = R^2\omega(\psi)\nabla\varphi + \lambda\mathbf{B}$  form if  $p$  is a flux function

$$\begin{aligned}\mathbf{v}_* &= \frac{\mathbf{B} \times \nabla p}{neB^2} \\ &= R^2 \frac{p'}{ne} \nabla\varphi - \frac{p'}{ne} \frac{RB_\varphi}{B^2} \mathbf{B}\end{aligned} \quad \Rightarrow \quad \begin{aligned}\omega_* &= \frac{p'}{ne} \\ \lambda_* &= \frac{p'}{ne} \frac{RB_\varphi}{B^2}\end{aligned}$$

# Parallel Thermal Conductivity Narrows Rotation Resonance

$$q=2$$



Single-fluid calculation

# Two-Fluid Model

$$\frac{\partial n}{\partial t} + \nabla \cdot (n\mathbf{u}) = 0$$

$$n \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = \mathbf{J} \times \mathbf{B} - \nabla p - \nabla \cdot \Pi$$

$$\frac{\partial p}{\partial t} + \mathbf{u} \cdot \nabla p = -\Gamma p \nabla \cdot \mathbf{u} - \frac{d_i}{n} \mathbf{J} \cdot \left( \Gamma p_e \frac{\nabla n}{n} - \nabla p_e \right) - (\Gamma - 1) \nabla \cdot \mathbf{q}$$

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

$$\mathbf{E} = -\mathbf{u} \times \mathbf{B} + \eta \mathbf{J} + \frac{d_i}{n} (\mathbf{J} \times \mathbf{B} - \nabla p_e)$$

$$\Pi = -\mu \left[ \nabla \mathbf{u} + (\nabla \mathbf{u})^T \right]$$

$$\mathbf{q} = -\kappa \nabla \left( \frac{p}{n} \right) - \kappa_{\parallel} \mathbf{b} \mathbf{b} \cdot \nabla \left( \frac{p_e}{n} \right)$$

$$\mathbf{J} = \nabla \times \mathbf{B}$$

$$\Gamma = 5/3$$

$$p_e = p/2$$

- Complete (not reduced) **two-fluid** model is implemented
- **Time-independent** equations may be solved directly for linear response