

NUMERICAL CALCULATION OF THE NEOCLASSICAL ELECTRON DISTRIBUTION FUNCTION IN AN AXISYMMETRIC TORUS

B.C. LYONS (PPPL), S.C. JARDIN (PPPL), J.J. RAMOS (MIT PSFC)

ANNUAL CEMM MEETING
SALT LAKE CITY, UT
SUNDAY, NOVEMBER 13, 2011

Outline

2

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- Initial Results
- Conclusion

Outline

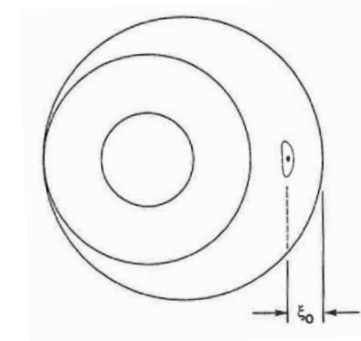
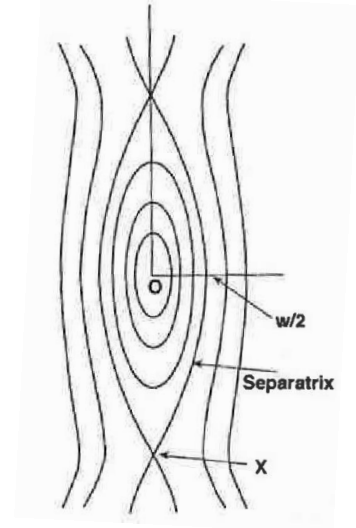
3

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- Initial Results
- Conclusion

Neoclassical tearing mode (NTMs)

4

- Density, temperature, pressure, etc. tend to equilibrate across an island width
- Difference in current at O-point and X-point can drive island growth
 - ▣ Without these gradients, there can be no bootstrap current within the island
 - ▣ Bootstrap current at the X-point can drive island growth
- Large islands allow hot, dense plasma near core to be transported outward, reducing confinement
- Modifications to magnetic topology can result in macroscopic instability and disruption



Images taken from [The Theory of Toroidally Confined Plasmas](#) by R. White, 2006

NTM stability modeling

5

- NTM stability place a severe limit on maximum β
- NTMs incorporate a lot of physics
 - ▣ Cause: Neoclassical kinetic theory
 - ▣ Effect: MHD destabilization
 - ▣ Requires a hybrid model
- High-fidelity simulations required for prediction, control, avoidance, and understanding of NTMs
 - ▣ Especially important for ITER operation, where very few disruptions can be tolerated

Framework for hybrid solver

6

What's needed

Solve the drift kinetic equation in a **general, 3D**, toroidal geometry for the **ion and electron** perturbed distribution functions in parameter regimes **relevant to ITER and reactors** and **couple to an MHD solver**

Current work

Solve the drift kinetic equation in a **2D, large aspect ratio tokamak** for the **neoclassical, electron** perturbed distribution function

Outline

7

- Introduction and Motivation
- **Analytic Model¹**
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- Initial Results
- Conclusion

¹ Ramos, J.J. 2010. Phys. Plasmas. 17, 082502.

Electron DKE

8

$$\frac{\partial \bar{f}_e}{\partial t} + \dot{\mathbf{x}} \cdot \frac{\partial \bar{f}_e}{\partial \mathbf{x}} + \dot{v}_{\parallel} \frac{\partial \bar{f}_e}{\partial v_{\parallel}} + \dot{v}_{\perp} \frac{\partial \bar{f}_e}{\partial v_{\perp}} = \langle C_{ee}[f_e, f_e] + C_{ei}[f_e, f_i] \rangle$$

- Derived from average of Fokker-Planck equation over gyromotion
 - ▣ Determines form of $\dot{\mathbf{x}}$, \dot{v}_{\parallel} , and \dot{v}_{\perp}
 - ▣ Collision operators taken in their linearized Landau form
- Two expansion parameters for high-temperature fusion plasmas

$$\delta \sim \rho_i/L \ll 1$$

$$\nu_* \sim L/\lambda_{\text{mfp}} \sim \delta$$

- Four common subsidiary parameters

$$m_e/m_i \sim \delta^2$$

$$\delta_e \sim \rho_e/L \sim \delta^2$$

$$u_e/v_{the} \sim \delta^2$$

$$f_{NMe}/f_{Me} \sim \delta^2$$

- Equations maintained to third order in δ
 - ▣ Scale at which collisional dynamics first become important
 - ▣ Terms of order $\delta_e \nu_*$ will be kept, but δ_e^2 dropped
 - ▣ Equivalent to neoclassical electron banana regime

Stationary, Axisymmetric Equilibrium

9

□ Nested flux surfaces labeled by $\psi = \psi_{PF}/2\pi$

□ Fields: $\mathbf{B} = \nabla\psi \times \nabla\zeta + RB_\zeta \nabla\zeta$

$$\mathbf{E} = -\nabla\phi - \frac{V_{loop}}{2\pi} \nabla\zeta$$

□ Lowest-order fluid equations result in

$$n = n(\psi) \quad T_s = T_s(\psi) \quad \phi = \phi(\psi)$$

$$RB_\zeta = I(\psi) \quad \mathbf{u}_s = U_s(\psi)\mathbf{B} + R^2 \left[\frac{d\phi}{d\psi} + \frac{1}{e_s n} \frac{dP_s}{d\psi} \right] \nabla\zeta$$

Resulting DKE

10

- Given these assumptions, it is convenient to write

$$\bar{f}_e = f_{Me} + (g_{e,0} + g_{e,1} \cos \chi) f_{Me} + h_e$$

where $g_{e,0}$ and $g_{e,1}$ have analytic forms

- Then, the DKE for h_e can be reduced to

$$v_{\parallel} (\mathbf{b} \cdot \nabla \theta) \frac{\partial h_e}{\partial \theta} - C_e[h_e] = S_e v_{\parallel}$$

where $v_{\parallel}(\psi, \theta, v, \lambda) = \pm v [1 - \lambda B(\psi, \theta) / B_{max}(\psi)]^{1/2}$

$$\lambda(\psi, \theta, \chi) = \sin^2 \chi B_{max}(\psi) / B(\psi, \theta)$$

Source Term

11

Source contains Ohmic drive, interaction with ion flow, and pressure and temperature gradient bootstrap drive

$$S_e = \left\{ \frac{eV_{loop}I}{2\pi T_e B R^2} + \nu_e \left(U_i B + \frac{I}{enB} \frac{dP}{d\psi} \right) \frac{v_{the}}{v_{thi}^2 v} \xi \left(\frac{v}{v_{thi}} \right) \right. \\ \left. + \frac{\nu_e m_e I}{e B T_e} \frac{dT_e}{d\psi} \frac{v_{the}}{v} \left[2\varphi \left(\frac{v}{v_{the}} \right) - 10\xi \left(\frac{v}{v_{the}} \right) \right. \right. \\ \left. \left. + \frac{1}{2} \varphi \left(\frac{v}{v_{thi}} \right) - \frac{5v_{the}^2}{2v_{thi}^2} \xi \left(\frac{v}{v_{thi}} \right) \right] \right\} f_{Me}$$

Solubility Condition

12

- Standard solution method for neoclassical theory

$$h_e = \underbrace{\zeta(v_{\parallel})H(1 - \lambda)K_e(\psi, v, \lambda)}_{h^{odd}} + h_e^{(3)}$$

- DKE becomes $v_{\parallel}(\mathbf{b} \cdot \nabla\theta) \frac{\partial h_e^{(3)}}{\partial \theta} - C_e[h^{odd}] = S_e v_{\parallel}$

- Solubility condition:
$$\oint_{\psi, v, \lambda} \frac{dl}{v_{\parallel}} C_e[h^{odd}] = - \oint_{\psi, v, \lambda} dl S_e$$

- Contour integrals taken along one poloidal turn of magnetic field line

Integral over Collision Operator

13

$$\begin{aligned}
 \oint_{\psi, v, \lambda} \frac{dl}{v_{\parallel}} C_e[h^{odd}] = & \frac{2\nu_D}{v} \frac{\partial}{\partial \lambda} \left(\eta_1 \lambda \frac{\partial}{\partial \lambda} K_e \right) \\
 & + \nu_e \eta_2 v_{the}^3 \left[\frac{1}{v^3} \frac{d}{dv} \left\{ \begin{aligned} & \xi \left(\frac{v}{v_{the}} \right) \left[v \frac{d}{dv} + \frac{v^2}{v_{the}^2} \right] \\ & + \xi \left(\frac{v}{v_{thi}} \right) \left[v \frac{d}{dv} + \frac{m_e v^2}{m_i v_{thi}^2} \right] \end{aligned} \right\} + \frac{4\pi f_{Me}}{nv} \right] K_e \\
 & - \frac{\nu_e v_{the}}{nv} f_{Me} \int_0^{2\pi} JB \left[1 - \lambda \frac{B}{B_{max}} \right]^{-\frac{1}{2}} \Phi d\theta \\
 & + \frac{\nu_e v}{nv_{the}} f_{Me} \frac{d^2}{dv^2} \int_0^{2\pi} JB \left[1 - \lambda \frac{B}{B_{max}} \right]^{-\frac{1}{2}} \Psi d\theta
 \end{aligned}$$

where

$$\eta_1(\psi, \lambda) = B_{max} \int_0^{2\pi} J \left[1 - \lambda \frac{B}{B_{max}} \right]^{\frac{1}{2}} d\theta$$

$$\eta_2(\psi, \lambda) = \int_0^{2\pi} JB \left[1 - \lambda \frac{B}{B_{max}} \right]^{-\frac{1}{2}} d\theta$$

Outline

14

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- Initial Results
- Conclusion

Expansions

15

- Expand Rosenbluth Potentials in Legendre and Fourier series

$$\begin{pmatrix} \Phi(\psi, \cos \chi, \theta, v) \\ \Psi(\psi, \cos \chi, \theta, v) \end{pmatrix} = \sum_{m=0}^M \sum_{l=1, \text{odd}}^{2L-1} \begin{pmatrix} \Phi_{l,m}(\psi, v) \\ \Psi_{l,m}(\psi, v) \end{pmatrix} P_l(\cos \chi) \cos m\theta$$

- Then expand K_e , $\Phi_{l,m}$, and $\Psi_{l,m}$ in finite elements in v and λ , as necessary

$$K_e(\psi, v, \lambda) = \sum_{i=0}^N \sum_{j=0}^J K_{i,j}(\psi) \varphi_i(v) \varphi_j(\lambda)$$

$$\begin{pmatrix} \Phi_{l,m}(v) \\ \Psi_{l,m}(v) \end{pmatrix} = \sum_{i=0}^N \begin{pmatrix} \Phi_{i,l,m} \\ \Psi_{i,l,m} \end{pmatrix} \varphi_i(v)$$

Expanded Form

16

$$\begin{aligned}
 & \sum_{i=0}^N \sum_{j=0}^J \left\{ 2v^2 \nu_D \frac{d}{d\lambda} \left(\eta_1 \lambda \frac{d\varphi_j(\lambda)}{d\lambda} \right) K_{i,j} \varphi_i(v) \right. \\
 & + \nu_e \eta_2 v_{the}^3 \left[\frac{d}{dv} \left\{ \begin{aligned} & \xi \left(\frac{v}{v_{the}} \right) \left[v \frac{d\varphi_i(v)}{dv} + \frac{v^2}{v_{the}^2} \varphi_i(v) \right] \\ & + \xi \left(\frac{v}{v_{thi}} \right) \left[v \frac{d\varphi_i(v)}{dv} + \frac{m_e v^2}{m_i v_{thi}^2} \varphi_i(v) \right] \end{aligned} \right\} + \frac{4\pi v^2}{n} f_{Me} \varphi_i(v) \right] K_{i,j} \varphi_j(\lambda) \\
 & - \frac{\nu_e v_{the} v^2}{n} f_{Me} \sum_{m=0}^M \sum_{l=1, \text{odd}}^{2L-1} a_{l,m} \Phi_{i,l,m} \phi_i(v) \\
 & \left. - \frac{\nu_e v^4}{n v_{the}} f_{Me} \sum_{m=0}^M \sum_{l=1, \text{odd}}^{2L-1} a_{l,m} \Psi_{i,l,m} \frac{d^2 \phi_i(v)}{dv^2} \right\} = -v^3 \oint_{\psi, v, \lambda} dl S_e
 \end{aligned}$$

$$\left[\frac{d}{dv} \left(v^2 \frac{d\varphi_i(v)}{dv} \right) - l(l+1) \varphi_i(v) \right] \begin{pmatrix} \Phi_{i,l,m} \\ \Psi_{i,l,m} \end{pmatrix} = \begin{pmatrix} v^2 \varphi_i(v) \sum_{j=0}^J D_{j,l,m} K_{i,j} \\ v^2 \Phi_{i,l,m} \varphi_i(v) \end{pmatrix}$$

$$a_{l,m} = \int_0^{2\pi} d\theta J B \left[1 - \lambda \frac{B}{B_{max}} \right]^{-1/2} P_l \left(\left[1 - \lambda \frac{B}{B_{max}} \right]^{1/2} \right) \cos m\theta$$

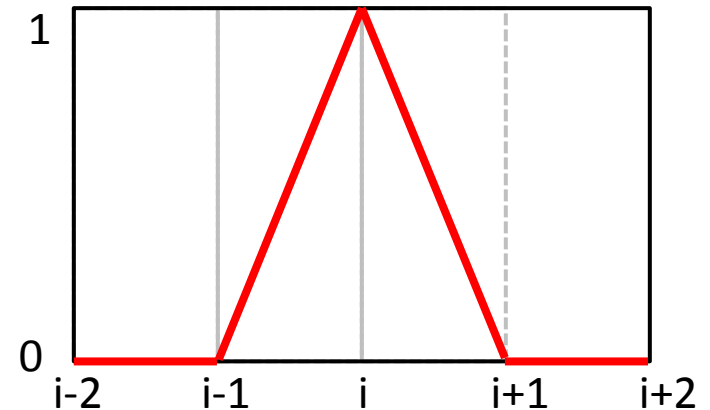
$$D_{j,l,m} = -\frac{2(2l+1)}{1 + \delta_{m,0}} \int_0^{2\pi} d\theta \cos m\theta \int_0^1 d\lambda P_l \left(\left[1 - \lambda \frac{B}{B_{max}} \right]^{1/2} \right) \varphi_j(\lambda) \frac{B}{B_{max}} \left[1 - \lambda \frac{B}{B_{max}} \right]^{-1/2}$$

Galerkin Method

17

- Take the inner product of the previous equations with each finite element
- Use linear tent functions:
- Only overlap with their two nearest neighbors and themselves
- DKE becomes tridiagonal in both v and λ
- Rosenbluth Potential eqs. are tridiagonal in v and dense in λ

$$\varphi_p(x) = \begin{cases} \frac{x-x_{i-1}}{x_i-x_{i-1}} & : x_{i-1} \leq x \leq x_i \\ \frac{x_{i+1}-x}{x_{i+1}-x_i} & : x_i \leq x \leq x_{i+1} \end{cases}$$



Block Tridiagonal Algorithm

18

- Since all equations are tridiagonal in \mathbf{v} , we rewrite the coupled set as a block tridiagonal matrix eq.

$$\mathbf{A}_i \cdot \mathbf{U}_{i+1} - \mathbf{B}_i \cdot \mathbf{U}_i + \mathbf{C}_i \cdot \mathbf{U}_{i-1} = \mathbf{D}_i$$

- Size of each block matrix is $(J + 2L(M + 1))^2$
- Given appropriate boundary conditions, there exists a straightforward algorithm to solve for \mathbf{U}
- Computation time required is $O(N (J + 2L(M + 1))^3)$

Boundary Conditions

19

□ For v

$$\square K_e(0, \lambda) = 0 \quad K_e(" \infty " = v_{max}, \lambda) = 0$$

$$\square \Phi_{l,m}(0) = 0 \quad \frac{d\Phi_{l,m}}{dv}(v_{max}) = -(l+1) \frac{\Phi_{l,m}(v_{max})}{v_{max}}$$

$$\square \Psi_{l,m}(0) = 0 \quad \frac{d\Psi_{l,m}}{dv}(v_{max}) = -(l-1) \frac{\Psi_{l,m}(v_{max})}{v_{max}}$$

□ For λ

□ $K_e(v, 0)$ must be regular

$$\square K_e(v, 1) = 0$$

□ $\frac{\partial K_e}{\partial \lambda}(v, 1) = 0$ requires boundary layer (future work)

Outline

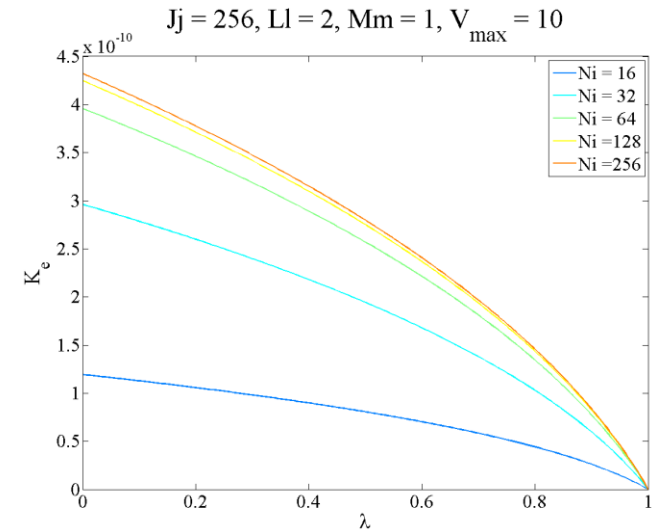
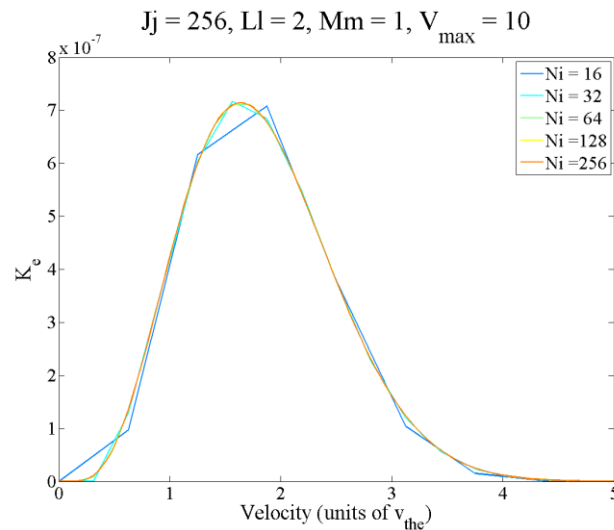
20

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ **Convergence Studies**
- Initial Results
- Conclusion

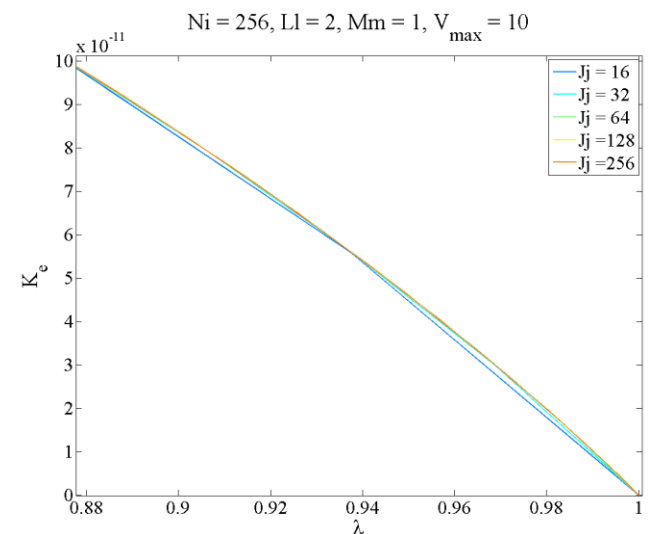
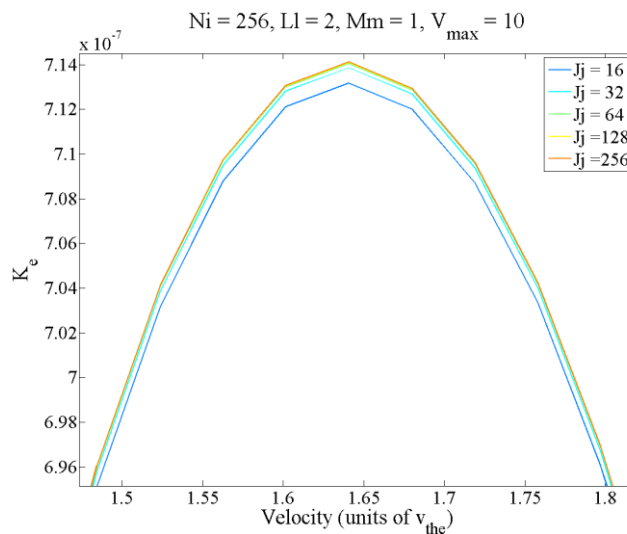
Convergence (1)

21

Velocity
Finite
Elements



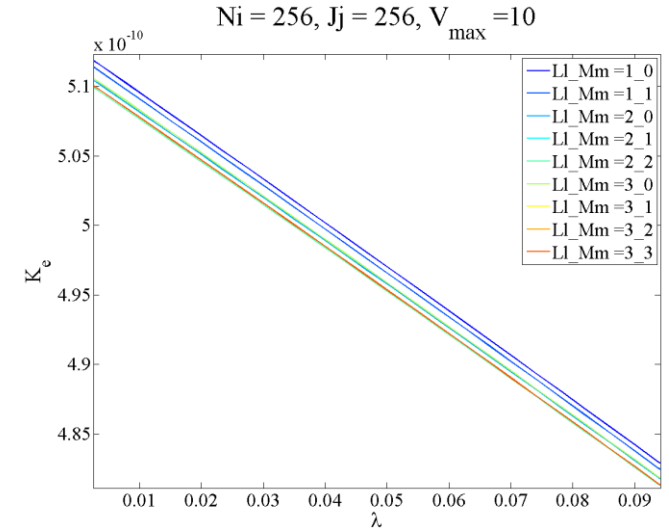
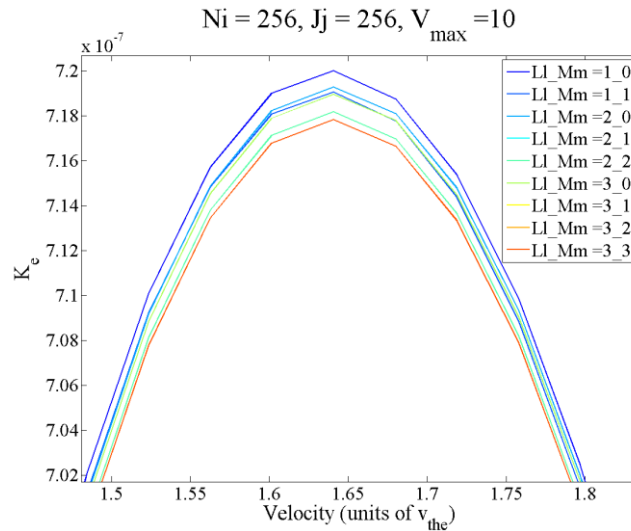
Lambda
Finite
Elements



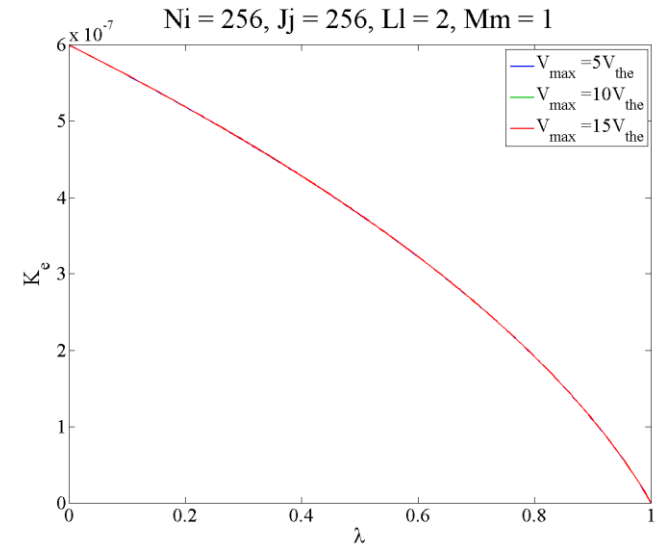
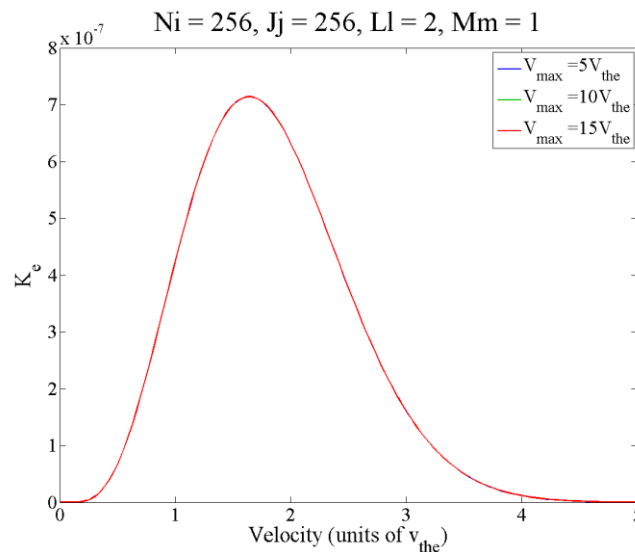
Convergence (2)

22

Legendre
& Fourier
Terms



Maximum
Velocity



Outline

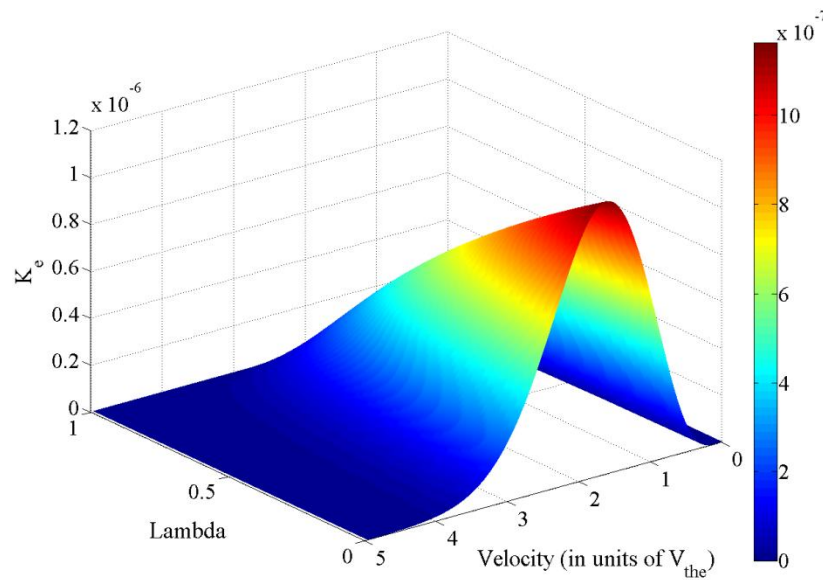
23

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- **Initial Results**
- Conclusion

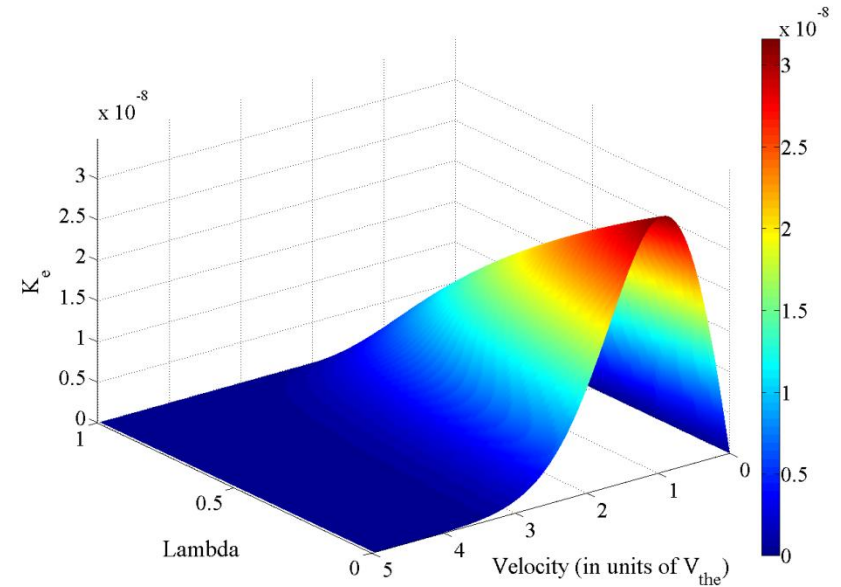
Example Distribution Functions

24

Ohmic Drive



Density-Gradient Drive



Calculating Current

25

- Need part of distribution function that is odd wrt v_{\parallel}

$$\bar{f}_{NM_e}^{odd} = \varsigma(v_{\parallel})H(1 - \lambda)K_e - v_{\parallel} \left[\frac{m_e U_e B}{T_e} + \frac{m_e I}{2eBT_e} \left(\frac{m_e v^2}{T_e} - 5 \right) \frac{dT_e}{d\psi} \right] f_{M_e}$$

- Requiring $\int d^3\mathbf{v} v_{\parallel} \bar{f}_{NM_e}^{odd} = 0$, we find that

$$U_e(\psi) = \frac{2\pi}{nB_{max}} \int_0^{\infty} dv v^3 \int_0^1 d\lambda K_e(\psi, v, \lambda)$$

- Then we use $j_{\parallel} = (U_i - U_e)B + \frac{I}{B} \frac{dP}{d\psi}$

Ohmic Drive Conductivity

26

- On-axis: $\sigma_{\parallel} = \sigma_{Spitzer} \approx 1.96\sigma_{\perp}$

$$\sigma_{\perp} = \frac{e^2 n}{m_e \nu_{Brag}}$$

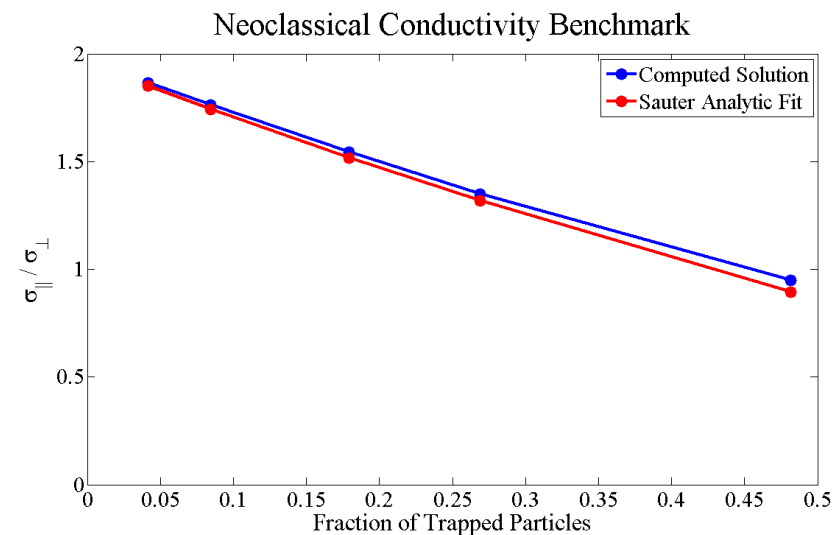
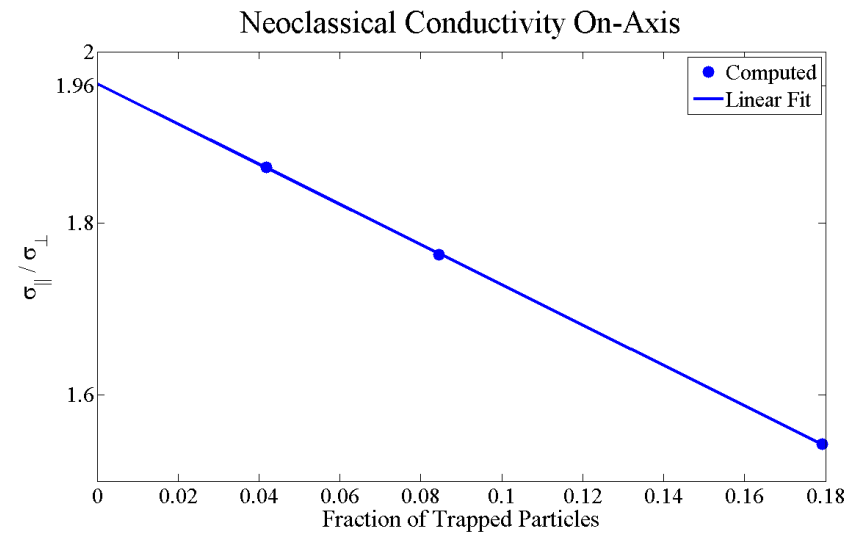
- Trapped particles carry no current
 - ▣ To lowest order, expect conductivity to decrease linearly with the trapped particle fraction

$$f_t = 1 - \frac{3}{4} \left\langle \frac{B^2}{B_{max}^2} \right\rangle \int_0^1 \frac{\lambda d\lambda}{\left\langle \sqrt{1 - \lambda B/B_{max}} \right\rangle}$$

- Sauter analytic fit¹

$$\frac{\sigma_{neo}}{\sigma_{\perp}} \approx 1.96 (1 - 1.36 f_t + 0.59 f_t^2 - 0.23 f_t^3)$$

¹ Sauter, O et al. (1999) Phys. Plasmas: 6,7.



Density-Gradient Bootstrap Current

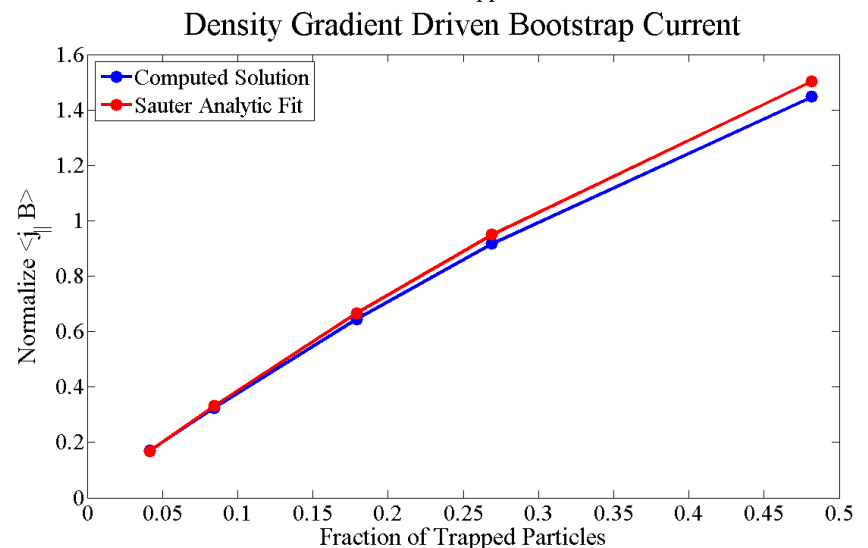
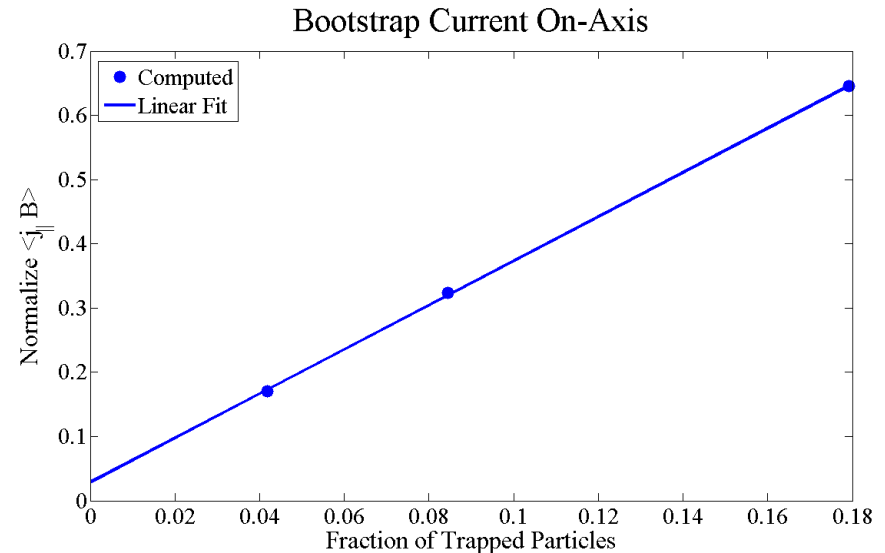
27

- Expect zero current for $f_t = 0$
 - To lowest order, current should decrease linearly with trapped particle fraction

- Sauter Analytic fit

$$\langle j_{\parallel} B \rangle = -I \mathcal{L}_{31} \frac{dP}{d\psi}$$

$$\mathcal{L}_{31} = 1.7f_t - 0.95f_t^2 + 0.15f_t^3 + 0.1f_t^4$$



Outline

28

- Introduction and Motivation
- Analytic Model
- Computational Methods
 - ▣ Expansions and Algorithm
 - ▣ Convergence Studies
- Initial Results
- Conclusion

Summary

- A code has been written to solve for the component of the non-Maxwellian electron distribution function necessary to compute the current in an axisymmetric toroidal plasma
- Code demonstrates good convergence
- Ohmic and density-gradient sources have been benchmarked against the Sauter analytic fits for a large-aspect ratio expansion equilibrium

Future Work

30

□ Short Term

- Complete implementation of temperature-gradient driven source
- Generalize geometry to use solution from Grad-Shafranov solver
- Benchmark against NEO and NCLASS
- Implement simple (i.e., lowest-order) ion code
- Couple with MHD code (e.g., M3D-C1)

□ Long Term

- Generalize to 3D Geometry
- Develop ion theory to appropriate ordering
- Implement fully 3D, coupled ion-electron code
- Couple with MHD code (e.g., M3D-C1)
- Perform NTM and sawtooth studies

Acknowledgements

- This research was supported in part by an award from the Department of Energy (DOE) Office of Science Graduate Fellowship Program (DOE SCGF). The DOE SCGF Program was made possible in part by the American Recovery and Reinvestment Act of 2009. The DOE SCGF program is administered by the Oak Ridge Institute for Science and Education for the DOE. ORISE is managed by Oak Ridge Associated Universities (ORAU) under DOE contract number DE-AC05-06OR23100. All opinions expressed in this paper are the author's and do not necessarily reflect the policies and views of DOE, ORAU, or ORISE.
- This presentation has been authored by Princeton University and collaborators under Contract Number DE-AC02-09CH11466 with the U.S. Department of Energy.

32

Additional Slides

Coefficient functions

33

- Reference frame of the macroscopic flow

$$\dot{\mathbf{x}} = \mathbf{u}_e - \mathbf{u}_{De} + v_{\parallel} \mathbf{b} + \frac{v_{\perp}^2}{2} \nabla \times \left(\frac{\mathbf{b}}{\Omega_{ce}} \right) + \left(v_{\parallel}^2 - \frac{v_{\perp}^2}{2} \right) \frac{\mathbf{b} \times \boldsymbol{\kappa}}{\Omega_{ce}}$$

$$\dot{v}_{\parallel} = \frac{\mathbf{b} \cdot (\nabla \cdot P_e^{CGL} - \mathbf{F}_e^{coll})}{m_e n} - v_{\parallel} \mathbf{b} \cdot [(\mathbf{b} \cdot \nabla)(\mathbf{u}_e - \mathbf{u}_{De})] - \frac{v_{\perp}^2}{2} \mathbf{b} \cdot \nabla \ln B + \frac{v_{\parallel} v_{\perp}^2}{2} \nabla \cdot \left(\frac{\mathbf{b} \times \boldsymbol{\kappa}}{\Omega_{ce}} \right)$$

$$\dot{v}_{\perp} = \frac{v_{\perp}}{2} \left\{ \mathbf{b} \cdot [(\mathbf{b} \cdot \nabla)(\mathbf{u}_e - \mathbf{u}_{De})] - \nabla \cdot (\mathbf{u}_e - \mathbf{u}_{De}) + v_{\parallel} \mathbf{b} \cdot \nabla \ln B - v_{\parallel}^2 \nabla \cdot \left(\frac{\mathbf{b} \times \boldsymbol{\kappa}}{\Omega_{ce}} \right) \right\}$$

where $\mathbf{u}_{De} = \frac{1}{m_e n \Omega_{ce}} [\mathbf{b} \cdot \nabla p_{e\perp} + (p_{e\parallel} - p_{e\perp})(\mathbf{b} \times \boldsymbol{\kappa})]$

$$\mathbf{b} \cdot (\nabla \cdot P_e^{CGL}) = \mathbf{b} \cdot \nabla p_{e\parallel} - (p_{e\parallel} - p_{e\perp}) \mathbf{b} \cdot \nabla \ln B$$

$$\boldsymbol{\kappa} = (\mathbf{b} \cdot \nabla) \mathbf{b}$$

Electron –Electron Collision Operator

34

$$C_{ee}[f_e, f_e] = C_{ee}[f_{Me}, f_{NMe}] + C_{ee}[f_{NMe}, f_{Me}]$$

$$C_{ee}[f_{Me}, f_{NMe}] = \frac{\nu_e v_{the}}{n} f_{Me}(v) \left\{ 4\pi v_{the}^2 f_{NMe}(\mathbf{v}) - \Phi[f_{NMe}](\mathbf{v}) + \frac{\mathbf{v}\mathbf{v}}{v_{the}^2} : \frac{\partial^2 \Psi[f_{NMe}](\mathbf{v})}{\partial \mathbf{v} \partial \mathbf{v}} \right\}$$

$$C_{ee}[f_{NMe}, f_{Me}] = \frac{\nu_e v_{the}^3}{v^3} \left\{ \left[\varphi \left(\frac{v}{v_{the}} \right) - \xi \left(\frac{v}{v_{the}} \right) \right] \mathcal{L}[f_{NMe}](\mathbf{v}) \right. \\ \left. + \mathbf{v} \cdot \frac{\partial}{\partial \mathbf{v}} \left[\xi \left(\frac{v}{v_{the}} \right) \mathbf{v} \cdot \frac{\partial f_{NMe}(\mathbf{v})}{\partial \mathbf{v}} + \frac{v^2}{v_{the}^2} \xi \left(\frac{v}{v_{the}} \right) f_{NMe}(\mathbf{v}) \right] \right\}$$

where $\mathcal{L}[f](\mathbf{v}) = \frac{v^3}{2} \frac{\partial}{\partial \mathbf{v}} \cdot \left\{ \frac{1}{v} \frac{\partial f(\mathbf{v})}{\partial \mathbf{v}} - \frac{1}{v^3} \left[\mathbf{v} \cdot \frac{\partial f(\mathbf{v})}{\partial \mathbf{v}} \right] \mathbf{v} \right\}$ $\frac{\partial}{\partial \mathbf{v}} \cdot \frac{\partial \Phi[f](\mathbf{v})}{\partial \mathbf{v}} = -4\pi f(\mathbf{v})$

$$\varphi \left(\frac{v}{v_{the}} \right) = \frac{v}{n} \Phi[f_{Me}](v) = \sqrt{\frac{2}{\pi}} \int_0^{v/v_{the}} dt \exp(-t^2/2)$$
 $\frac{\partial}{\partial \mathbf{v}} \cdot \frac{\partial \Psi[f](\mathbf{v})}{\partial \mathbf{v}} = \Phi[f](\mathbf{v})$

$$\xi \left(\frac{v}{v_{the}} \right) = \frac{1}{nv} \mathbf{v}\mathbf{v} : \frac{\partial^2 \Psi[f_{Me}](v)}{\partial \mathbf{v} \partial \mathbf{v}} = \frac{v_{the}^2}{v^2} \left[\varphi \left(\frac{v}{v_{the}} \right) - \sqrt{\frac{2}{\pi}} \frac{v}{v_{the}} \exp \left(-\frac{v^2}{2v_{the}^2} \right) \right]$$
 $\nu_e = 3 \sqrt{\frac{\pi}{2}} \nu_{Braginskii}$

Electron-Ion Collision Operator

35

$$C_{ei}[f_e, f_i] = C_{ei}[f_{Mi}, f_{NMe}] + C_{ei}[f_i, f_{Me}]$$

$$C_{ei}[f_{NMe}, f_{Mi}] = \frac{\nu_e v_{the}^3}{v^3} \left\{ \left[\varphi \left(\frac{v}{v_{thi}} \right) - \xi \left(\frac{v}{v_{thi}} \right) \right] \mathcal{L}[f_{NMe}](\mathbf{v}) \right. \\ \left. + \mathbf{v} \cdot \frac{\partial}{\partial \mathbf{v}} \left[\xi \left(\frac{v}{v_{thi}} \right) \mathbf{v} \cdot \frac{\partial f_{NMe}(\mathbf{v})}{\partial \mathbf{v}} + \frac{m_e v^2}{m_i v_{thi}^2} \xi \left(\frac{v}{v_{thi}} \right) f_{NMe}(\mathbf{v}) \right] \right\}$$

$$C_{ei}[f_{Me}, f_i] = \nu_e v_{the} f_{Me}(v) \left[\left(\frac{T_e}{T_i} - 1 \right) \frac{4\pi v_{thi}^2}{n} f_{Mi}(v) \right. \\ \left. + \frac{\mathbf{v} \cdot (\mathbf{u}_i - \mathbf{u}_e)}{v_{thi}^2 v} \xi \left(\frac{v}{v_{thi}} \right) + \frac{m_e}{m_i} \left(\frac{T_e}{T_i} - 1 \right) \frac{v}{v_{thi}^2} \xi \left(\frac{v}{v_{thi}} \right) \right]$$

Gyro-average of the collision operators

36

- Maxwellian-test part of C_{ei} has analytic solution

$$\langle C_{ei}[f_{Me}, f_i] \rangle (v, \chi) = \mathcal{D}_{e,0}(v) + \mathcal{D}_{e,1}(v) \cos \chi$$

where
$$\mathcal{D}_{e,0}(v) = \nu_e v_{the} f_{Me} \left(\frac{T_e}{T_i} - 1 \right) \left[\frac{4\pi v_{thi}^2}{n} f_{Mi} - \frac{v}{v_{the}^2} \xi \left(\frac{v}{v_{thi}} \right) \right]$$

$$\mathcal{D}_{e,1}(v) = \nu_e f_{Me} \frac{v_{the} j_{\parallel}}{v_{thi}^2 e n} \xi \left(\frac{v}{v_{thi}} \right)$$

- And the remainder is simple

$$\langle C_{ee}[f_{Me}, f_{NMe}] + C_{ee}[f_{NMe}, f_{Me}] + C_{ei}[f_{NMe}, f_{Mi}] \rangle = C_e[\bar{f}_{NMe}](v, \chi)$$

Or
$$\langle C_e[f] \rangle = C_e[\bar{f}]$$