

Extended MHD Benchmarking and Validation

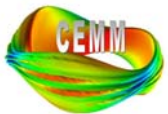
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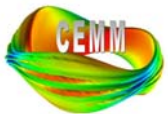


Important Target Problems

- Non-linear ELM evolution
- Neo-classical tearing modes/island dynamics
- Giant sawteeth
- RF/MHD coupling
- Plasma relaxation: characteristic fields and flows

All are extremely complicated and require “extended MHD”

How do we know we’re getting the “right” answer?

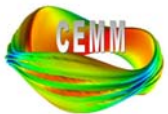


Extensions to Resistive MHD

- Anisotropic heat flux
- 2-fluid Ohm's law
- Anisotropic parallel viscosity
- Ion gyro-viscosity*
- Neo-classical stress tensor for ions* and electrons*
- Energetic ion species

**There is no general agreement on the form of several of these terms*

How do we know we're getting the "right" answer?



Algorithms are Complicated

$$m_i n^{j+1/2} \left(\frac{\Delta \mathbf{V}}{\Delta t} + \underbrace{\frac{1}{2} \mathbf{V}^j \cdot \nabla \Delta \mathbf{V} + \frac{1}{2} \Delta \mathbf{V} \cdot \nabla \mathbf{V}^j}_{\text{Implicit advection}} \right) - \underbrace{\frac{\Delta t L^{j+1/2}(\Delta \mathbf{V})}{SI \text{ MHD}}}_{SI \text{ MHD}} + \underbrace{\nabla \cdot \Pi_i(\Delta \mathbf{V})}_{\text{Includes ALL stresses}} =$$

$$\mathbf{J}^{j+1/2} \times \mathbf{B}^{j+1/2} - m_i n^{j+1/2} \mathbf{V}^j \cdot \nabla \mathbf{V}^j - \nabla p^{j+1/2} - \nabla \cdot \Pi_i(\mathbf{V}^j)$$

Momentum

$$\frac{\Delta n}{\Delta t} + \frac{1}{2} \mathbf{V}^{j+1} \cdot \nabla \Delta n = -\nabla \cdot (\mathbf{V}^{j+1} \cdot n^{j+1/2})$$

Continuity

$$\frac{3n}{2} \left(\frac{\Delta T_\alpha}{\Delta t} + \frac{1}{2} \mathbf{V}_\alpha^{j+1} \cdot \nabla \Delta T_\alpha \right) + \frac{1}{2} \underbrace{\nabla \cdot \mathbf{q}_\alpha(\Delta T_\alpha)}_{\text{Anisotropic thermal conduction}} =$$

$$-\frac{3n}{2} \mathbf{V}_\alpha^{j+1} \cdot \nabla T_\alpha^{j+1/2} - n T_\alpha^{j+1/2} \nabla \cdot \mathbf{V}_\alpha^{j+1} - \nabla \cdot \mathbf{q}_\alpha(T_\alpha^{j+1/2}) + Q_\alpha^{j+1/2}$$

Energy

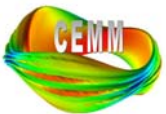
$$\frac{\Delta \mathbf{B}}{\Delta t} + \frac{1}{2} \mathbf{V}^{j+1} \cdot \nabla \Delta \mathbf{B} + \frac{1}{2} \nabla \times \frac{1}{ne} \left(\mathbf{J}^{j+1/2} \times \Delta \mathbf{B} + \Delta \mathbf{J} \times \mathbf{B}^{j+1/2} \right) + \frac{1}{2} \nabla \times \eta \Delta \mathbf{J} =$$

Implicit HALL term *Implicit resistive term*

$$-\nabla \times \left[\frac{1}{ne} \left(\mathbf{J}^{j+1/2} \times \mathbf{B}^{j+1/2} - \nabla p_e \right) - \mathbf{V}^{j+1} \times \mathbf{B}^{j+1/2} + \eta \mathbf{J}^{j+1/2} \right]$$

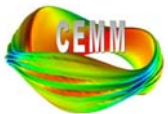
Maxwell/Ohm

How do we know we're getting the "right" answer?



Need Simple Problems with Known Solutions

- Simple geometry, but capture essential physics
- Analytic solution preferred, but independent numerical results useful
- Start simple => add complications
- Linear is good, non-linear better (but attainable?)
- *Need help from theory*

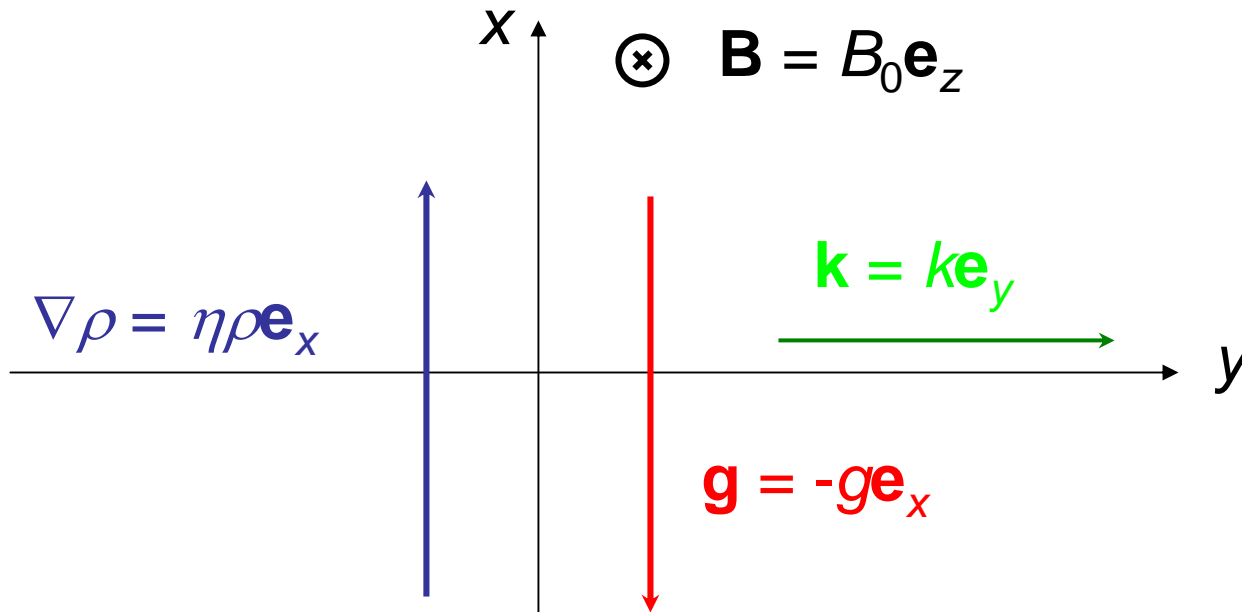


Extended MHD Validation Problems

<ul style="list-style-type: none"> • g-mode interchange in a slab (Rayleigh-Taylor-Parker-Roberts-Taylor) 	<ul style="list-style-type: none"> • MHD • 2-fluid stabilization • Gyro-viscous stabilization
<ul style="list-style-type: none"> • Collisional drift waves in a slab (Coppi, et al.) 	<ul style="list-style-type: none"> • 2-fluid terms (Hall) • Collisional effects • Stability thresholds
<ul style="list-style-type: none"> • GEM reconnection problem (slab) 	<ul style="list-style-type: none"> • 2-fluid reconnection • Comparison with MHD • Well documented numerical results • Non-linear
<ul style="list-style-type: none"> • Critical island width for temperature flattening (Fitzpatrick) 	<ul style="list-style-type: none"> • Anisotropic thermal conduction
<ul style="list-style-type: none"> • Destabilization of neo-classical tearing mode (Gianakon, Kruger, Hegna) 	<ul style="list-style-type: none"> • Models for neo-classical closures • Linear
<ul style="list-style-type: none"> • Kink stabilization by energetic particles (Cheng, Fu, Kim) 	<ul style="list-style-type: none"> • Energetic particle ion closures schemes • Linear • Numerical results



Example: g-mode Stability (Roberts and Taylor, 1963)



$$\left. \begin{aligned}
 \frac{d}{dx} \left(p_0 + \frac{B_0^2}{2\mu_0} \right) &= -\rho_0 g \\
 \frac{d\rho_0}{dx} &= \eta \rho_0, \quad \eta \equiv 1/L_n
 \end{aligned} \right\} \text{Only } p_T = p_0 + \frac{B_0^2}{2\mu_0} \text{ matters}$$



2-fluid/Gyro-viscous Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \mathbf{V} = 0$$

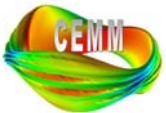
$$\rho \frac{d\mathbf{V}}{dt} = -\nabla \left(p + \frac{B^2}{2\mu_0} \right) + \rho \mathbf{g} - \nabla \cdot \Pi$$

$$\mathbf{E} = -\mathbf{V} \times \mathbf{B} + \frac{M}{\rho e} \left[\rho \frac{d\mathbf{V}}{dt} + \nabla p_i - \rho \mathbf{g} + \nabla \cdot \Pi \right]$$

$$\Pi_{xx} = -\Pi_{yy} = -\rho \nu \left(\frac{\partial \mathcal{V}_y}{\partial x} + \frac{\partial \mathcal{V}_x}{\partial y} \right)$$

$$\Pi_{xy} = \Pi_{yx} = \rho \nu \left(\frac{\partial \mathcal{V}_x}{\partial x} - \frac{\partial \mathcal{V}_y}{\partial y} \right)$$

$$\nu = \rho_i^2 \Omega / 2 \quad \rho_i^2 = V_{th}^2 / \Omega^2$$



Simplifying Assumptions

Only variations in $p_T = p + B^2 / 2\mu_0$ affect dynamics

⇒ Ignore perturbations to \mathbf{B}

⇒ $\nabla \times \mathbf{E} = 0$ (low β , electrostatic)

Assume ions are barotropic, $p_i = p_i(\rho)$

⇒ Simplifies Ohm's law

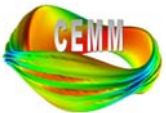
Variation in x much weaker than variation in y

⇒ $\eta^2 \ll k^2$

⇒ Can ignore explicit x -dependence of equilibrium

Assume $\exp(i\omega t +iky)$ dependence

⇒ Linearized equations are algebraic



Final g-mode Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \mathbf{V} = 0$$

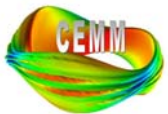
$$\rho \frac{d\mathbf{V}}{dt} = -\nabla p_T + \rho \mathbf{g} - \nabla \cdot \Pi$$

$$\nabla \cdot \mathbf{V} + \frac{1}{\Omega} \nabla \times \left[\frac{d\mathbf{V}}{dt} - \frac{1}{\rho^2} \nabla \rho \times \nabla \cdot \Pi \right] = 0$$

Plus definition of Π

4 equations in 4 unknowns: ρ , \mathbf{V} , p_T

Last equation serves as "equation of state", or closure



Stability Results

$$\omega^2 - \omega_* \omega + \gamma_{MHD}^2 = 0$$

$$\omega_* = \omega_{*2F} + \omega_{*GV}$$

$$\omega_{*2F} = \frac{gk}{\Omega}$$

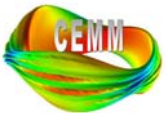
$$\omega_{*GV} = \frac{1}{2} \frac{\rho_i^2 k^2}{kL} \Omega$$

$$\gamma_{MHD}^2 = \frac{g}{L} + \frac{g^2}{V_A^2 + C_s^2}$$

Compressible Correction

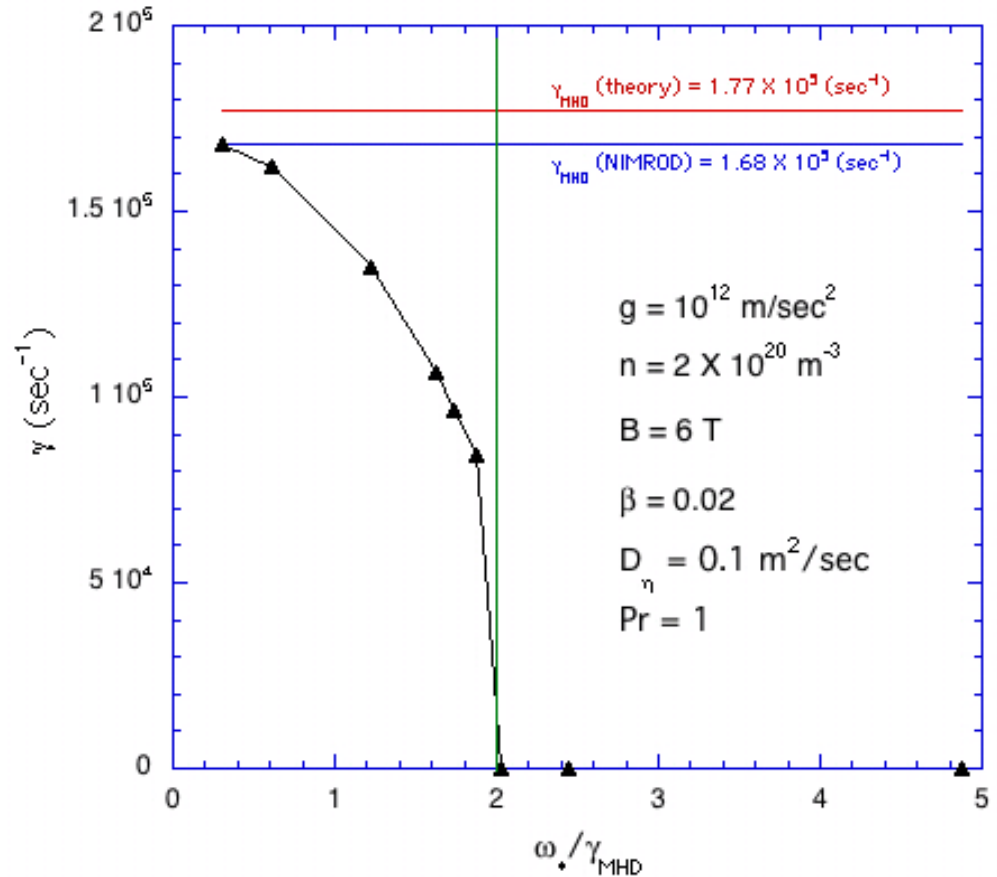
$$\omega = \frac{1}{2} \left(\omega_* \pm \sqrt{\omega_*^2 - 4\gamma_{MHD}^2} \right)$$

Stable if: $\omega_* > 2\gamma_{MHD}$



2-fluid g-mode in NIMROD

- Validation of NIMROD on g-mode problem
- 2-fluid only
- Fully compressible
- Walls placed far away
- Get good agreement with theory on both 2-fluid stability threshold and MHD growth rate
- Found heuristic time step CFL limit:
 $\omega_{*MAX} \Delta t < 1/4$
- Still working on GV validation



Problem can be “Extended”

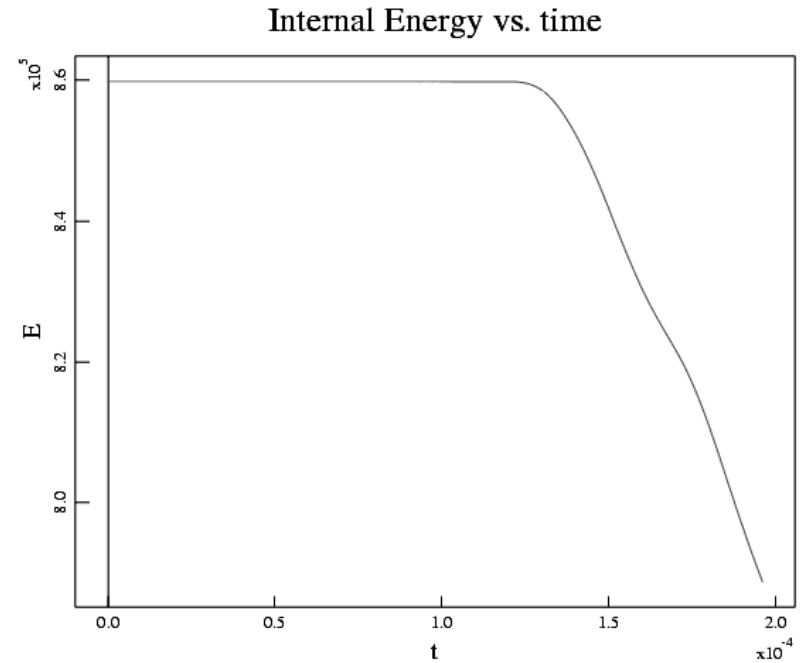
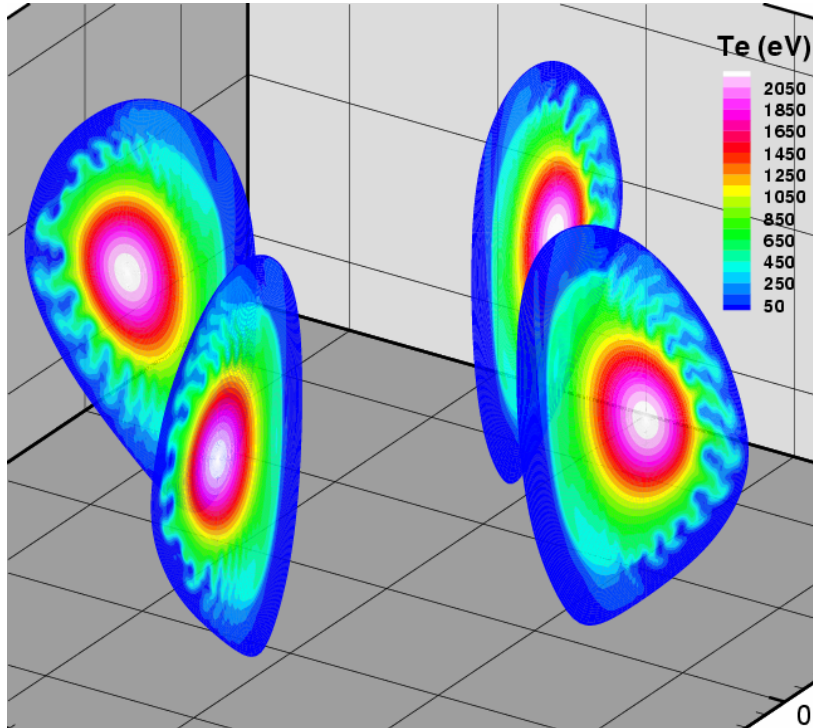
<ul style="list-style-type: none">• Add transverse component of magnetic field (B_y)	<ul style="list-style-type: none">• k_{\parallel} effects• Stabilization• Whistlers and KAWs
<ul style="list-style-type: none">• Add sheared transverse field ($B_y(x)$)	<ul style="list-style-type: none">• Mode localization
<ul style="list-style-type: none">• Move walls closer	<ul style="list-style-type: none">• Boundary conditions (not trivial for 2-fluid model)
<ul style="list-style-type: none">• Scaling with resistivity	<ul style="list-style-type: none">• 2-fluid effects on resistive g-modes

Need analytic solutions of these problems



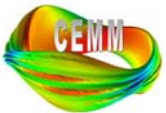
Nonlinear ELM Evolution

(Where we'd like accurate 2-fluid models)



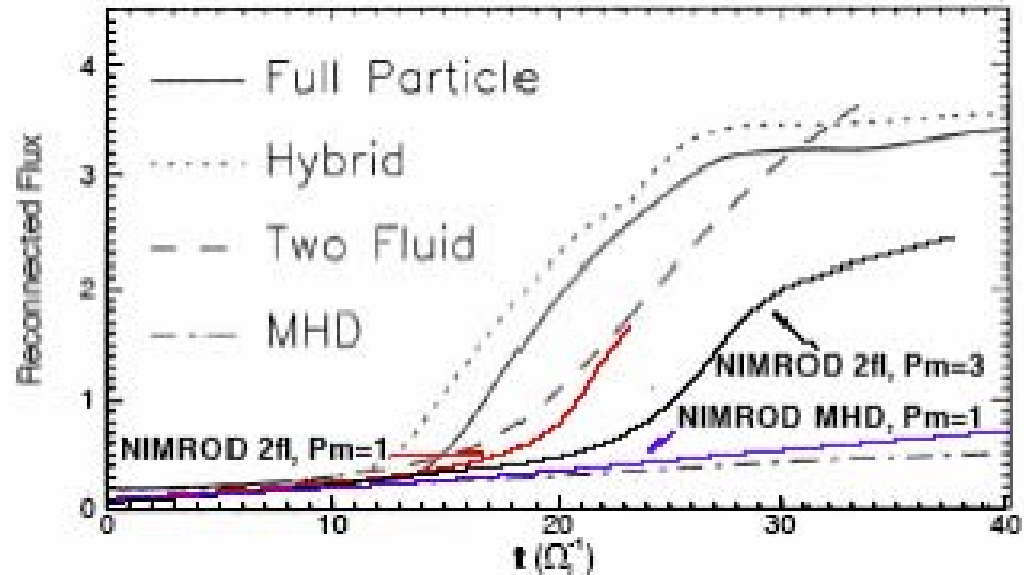
- Resistive MHD
- Anisotropic thermal conduction
- ELM interaction with wall

- 70 kJ lost in 60 μ sec

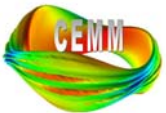


Two-fluid Reconnection

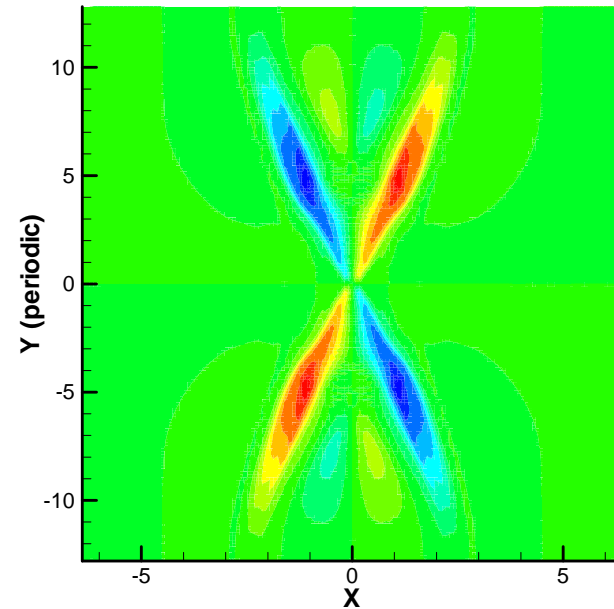
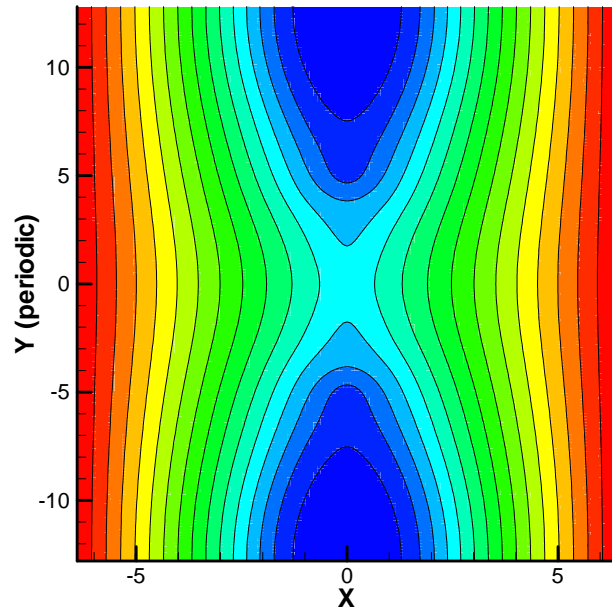
GEM Problem



- 2-D slab
- $\eta = 0.005$
- Good agreement with many other calculations
- Computed with same code used for tokamaks, spheromaks, RFPs



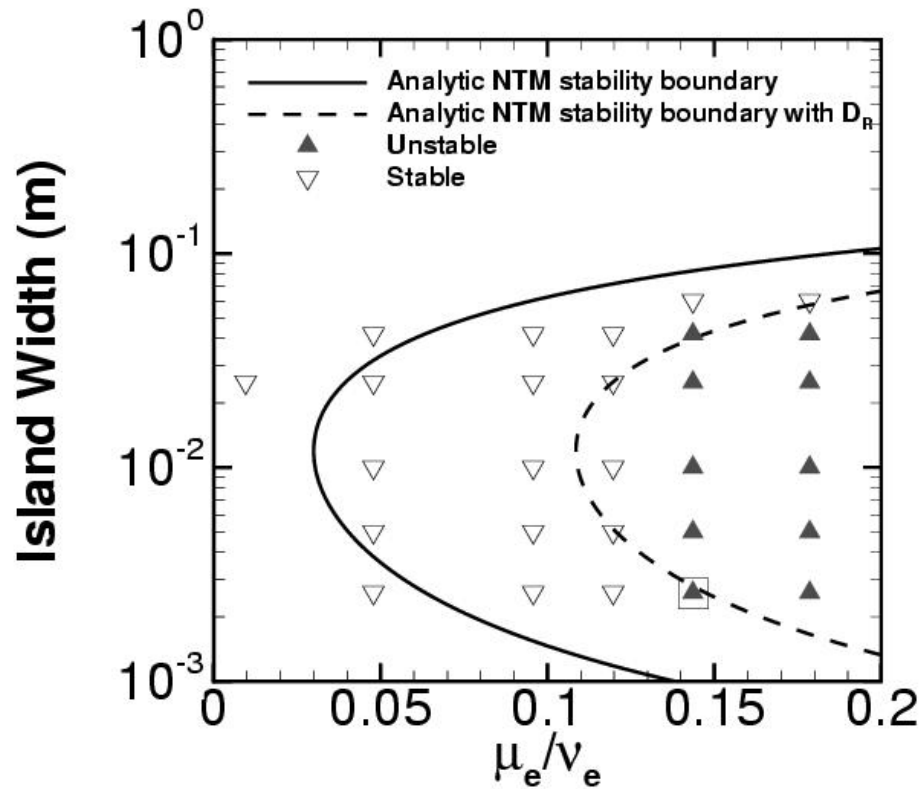
The NIMROD Hall-MHD computation shows important characteristics of two-fluid reconnection.



The characteristic results from $t=23 \Omega^{-1}$ are the open geometry of the reconnecting magnetic flux (left) and the quadrupole out-of-plane magnetic field (right).



Test of “Heuristic Closure” for Neoclassical Physics



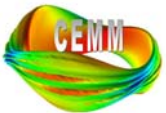
(Gianakon et.al., Phys. Plasmas **9**, 536 (2002))

Neo-classical theory gives flux surface average

Local form for stress tensor forces:

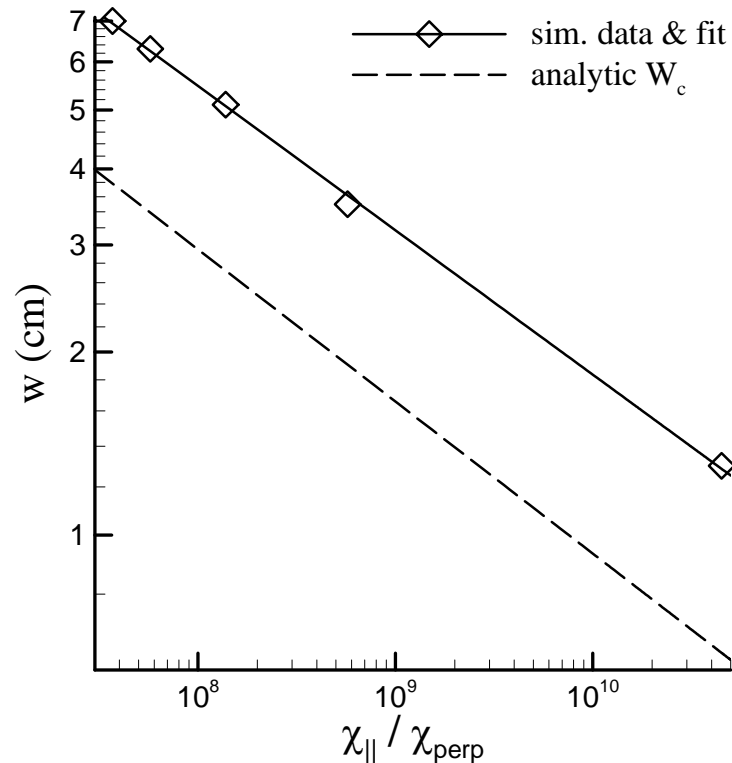
$$\nabla \cdot \Pi_{\alpha} = \rho_{\alpha} \mu_{\alpha} \langle B^2 \rangle \frac{\mathbf{V}_{\alpha} \cdot \mathbf{e}_{\theta}}{(B_{\alpha} \cdot \mathbf{e}_{\theta})^2} \mathbf{e}_{\theta}$$

- Valid for both ion and electrons
- Energy conserving and entropy producing
- Gives:
 - bootstrap current
 - neoclassical resistivity
 - polarization current enhancement



Testing Anisotropic Heat Conduction

- Critical island width for temperature flattening
- Dealing with extreme anisotropy
- Agreement on scaling (Fitzpatrick)



Beyond Extended MHD: Parallel Kinetic closures

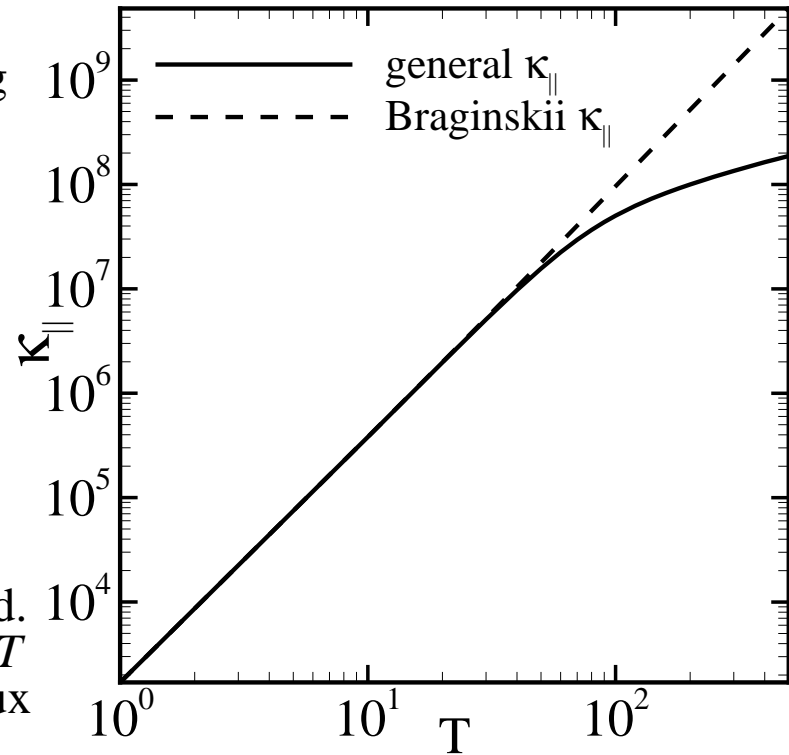
• Parallel closures for q_{\parallel} and Π_{\parallel} derived using Chapman-Enskog-like approach.

• Non-local; requires integration along perturbed field lines.

• General closures map continuously from collisional to nearly collisionless regime.

• General q_{\parallel} closure predicts collisional response for heat flow inside magnetic island. As plasma becomes moderately collisional ($T > 50$ eV), general closure predicts correct flux limited response.

• Incorporated into global extended MHD algorithms.



Thermal diffusivity as function of T showing $T^{5/2}$ response of Braginskii and general closure.



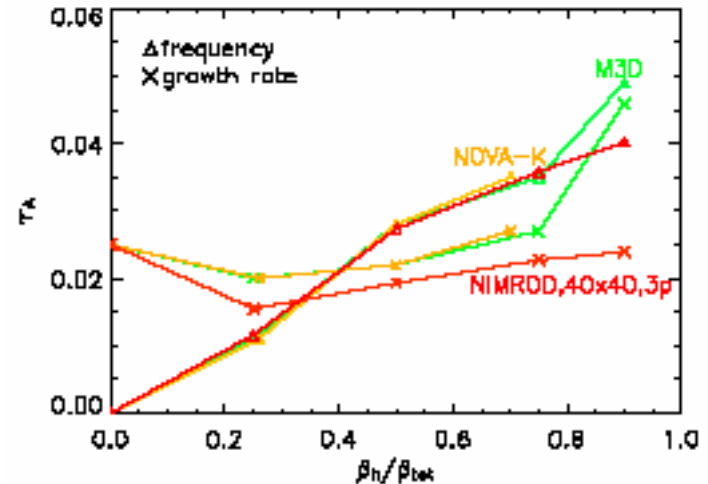
Beyond Extended MHD: Kinetic Minority Species

- Minority ions species affects bulk evolution:

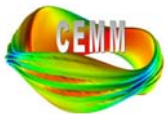
$$n_h \ll n_0 \quad , \quad \beta_h \sim \beta_0$$

$$Mn \frac{d\mathbf{V}}{dt} = \mathbf{J} \times \mathbf{B} - \underbrace{\nabla \cdot \Pi}_{\text{Bulk Plasma}} - \underbrace{\nabla \cdot \Pi_h}_{\text{Hot Minority Ion Species}}$$

$$\delta\Pi_h = \int M (\mathbf{v} - \mathbf{V}_h)(\mathbf{v} - \mathbf{V}_h) \delta f(\mathbf{x}, \mathbf{v}) d^3\mathbf{v}$$



- δf determined by kinetic particle simulation in evolving fields
- Demonstrated transition from internal kink to fishbone
- Benchmark of three codes



Form of the Gyro-viscous Stress (Hooke's Law for a Magnetized Plasma)

- Braginskii: $\Pi_{\wedge} = \Pi^{g\nu} = \frac{p}{4\Omega} [(\mathbf{b} \times \mathbf{W}) \cdot (\mathbf{I} + 3\mathbf{b}\mathbf{b}) + transpose]$

$$\mathbf{W} = \nabla \mathbf{V} + \nabla \mathbf{V}^T - \frac{2}{3} \mathbf{I} \nabla \cdot \mathbf{V}$$

- Suggested modifications for consistency (*Mikhailovskii and Tsypin, Hazeltine and Meiss, Simakov and Catto, Ramos*) involve adding term proportional to the ion heat rate of strain:

$$\Pi_{\wedge q} = \frac{2}{5\Omega} [\mathbf{b} \times \mathbf{W}_q \cdot (\mathbf{I} + 3\mathbf{b}\mathbf{b}) + transpose]$$

$$\mathbf{W}_q = \nabla \mathbf{q}_i + \nabla \mathbf{q}_i^T - \frac{2}{3} \mathbf{I} \nabla \cdot \mathbf{q}_i$$

- Implicit numerical treatment difficult (new coupling between momentum and energy equations)
- What is the effect of this term on dispersion and stability?
 - *Does it introduce new normal modes?*
 - *Does it alter stability properties?*



Effect of Ion Heat Stress on Important Dynamics

$$\Pi \wedge q = \frac{2}{5\Omega} [\mathbf{b} \times \mathbf{W}_q \cdot (\mathbf{I} + 3\mathbf{b}\mathbf{b}) + \text{transpose}]$$

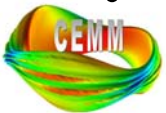
$$\mathbf{W}_q = \nabla \mathbf{q}_i + \nabla \mathbf{q}_i^T - \frac{2}{3} \mathbf{I} \nabla \cdot \mathbf{q}_i \quad \mathbf{q} = -\kappa_{\parallel} \nabla_{\parallel} T - \kappa_{\perp} \nabla_{\perp} T - \kappa \wedge \mathbf{b} \times \nabla_{\perp} T$$

$$\rho_0 \frac{\partial \mathbf{V}}{\partial t} = -\nabla p - \nabla \cdot \Pi \wedge q$$

$$\frac{\partial p}{\partial t} = -\gamma p_0 \nabla \cdot \mathbf{V}$$

$$\omega^2 = C_s^2 k^2 \left[1 + f(\theta) (\rho_i k)^2 \right] \quad f(0) = 0 \quad f(\pi/2) = 1$$

- Dispersive effect on compressional waves, but.....
- Negligible effect on g-mode stability
- Prioritization: *ignore these terms (for now!)*
- Open to counter arguments



Theory and Computation

- Theory and computation are synergistic
 - Just different tools for solving problems
- Theory needs guidance from the needs of large scale computations
- Computations need guidance for relevant equations and expectations from theory
- Closer collaboration between theory and computation required for the success of either program
- *Attempts to promote one at the expense of the other are unwise*



Summary

- Extended MHD problems are extremely difficult and complex
- Must be studied with equally complex algorithms
- Basic processes often masked (and also influenced) by geometry
- *How do we learn to trust the computational models?*
 - Define program of simple problems with known solutions to test aspects of the models
 - Hierarchy of problems from simple to more complex
 - Require all codes to run these problems
 - Urge theorists to propose relevant test problems
 - Cross your fingers when studying non-linear tokamaks!

