

The Center for Extended Magnetohydrodynamic Modeling

(Global Stability of Magnetic Fusion Devices)

S. Jardin—lead PI

a SciDAC activity...

Partners with:

TOPS

TSTT

APDEC

MIT: D. Brennan, [L. Sugiyama](#), J. Ramos

NYU: B. Hientzsch, [H. Strauss](#)

PPPL: J. Breslau, J. Chen, G. Fu, S. Klasky, [W. Park](#), R. Samtaney

SAIC: [D. Schnack](#), A. Pankin

TechX: S. Kruger

U. Colorado: [S. Parker](#), D. Barnes

U. Wisconsin: J. Callen, C. Hegna, [C. Sovinec](#), C. Kim

U. Utah: A. Sanderson

Utah State: E. Held

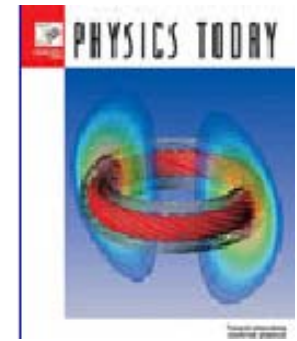
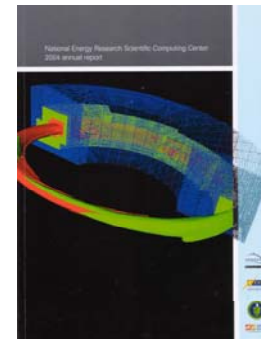


New York University



CEMM Bibliography for the period 5/04 – 5/05

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- S. E. Kruger, D. D. Schnack, and C. R. Sovinec 2005 Dynamics of the major disruption of a DIII-D plasma, *PHYSICS OF PLASMAS* 12 10-pages
- Wan, W; Chen, Y; Parker, SE. 2005. Gyrokinetic delta f simulation of the collisionless and semicollisional tearing mode instability. *PHYSICS OF PLASMAS* 12 (1): art. no.-012311.
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- Held, ED; Callen, JD; Hegna, CC; Sovinec, CR; Gianakon, TA; Kruger, SE. 2004. Nonlocal closures for plasma fluid simulations. *PHYSICS OF PLASMAS* 11 (5): 2419-2426.
- B.I. Cohen, E.B. Hooper, R.H. Cohen, D. N. Hill, H.S. McLean, R.D. Wood, S. Woodruff, C.R. Sovinec, and G.A.Cone, 2005 Simulation of Spheromak evolution and energy confinement, *PHYSICS OF PLASMAS*, 12 9-pages
- J. Ramos, 2005, "Fluid formalism for collisionless magnetized plasmas", *PHYSICS OF PLASMAS* 12 .
- J. Chen, S. C. Jardin, and H.R. Strauss, "Solving Anisotropic Transport Equations on Misaligned Grids", Springer-Verlag, Lecture Notes in Computer Science, 3516, pp. 1076-1079, 2005



Activity Areas

- Spatial Discretizations
 - M3D C1
 - Spectral and lumped mass elements
- Two-Fluid MHD and Associated Temporal Differencing
- Numerical Closures
- Sawtooth Modeling
- ELM Modeling
- Hybrid Calculations
- Adaptive Mesh Refinement
- Spheromak Modeling
- 2-fluid NSTX Modeling
- Visualization
- Misc.

2D 6-field 2-fluid model has been implemented in M3D-C¹

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}, \quad \vec{J} = \nabla \times \vec{B}$$

$$\vec{E} + \vec{V} \times \vec{B} = \frac{1}{ne} (\vec{R} + \vec{J} \times \vec{B} - \nabla p_e - \nabla \cdot \vec{\Pi}_e)$$

$$nM_i \left(\frac{\partial \vec{V}}{\partial t} + \vec{V} \cdot \nabla \vec{V} \right) + \nabla p_e = \vec{J} \times \vec{B} - \nabla \cdot \vec{\Pi}_i$$

$$\frac{3}{2} \frac{\partial p_e}{\partial t} + \nabla \cdot \left(\frac{3}{2} p_e \vec{V} \right) = -p_e \nabla \cdot \vec{V} + \frac{\vec{J}}{ne} \cdot \left[\frac{3}{2} \nabla p_e + \vec{R} - \nabla \cdot \vec{\Pi}_e \right]$$

$$\vec{R} = \eta ne \vec{J}$$

$$\vec{\Pi}_i = -\mu n \left[\nabla \vec{V} + \nabla \vec{V}^\dagger \right] + h \mu n \nabla^2 \left[\nabla \vec{V} + \nabla \vec{V}^\dagger \right]$$

$$\vec{\Pi}_e = \lambda ne \left[\nabla \vec{J} + \nabla \vec{J}^\dagger \right]$$

$$\vec{V} = \nabla U \times \hat{z} + \nabla_\perp \chi + V_z \hat{z},$$

$$\vec{B} = \nabla \psi \times \hat{z} + I \hat{z}$$

p_e

. take projections of momentum eqn:

$$-\hat{z} \cdot \nabla \times$$

$$\hat{z} \cdot$$

$$\nabla \cdot$$

. expand in C^1 finite elements

. full implicit time differencing

M3D-C¹ code has full Extended MHD (2-fluid) equations with implicit differencing that allows time step to be determined by accuracy only:

$$\begin{bmatrix} S_{11}^v & S_{12}^v & S_{13}^v \\ S_{21}^v & S_{22}^v & S_{23}^v \\ S_{31}^v & S_{32}^v & S_{33}^v \end{bmatrix} \cdot \begin{bmatrix} U \\ V_z \\ \chi \end{bmatrix}^{n+1} = \begin{bmatrix} D_{11}^v & D_{12}^v & D_{13}^v \\ D_{21}^v & D_{22}^v & D_{23}^v \\ D_{31}^v & D_{32}^v & D_{33}^v \end{bmatrix} \cdot \begin{bmatrix} U \\ V_z \\ \chi \end{bmatrix}^n + \begin{bmatrix} R_{11}^v & R_{12}^v & R_{13}^v \\ R_{21}^v & R_{22}^v & R_{23}^v \\ R_{31}^v & R_{32}^v & R_{33}^v \end{bmatrix} \cdot \begin{bmatrix} \psi \\ I \\ T_e \end{bmatrix}^n$$

Alfvén Wave physics

$$\begin{bmatrix} S_{11}^p & S_{12}^p & S_{13}^p \\ S_{21}^p & S_{22}^p & S_{23}^p \\ S_{31}^p & S_{32}^p & S_{33}^p \end{bmatrix} \cdot \begin{bmatrix} \psi \\ I \\ T_e \end{bmatrix}^{n+1} = \begin{bmatrix} D_{11}^p & D_{12}^p & D_{13}^p \\ D_{21}^p & D_{22}^p & D_{23}^p \\ D_{31}^p & D_{32}^p & D_{33}^p \end{bmatrix} \cdot \begin{bmatrix} \psi \\ I \\ T_e \end{bmatrix}^n + \begin{bmatrix} R_{11}^p & R_{12}^p & R_{13}^p \\ R_{21}^p & R_{22}^p & R_{23}^p \\ R_{31}^p & R_{32}^p & R_{33}^p \end{bmatrix} \cdot \begin{bmatrix} U \\ V_z \\ \chi \end{bmatrix}^{n+1} + \begin{bmatrix} Q_{11}^p & Q_{12}^p & Q_{13}^p \\ Q_{21}^p & Q_{22}^p & Q_{23}^p \\ Q_{31}^p & Q_{32}^p & Q_{33}^p \end{bmatrix} \cdot \begin{bmatrix} U \\ V_z \\ \chi \end{bmatrix}^n$$

Whistler, KAW, field diffusion physics

Phase-I: Reduced 2-field MHD:

$$\frac{\partial}{\partial t} \nabla^2 U + [\nabla^2 U, U] - [\nabla^2 \psi, \psi] = \mu \nabla^4 U$$

$$\frac{\partial \psi}{\partial t} + [\psi, U] = \eta \nabla^2 \psi$$

Phase-II: Fitzpatrick-Porcelli 4-field model:

$$\frac{\partial}{\partial t} \nabla^2 U = [U, \nabla^2 U] + [\nabla^2 \psi, \psi] + \mu \nabla^4 U$$

$$\frac{\partial V_z}{\partial t} = [U, V_z] + c_\beta [I, \psi] + \mu \nabla^2 V_z$$

$$\frac{\partial \psi}{\partial t} = [U, \psi] + d_\beta [\psi, I] + \eta \nabla^2 \psi$$

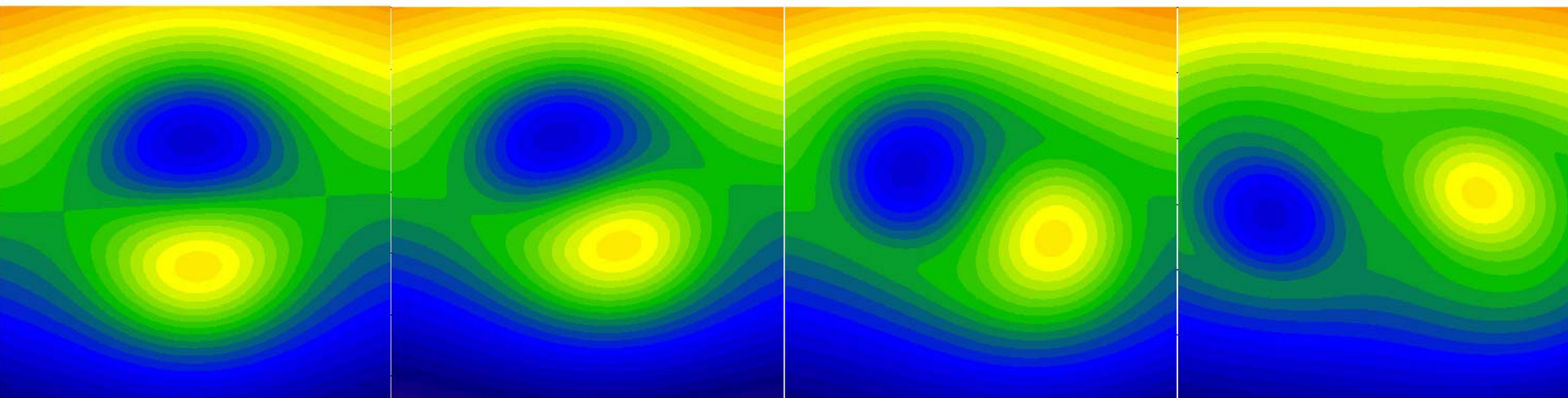
$$\frac{\partial I}{\partial t} = [U, I] + d_\beta [\nabla^2 \psi, \psi] + c_\beta [V_z, \psi] + c_\beta^2 \eta \nabla^2 I$$

$$\vec{V} = \nabla U \times \hat{z} + \nabla_\perp \chi + V_z \hat{z}$$

$$\vec{B} = \nabla \psi \times \hat{z} + I \hat{z}$$

Equations expressed in a form that allows non-trivial subsets of lower rank equations:

Non-linear evolution of tilting cylinder in full 6-field 2-fluid model

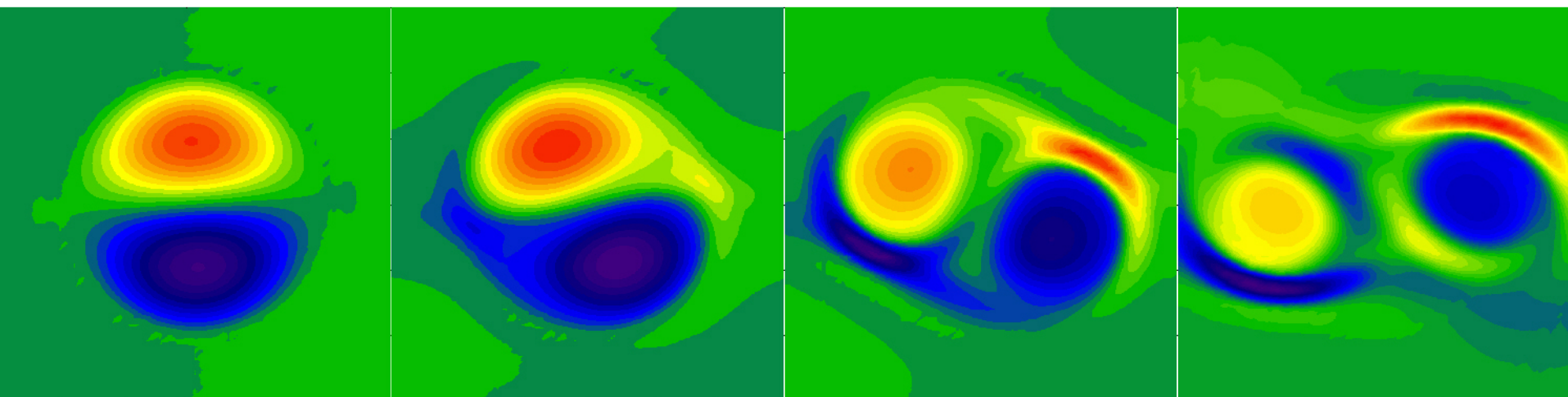


Ψ : $t=0.8$

Ψ : $t=3.8$

Ψ : $t=4.0$

Ψ : $t=4.8$



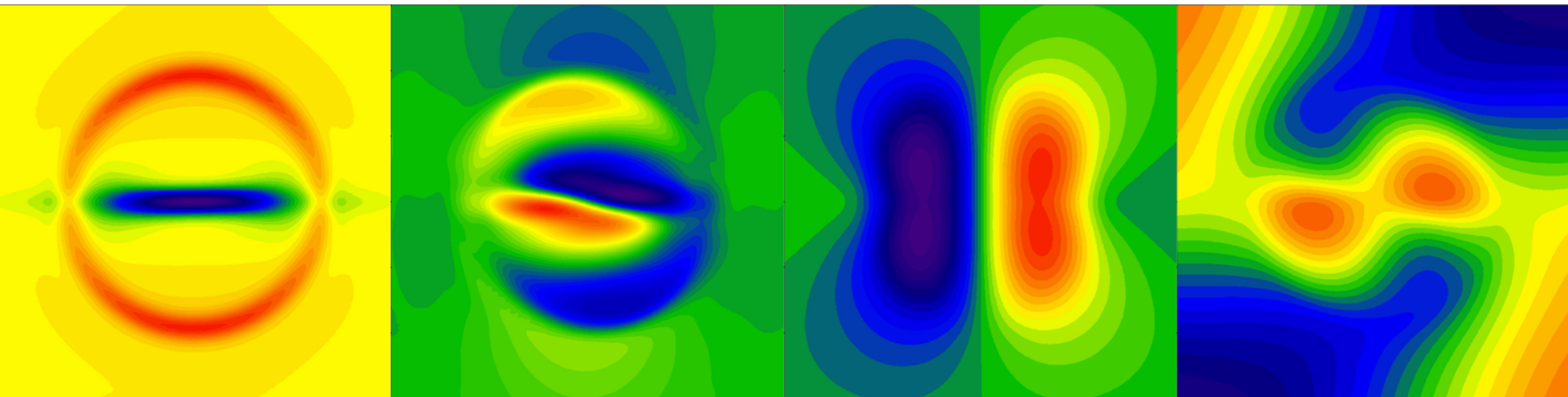
J : $t=0.8$

J : $t=3.2$

J : $t=4.0$

J : $t=4.8$

Linear eigenmode of tilting cylinder in 6-field 2-fluid model

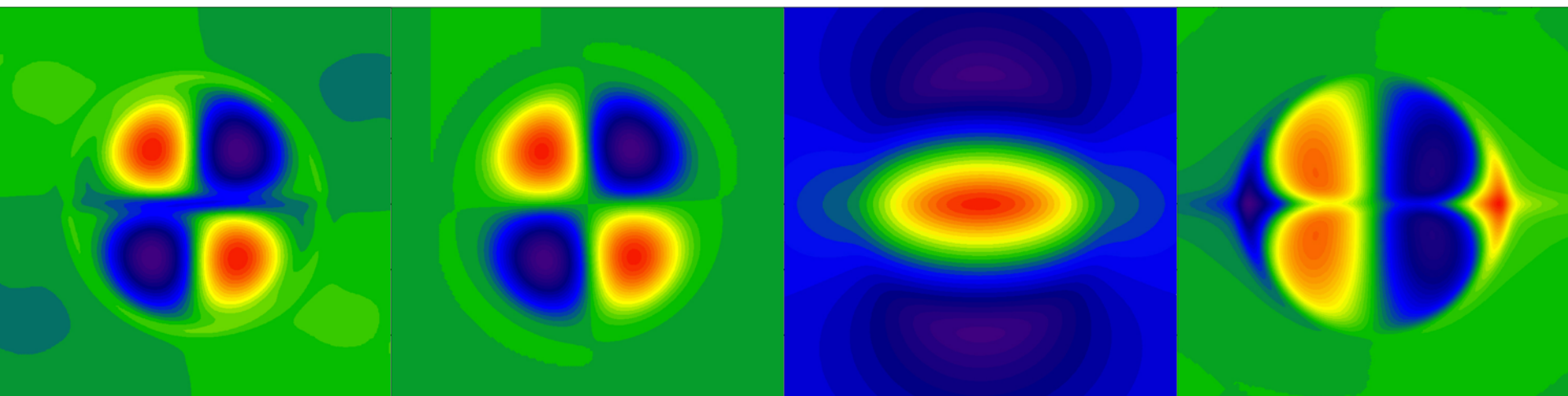


$\nabla^2 U$
Vorticity

V
Toroidal Velocity

Ψ
Poloidal Flux

χ
Velocity Potential



I
Toroidal field

P_e
Electron Pressure

U
Stream Function

J
Toroidal Current

**Braginskii
gyro-viscosity:**

$$\nabla \cdot \vec{\Pi} = \left\{ \left[\nabla \times \left(\frac{mp}{eB^2} \vec{B} \right) \cdot \nabla \right] \cdot \vec{V} - \nabla \left[\frac{mp}{2eB^2} \vec{B} \cdot (\nabla \times \vec{V}) \right] - \nabla \times \left\{ \frac{mp}{eB^2} \left[(\vec{B} \cdot \nabla) \vec{V} + \frac{1}{2} \left(\nabla \cdot \vec{V} - \frac{3}{B^2} \vec{B} \cdot [(\vec{B} \cdot \nabla) \vec{V}] \right) \vec{B} \right] \right\} \right. \\ \left. + (\vec{B} \cdot \nabla) \left\{ \frac{mp}{eB^2} \left(\frac{3}{B^2} \vec{B} \times [(\vec{B} \cdot \nabla) \vec{V}] + \frac{3}{2B^2} [\vec{B} \cdot (\nabla \times \vec{V})] \vec{B} - \nabla \times \vec{V} \right) \right\} \right\}$$

Ramos

$$\hat{z} \cdot \rightarrow [V_z, \alpha I] - \alpha \left\{ [\psi, \nabla_{\perp}^2 U] + \left[\frac{\partial \psi}{\partial x}, \frac{\partial U}{\partial x} - \frac{\partial \chi}{\partial y} \right] + \left[\frac{\partial \psi}{\partial y}, \frac{\partial U}{\partial y} + \frac{\partial \chi}{\partial x} \right] \right\} - \frac{\partial \alpha}{\partial x} \left[\psi, \frac{\partial U}{\partial x} - \frac{\partial \chi}{\partial y} \right] - \frac{\partial \alpha}{\partial y} \left[\psi, \frac{\partial U}{\partial y} + \frac{\partial \chi}{\partial x} \right] \\ + \frac{1}{2} \alpha \nabla_{\perp}^2 \chi \nabla_{\perp}^2 \psi + \frac{1}{2} (\alpha \nabla_{\perp}^2 \chi, \psi) - \frac{1}{2} [(\gamma \kappa, \psi) + \gamma \kappa \nabla_{\perp}^2 \psi] + [\gamma \xi_z, \psi] + \frac{1}{2} [\lambda I, \psi] + [\alpha \nabla_{\perp}^2 U, \psi]$$

$$-\hat{z} \cdot \nabla \times \rightarrow \left[\frac{\partial \chi}{\partial x} + \frac{\partial U}{\partial y}, \frac{\partial(\alpha I)}{\partial y} \right] - \left[\frac{\partial \chi}{\partial y} - \frac{\partial U}{\partial x}, \frac{\partial(\alpha I)}{\partial x} \right] + [\nabla_{\perp}^2 U, \alpha I] + \nabla_{\perp}^2 \{ \alpha [\psi, V_z] \} - \frac{1}{2} \nabla_{\perp}^2 (\alpha I \nabla_{\perp}^2 \chi) + \frac{1}{2} \nabla_{\perp}^2 (\gamma \kappa I) \\ + \frac{\partial}{\partial y} [\gamma \xi_x, \psi] - \frac{\partial}{\partial x} [\gamma \xi_y, \psi] + \frac{1}{2} \left\{ \frac{\partial \lambda}{\partial x} \left[\frac{\partial \psi}{\partial x}, \psi \right] + \frac{\partial \lambda}{\partial y} \left[\frac{\partial \psi}{\partial y}, \psi \right] + ([\lambda, \psi], \psi) + [\lambda \nabla_{\perp}^2 \psi, \psi] \right\} + \frac{\partial}{\partial x} \left[\psi, \alpha \frac{\partial V_z}{\partial x} \right] + \frac{\partial}{\partial y} \left[\psi, \alpha \frac{\partial V_z}{\partial y} \right]$$

$$\nabla \cdot \rightarrow \left[\frac{\partial \chi}{\partial x} + \frac{\partial U}{\partial y}, \frac{\partial(\alpha I)}{\partial x} \right] + \left[\frac{\partial \chi}{\partial y} - \frac{\partial U}{\partial x}, \frac{\partial(\alpha I)}{\partial y} \right] + [\nabla_{\perp}^2 \chi, \alpha I] + \frac{1}{2} \nabla_{\perp}^2 \{ \alpha [I \nabla_{\perp}^2 U - (\psi, V_z)] \} + \frac{\partial}{\partial x} [\gamma \xi_x, \psi] + \frac{\partial}{\partial y} [\gamma \xi_y, \psi] \\ + \frac{1}{2} [[\lambda, \psi], \psi] + \lambda \left[\frac{\partial \psi}{\partial y}, \frac{\partial \psi}{\partial x} \right] + \frac{1}{2} \frac{\partial \lambda}{\partial x} \left[\frac{\partial \psi}{\partial y}, \psi \right] - \frac{1}{2} \frac{\partial \lambda}{\partial y} \left[\frac{\partial \psi}{\partial x}, \psi \right] + \frac{\partial}{\partial x} \left\{ \alpha \left[\psi, \frac{\partial V_z}{\partial y} \right] \right\} - \frac{\partial}{\partial y} \left\{ \alpha \left[\psi, \frac{\partial V_z}{\partial x} \right] \right\} + [V_z, [\alpha, \psi]]$$

$$\alpha \equiv \frac{ep}{mB^2} = \frac{ep/m}{\left(\frac{\partial \psi}{\partial x} \right)^2 + \left(\frac{\partial \psi}{\partial y} \right)^2 + I^2}$$

$$\gamma = \frac{3ep/m}{\left[\left(\frac{\partial \psi}{\partial x} \right)^2 + \left(\frac{\partial \psi}{\partial y} \right)^2 + I^2 \right]^2}$$

$$\vec{\xi} = \left\{ \frac{\partial \psi}{\partial x} [\psi, V_z] + I \left[\psi, \frac{\partial \chi}{\partial y} - \frac{\partial U}{\partial x} \right] \right\} \hat{x} \\ + \left\{ \frac{\partial \psi}{\partial y} [\psi, V_z] - I \left[\psi, \frac{\partial \chi}{\partial x} + \frac{\partial U}{\partial y} \right] \right\} \hat{y}$$

$$\lambda = \gamma [(\psi, V_z) - I \nabla_{\perp}^2 U]$$

$$\kappa \equiv \frac{\partial \psi}{\partial y} \left[\frac{\partial \chi}{\partial x} + \frac{\partial U}{\partial y}, \psi \right] - \frac{\partial \psi}{\partial x} \left[\frac{\partial \chi}{\partial y} - \frac{\partial U}{\partial x}, \psi \right] + I [V_z, \psi] - \left\{ \frac{\partial \psi}{\partial x} \left[\psi, \frac{\partial \chi}{\partial x} + \frac{\partial U}{\partial y} \right] + \frac{\partial \psi}{\partial y} \left[\psi, \frac{\partial \chi}{\partial y} - \frac{\partial U}{\partial x} \right] \right\} \hat{z}$$

Breslau

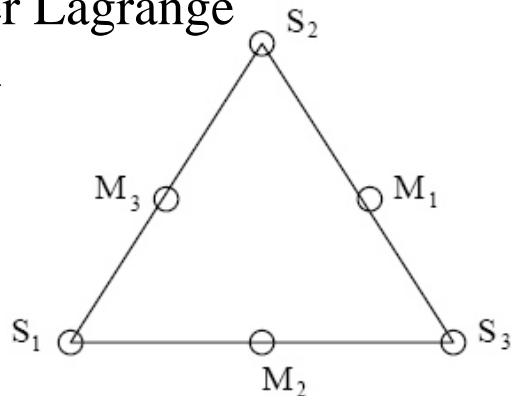
Activity Areas

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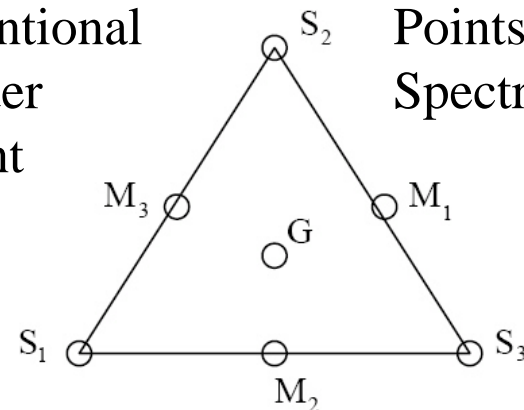
2nd and 3rd order lumped mass elements in M3D

- 2nd or 3rd order lumped mass elements in poloidal plane [Cohen et al, SIAM J. Numer. Anal. 38, 2047-2078 (2001)]
- Nodal points coincide with quadrature points
- Gives diagonal mass matrix ... important for M3D
- Theoretical 3rd (2nd order) and 4th order accuracy
- Now implemented in M3D .. being applied to ELM simulations
- Higher order spectral elements being explored by B. Hientzsch

Nodal points
of conventional
2nd order Lagrange
element



Quadrature
Points of
Conventional
2nd order
element



and

Nodal points
And quadrature
Points of 2nd order
Spectral element

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A new algorithm uses the leap-frog staggered data representation with a time-centered magnetic field update.

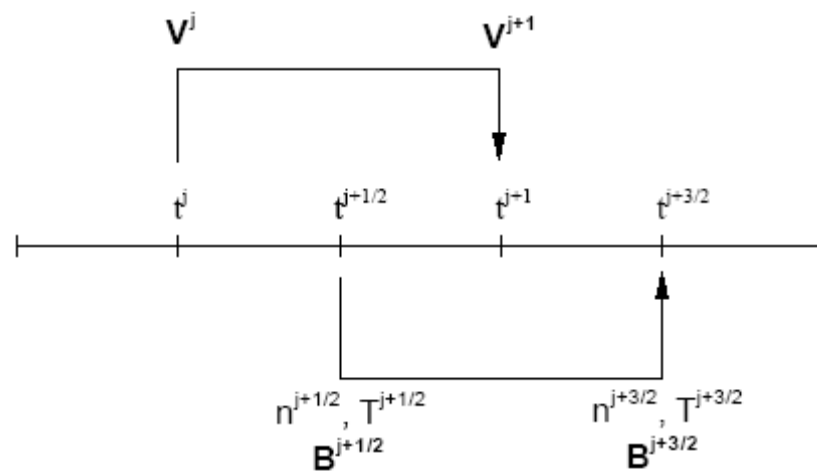
- This approach was motivated by the successful combination of the semi-implicit algorithm and time-centered advection (reported in http://www.cptc.wisc.edu/sovinec_research/meetings/sovinec_aps03poster.pdf)

Neglecting advection, dissipation, and the separate n and T advances for clarity:

$$(\rho + \Delta t^2 L) \Delta \mathbf{V} = (\Delta t \mathbf{J}^{n+1/2} \times \mathbf{B}^{n+1/2} - \Delta t \nabla p^{n+1/2})$$

$$\Delta p = -\Delta t \gamma p^{n+1/2} \nabla \cdot \mathbf{V}^{n+1}$$

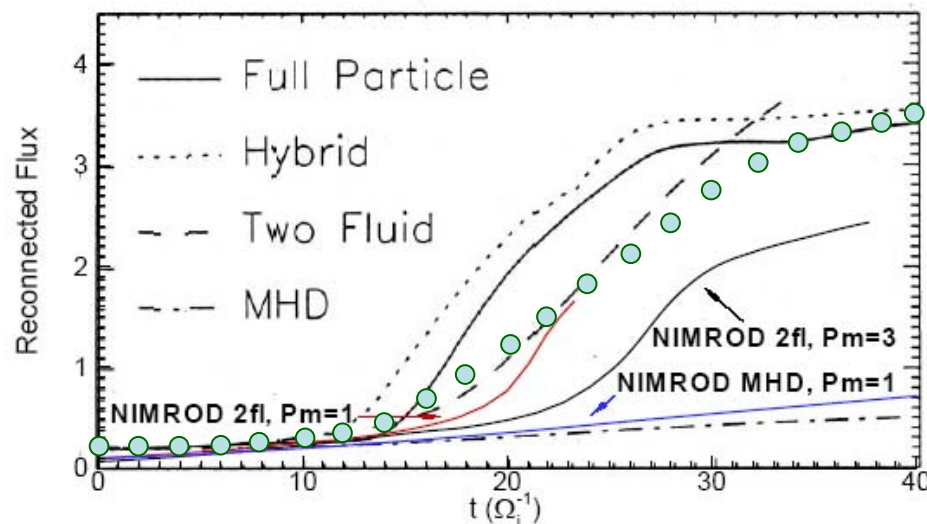
$$\Delta \mathbf{B} + \frac{\Delta t}{2} \nabla \times \frac{1}{ne} \left(\mathbf{J}^{n+1/2} \times \Delta \mathbf{B} + \frac{\nabla \times \Delta \mathbf{B}}{\mu_0} \times \mathbf{B}^{n+1/2} \right) = \Delta t \nabla \times (\mathbf{V}^{n+1} \times \mathbf{B}^{n+1/2}) - \Delta t \nabla \times \frac{1}{ne} (\mathbf{J}^{n+1/2} \times \mathbf{B}^{n+1/2} - \nabla p_e)$$



- The implicit Hall terms are linearized from the beginning of a time-step.

NIMROD reproduces fast reconnection in the GEM Challenge problem.

C. Sovinec and H. Tian, UW-Madison



● M3D-C¹, zero ion pressure, uniform density, $\eta=\mu=0.001$

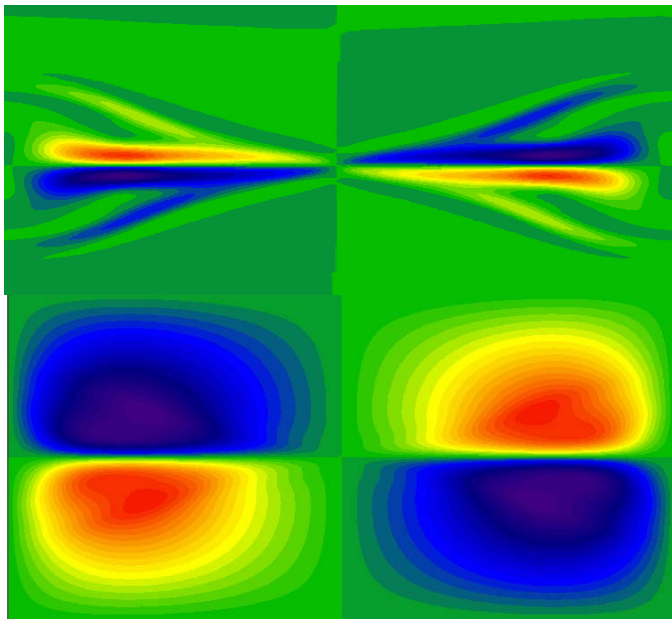
Reconnected magnetic flux in the GEM Challenge problem as a function of time.

- This comparison shows recent NIMROD Hall-MHD and resistive MHD results together with results published in Birn *et al.*, JGR.
- This problem has no guide field, and reconnection generates sonic flows well into the nonlinear phase of the 2-fluid computations.
- Since NIMROD does not have shock-capturing capabilities, viscosity is required. With a 72×96 mesh of biquadratic elements, $Pm=3$ is required to achieve saturation.

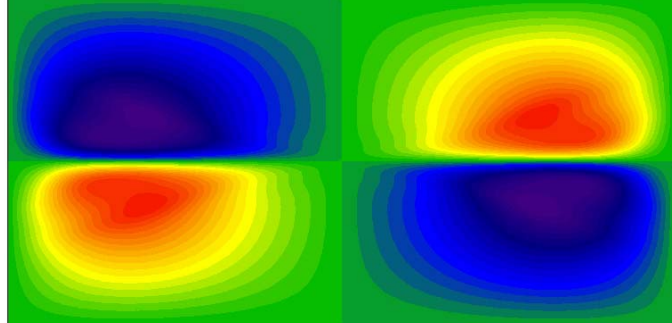
M3D-C' 61x61 triangles, no symmetry imposed: $t=30$

GEM Magnetic Reconnection 6-field 2-fluid model: $t=30$, $V_{\text{MAX}} \sim 0.8 V_A$

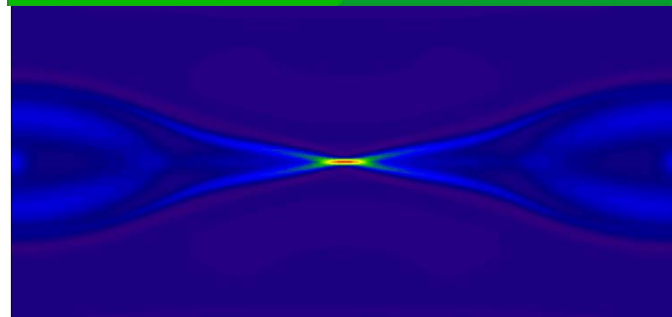
$\nabla^2 U$
Vorticity



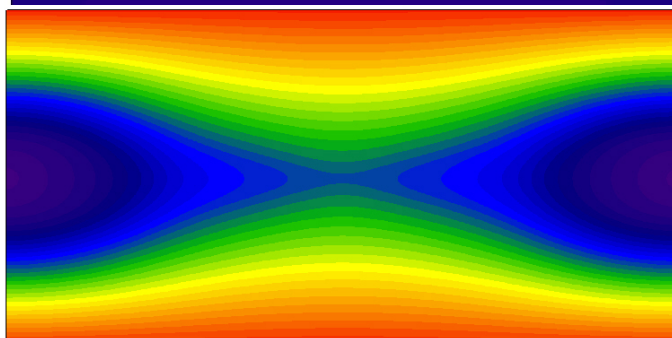
U
Stream
Function



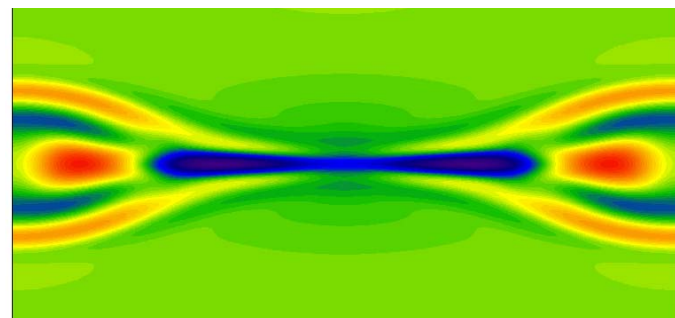
J
Toroidal
Current



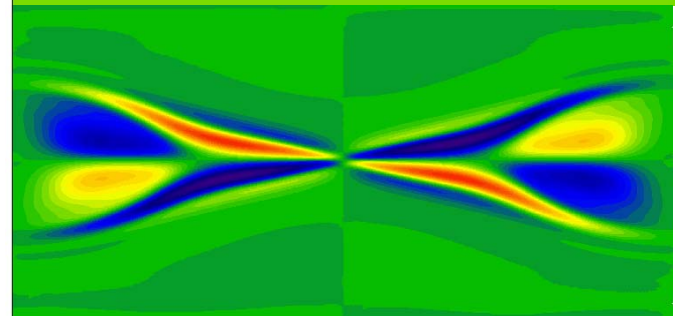
Ψ
Poloidal
Flux



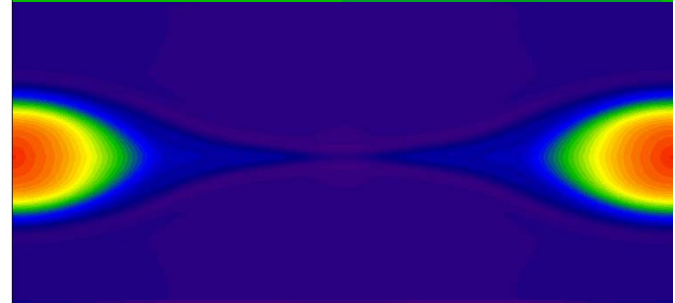
V
Toroidal
Velocity



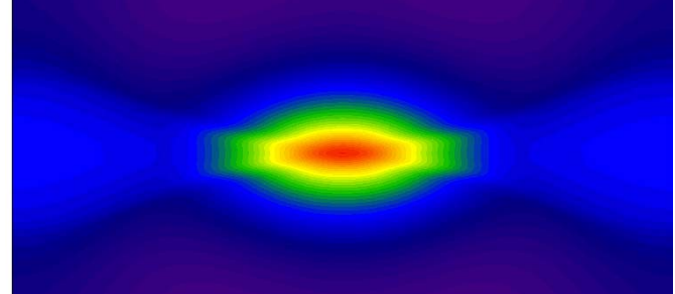
I
Toroidal
field



P_e
Electron
Pressure



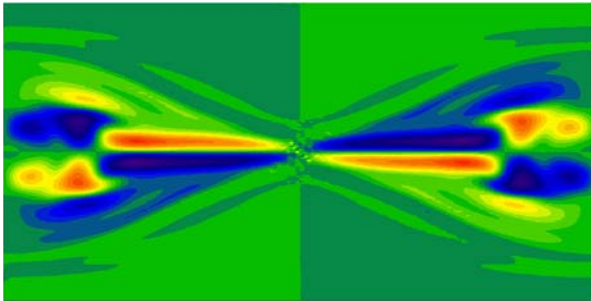
χ
Velocity
Potential



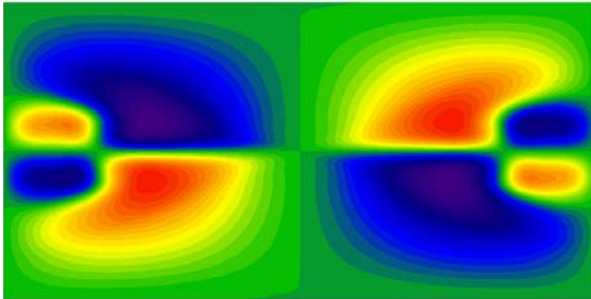
M3D-C¹ 61x61 triangles, no symmetry imposed: t=40

GEM Magnetic Reconnection 6-field 2-fluid model: t=40, $V_{\text{MAX}} \sim 0.8 V_A$

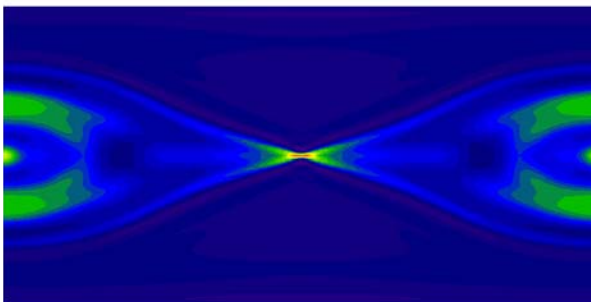
$\nabla^2 U$
Vorticity



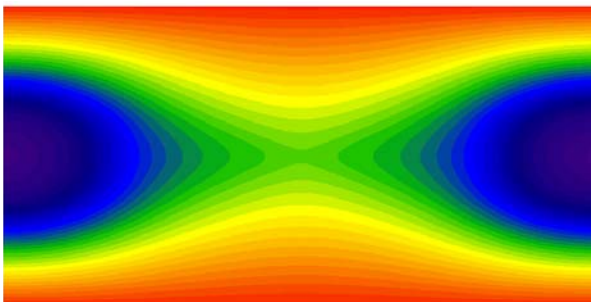
U
Stream
Function



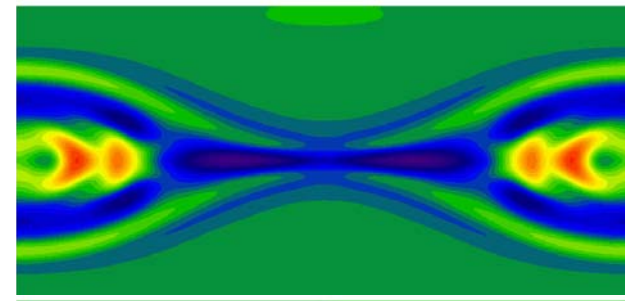
J
Toroidal
Current



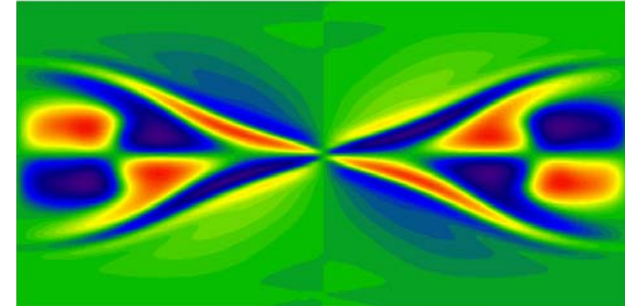
Ψ
Poloidal
Flux



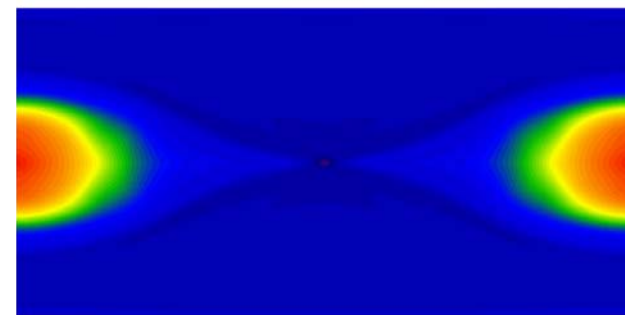
V
Toroidal
Velocity



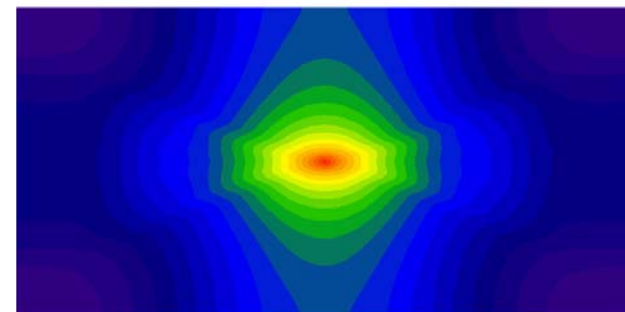
I
Toroidal
field



P_e
Electron
Pressure



χ
Velocity
Potential

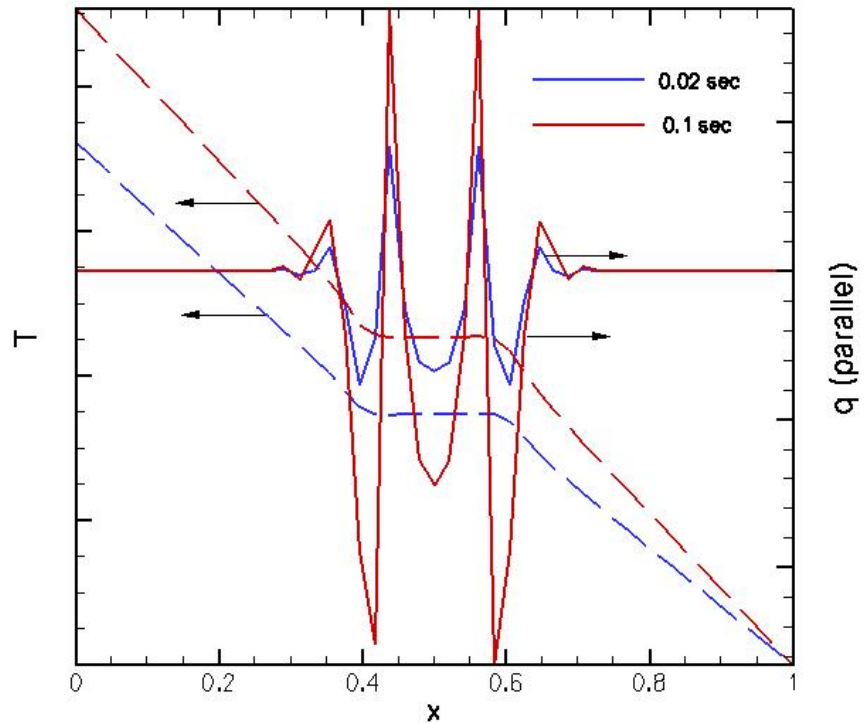


Activity Areas

- Spatial Discretizations
 - M3D C¹
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- Visualization
- Misc.

Improved efficiency of nonlocal, parallel closure implementation in NIMROD.

- Parallel heat flow, q_{\parallel} , and parallel ion stress now calculated by using a Lomb periodogram approach:
 - fit to approximate asymptotic forms of temperature and flow perturbations using data from integrations along magnetic field.
- Previous q_{\parallel} implementation took a week on 256 processors with $T = 1$ keV.
- Profiles shown at right calculated in 10 minutes on workstation with $T = 5$ keV.
- **Parallel closures ready to handle extreme temperatures and low collisionality of ITER plasmas.**

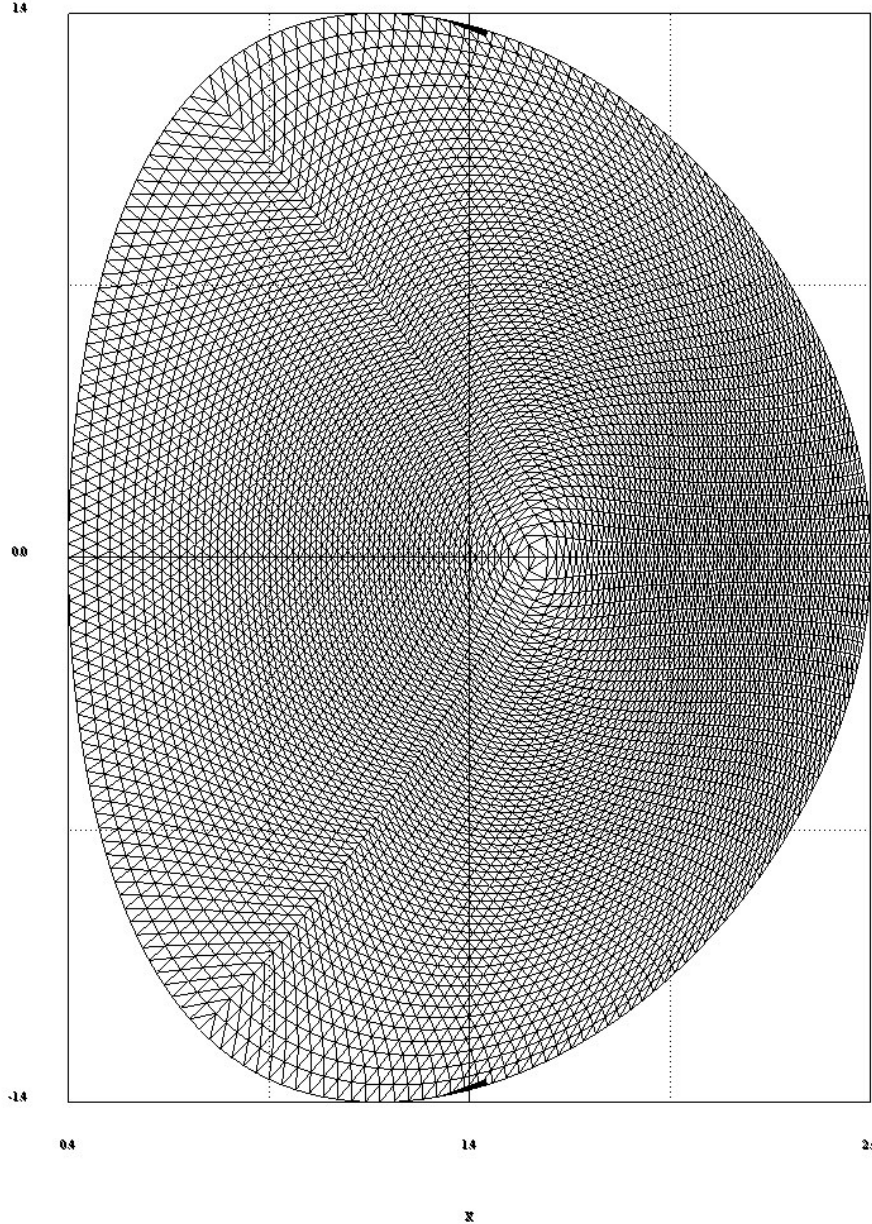


T and q_{\parallel} profiles across slab magnetic island show flattening in T and localized heat flow response. Island is centered at $0.4 < x < 0.6$ and $T = 5$ keV corresponds to a collision length of several kilometers.

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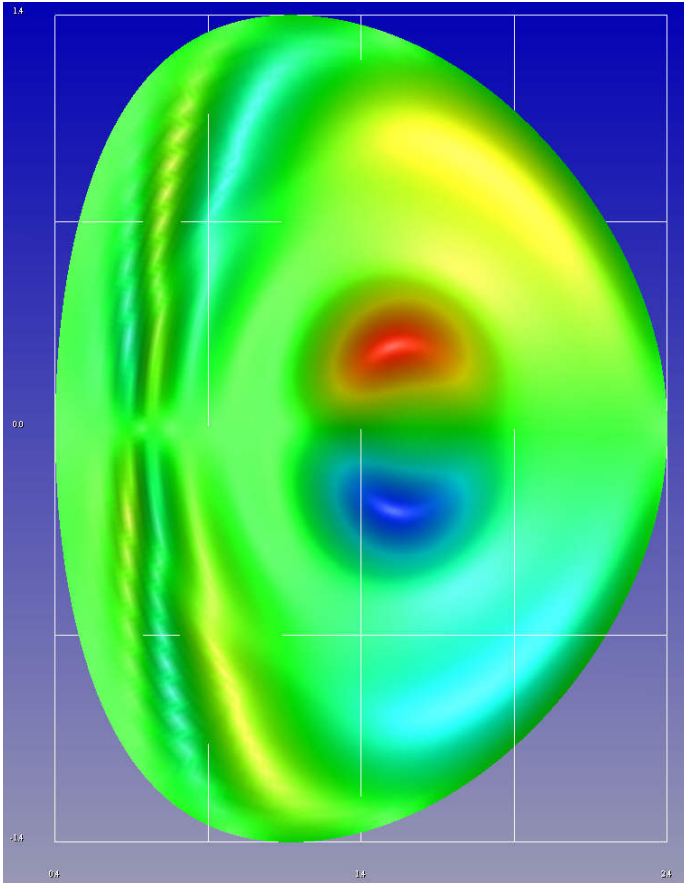
M3D Poloidal Mesh for CDX



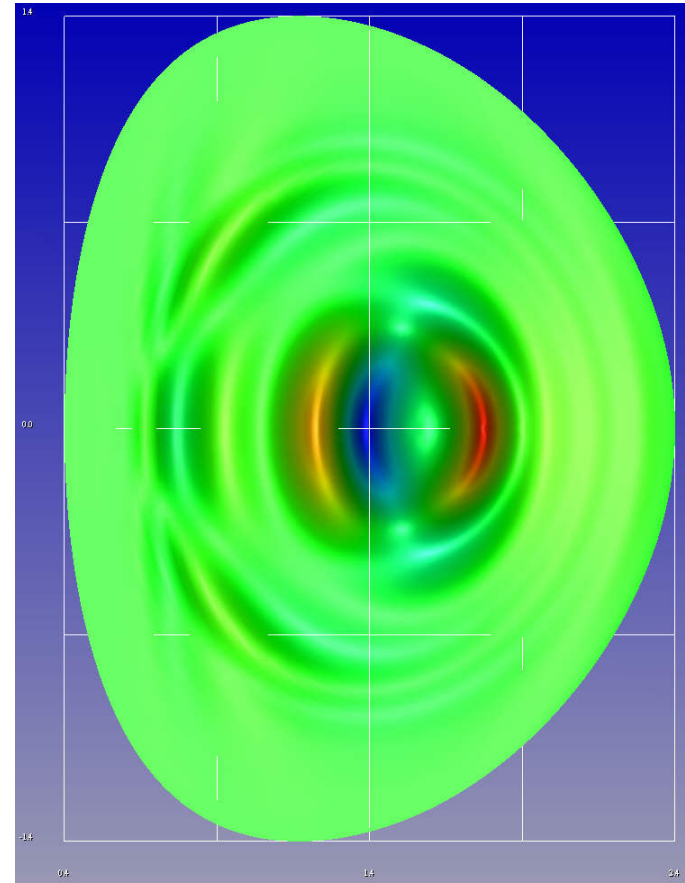
- 89 radial zones, up to 267 in θ in unstructured mesh
- Linear basis functions on triangular elements
- Conducting wall; current drive applied by adding a source term in Ohm's law.
- Finite differences toroidally; 24 planes

$n=1$ Eigenmode

Incompressible velocity
stream function U



Toroidal current density
 J_ϕ



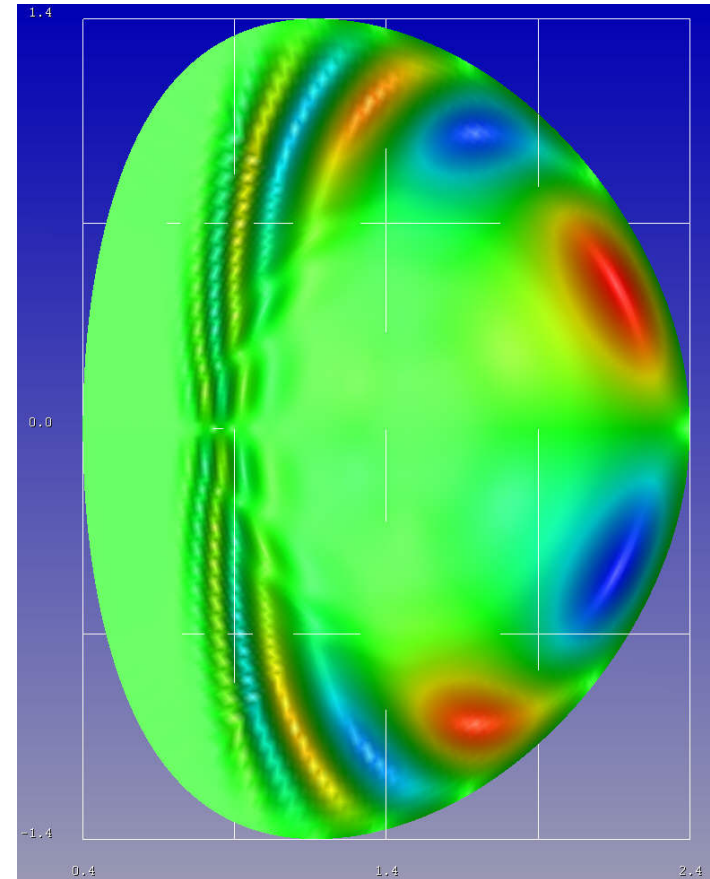
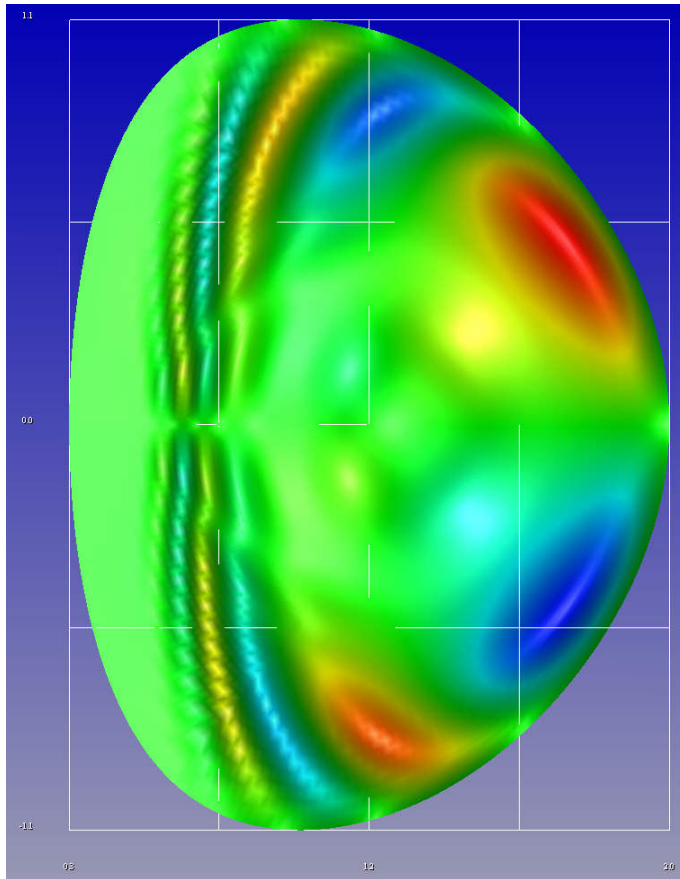
$$\gamma \tau_A = 8.61 \times 10^{-3} \rightarrow \text{growth time} = 116 \tau_A$$

Higher n Eigenmodes

Incompressible velocity
stream function U

$n = 2$

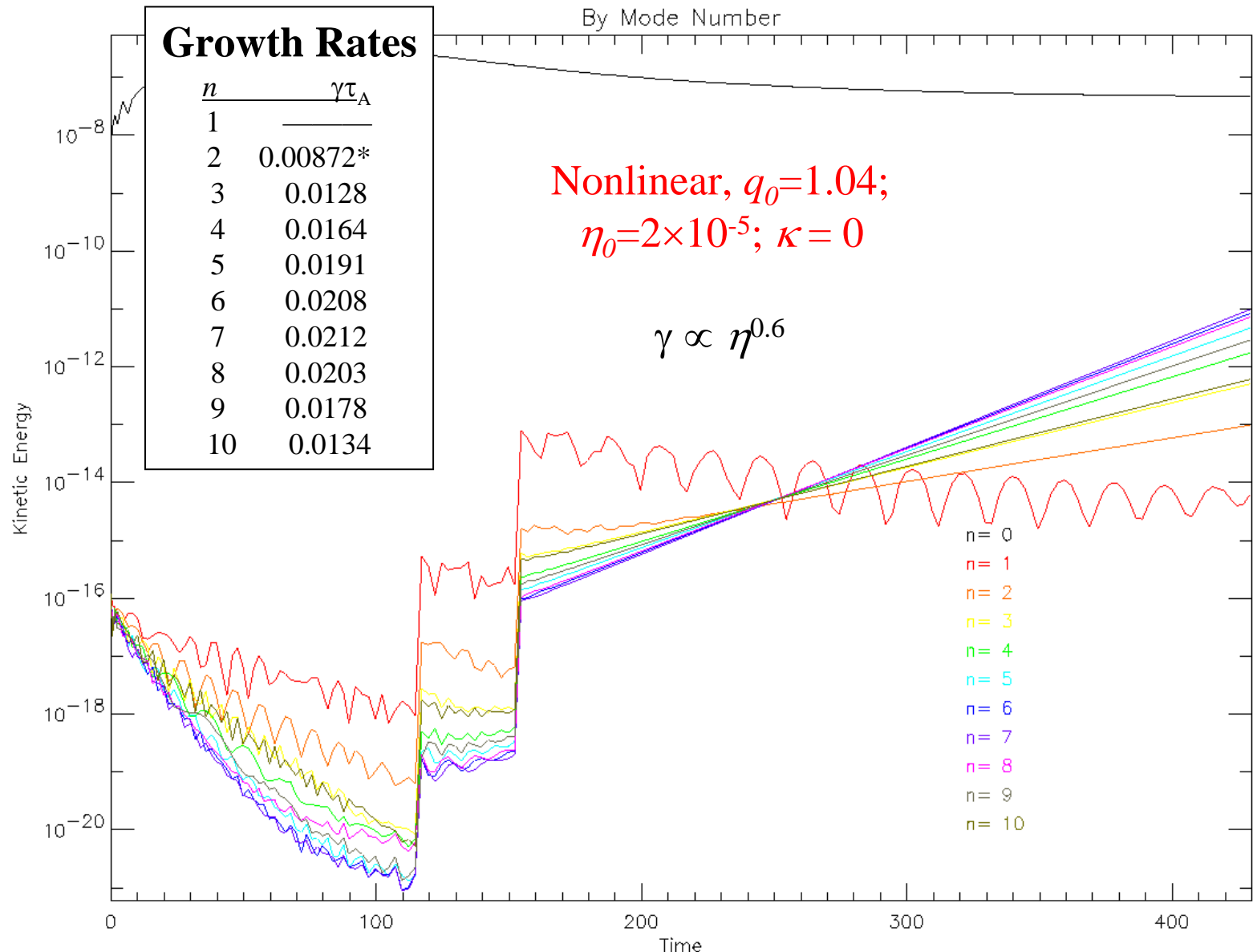
$n = 3$



$$m \geq 5$$
$$\gamma \tau_A = 1.28 \times 10^{-2}$$

$$m \geq 7$$
$$\gamma \tau_A = 1.71 \times 10^{-2}$$

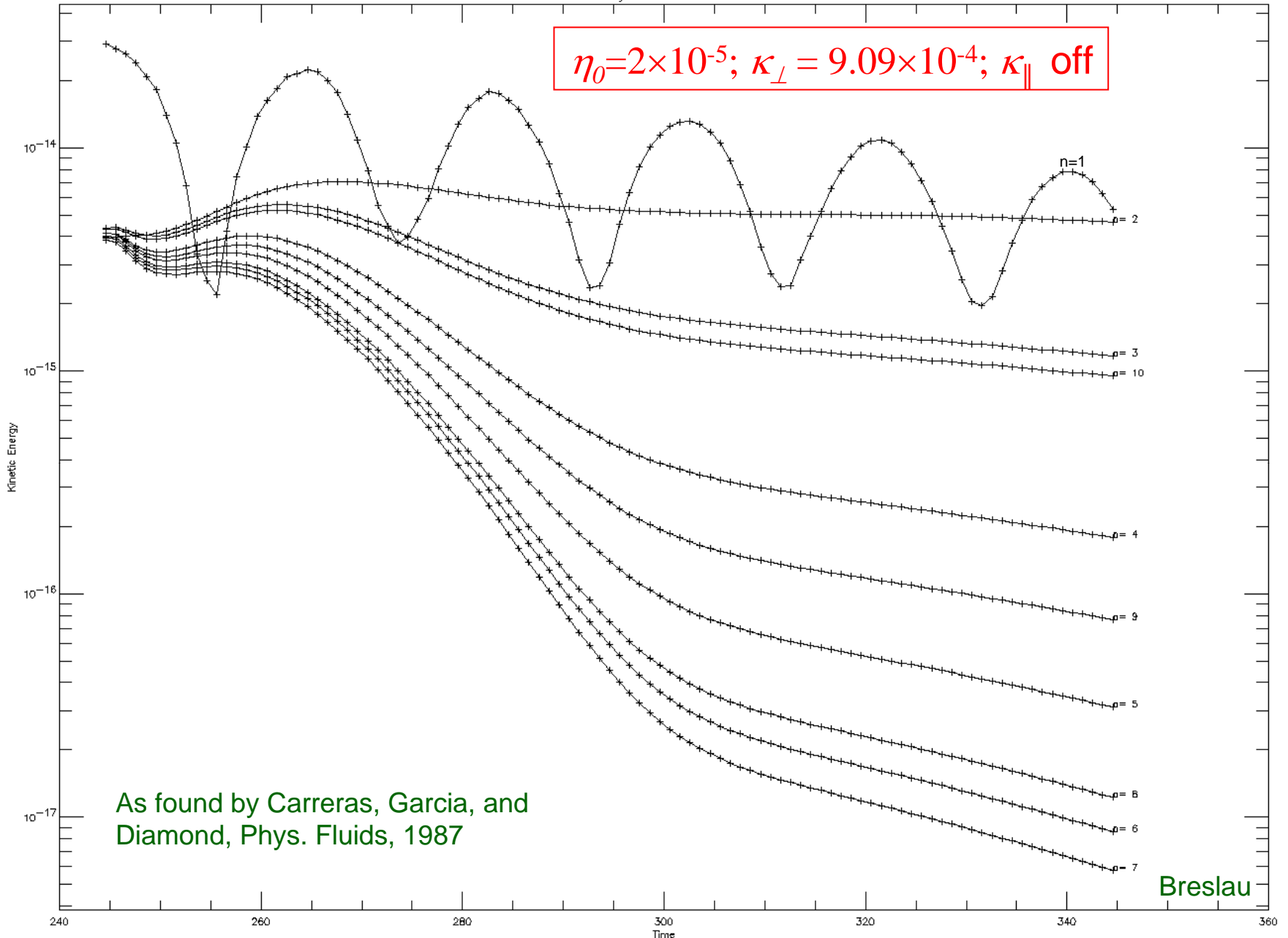
In Absence of Heat Conduction, Higher n Resistive Ballooning Modes are More Unstable than Internal Kink



High Perpendicular Heat Conduction Stabilizes All Resistive Ballooning Modes

By Mode Number

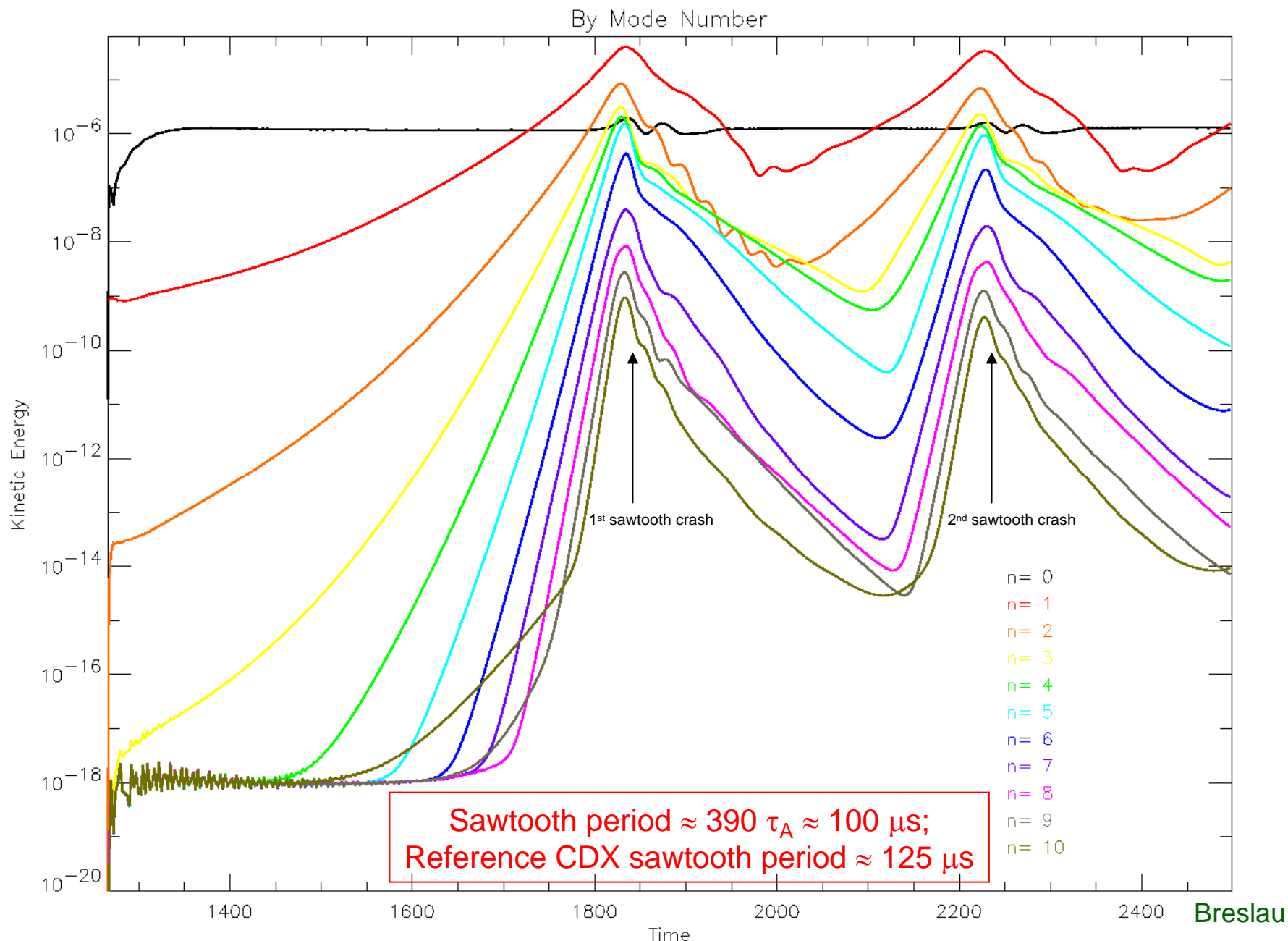
$$\eta_0 = 2 \times 10^{-5}; \kappa_{\perp} = 9.09 \times 10^{-4}; \kappa_{\parallel} \text{ off}$$



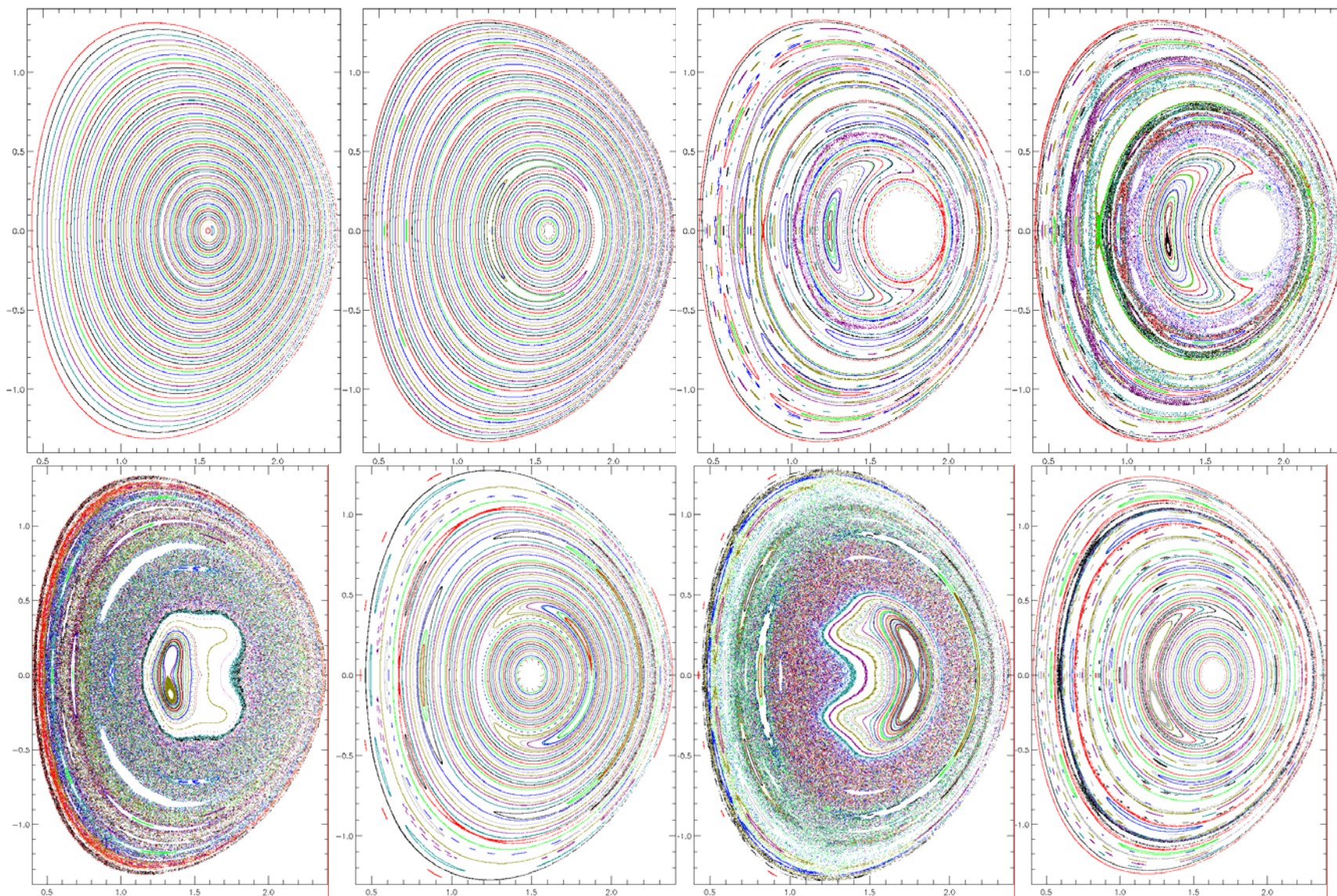
As found by Carreras, Garcia, and
Diamond, Phys. Fluids, 1987

Breslau

Nonlinear Evolution, Heat Conduction On



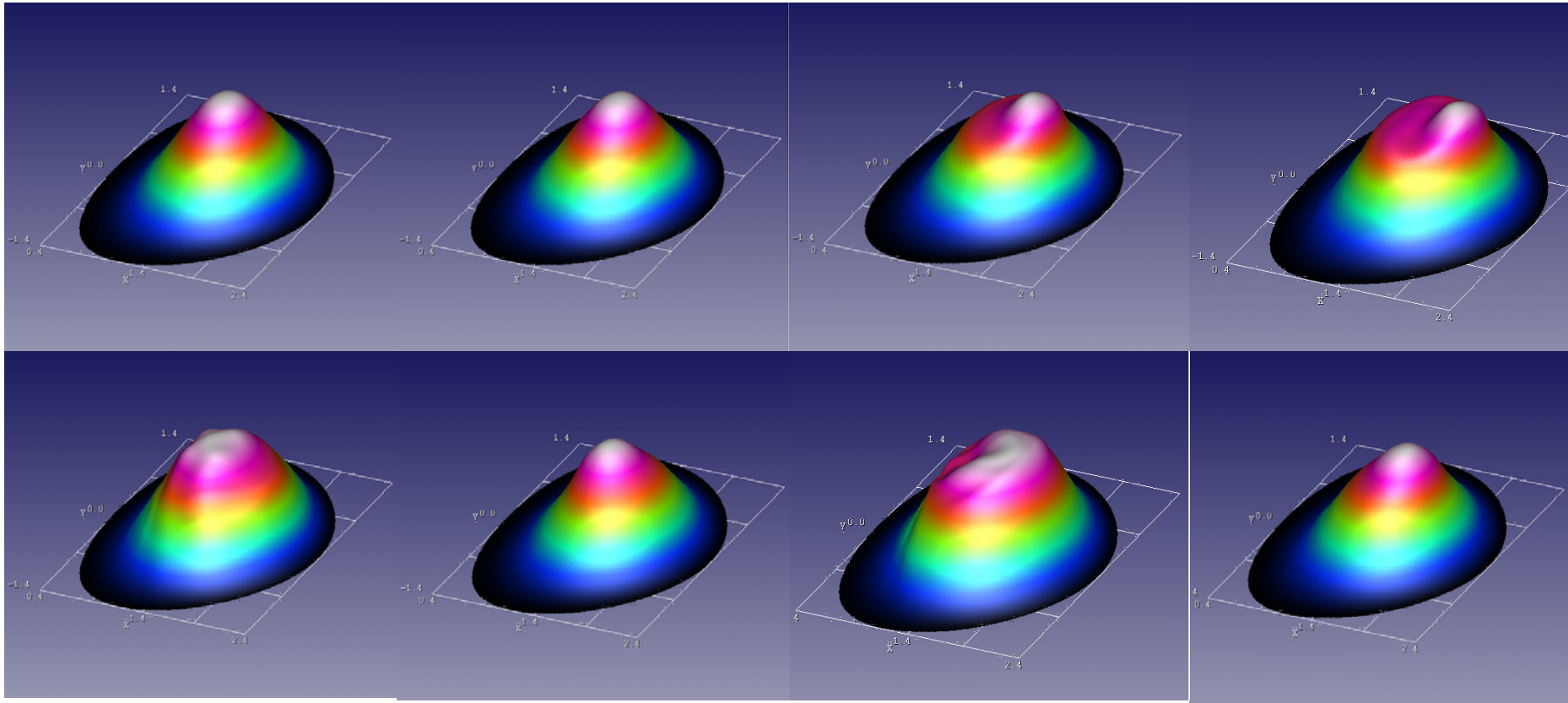
M3D field line plots during sawtooth cycles



After first crash

After second crash

Temperature profiles during CDX-U sawtooth crashes

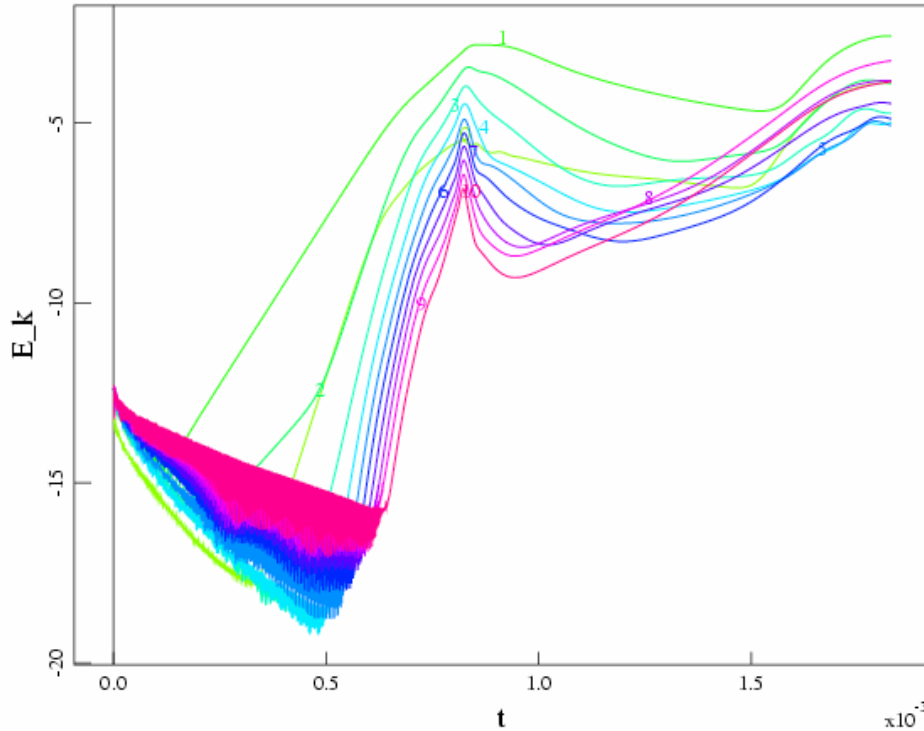


After first crash

After second crash

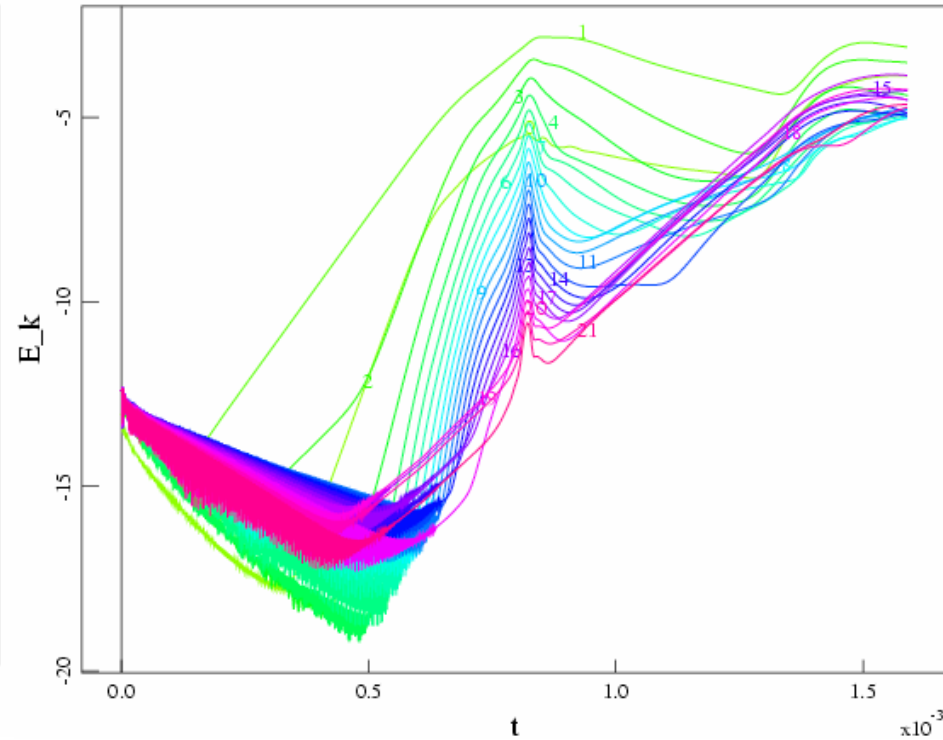
NIMROD Kinetic energy history

Kinetic Energy vs. t



11 modes

Kinetic Energy vs. t



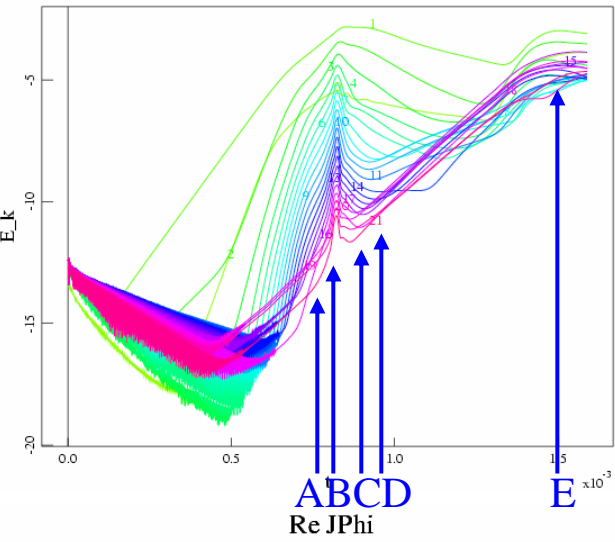
22 modes

- Same initial equilibrium as M3D: linear modes agree
- Large Anisotropic thermal conduction with $k_{\parallel}/k_{\perp}=10^8$
- Does not have experimental $k_{\perp}=200$ m²/s

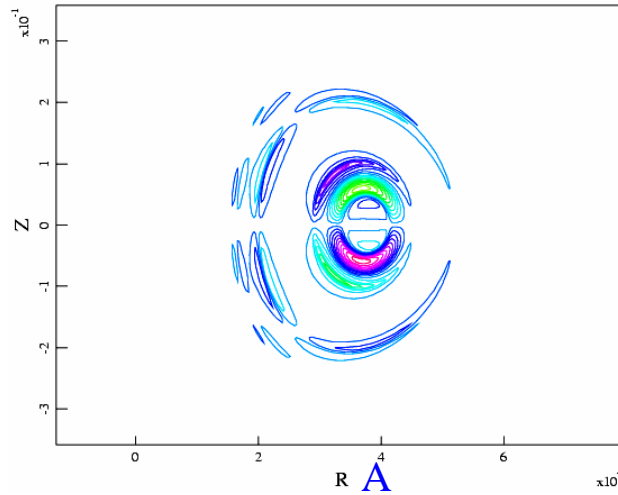
NIMROD n=1 current density

22 modes

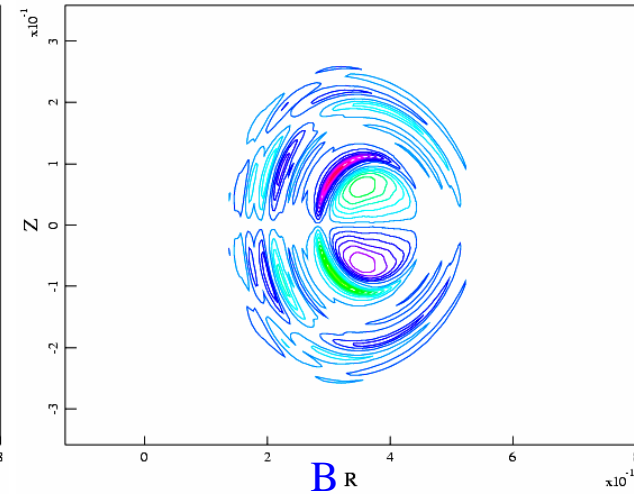
Kinetic Energy vs. t



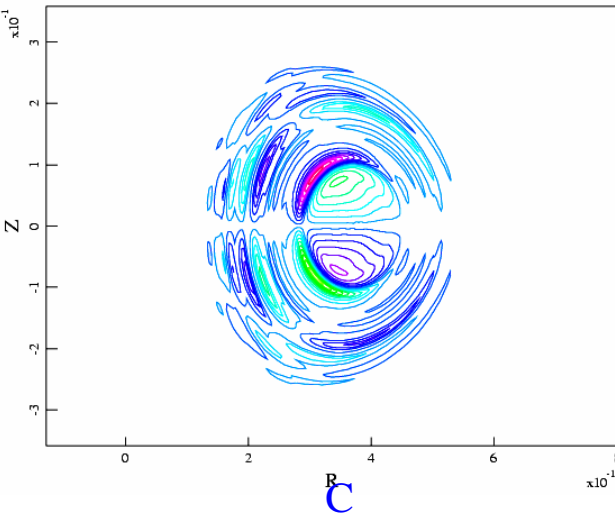
Re JPhi



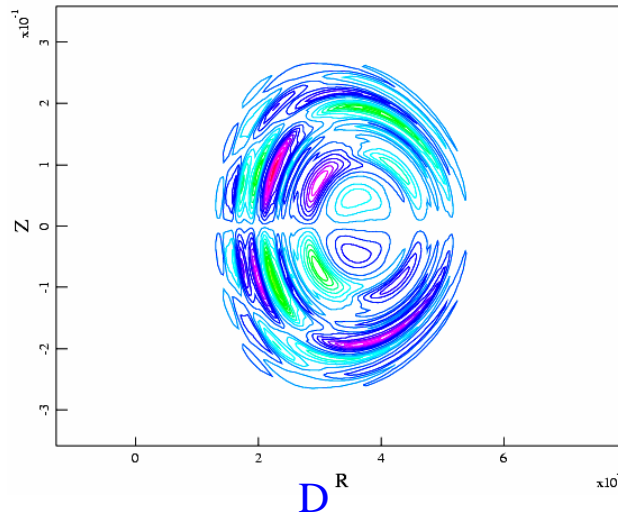
Re JPhi



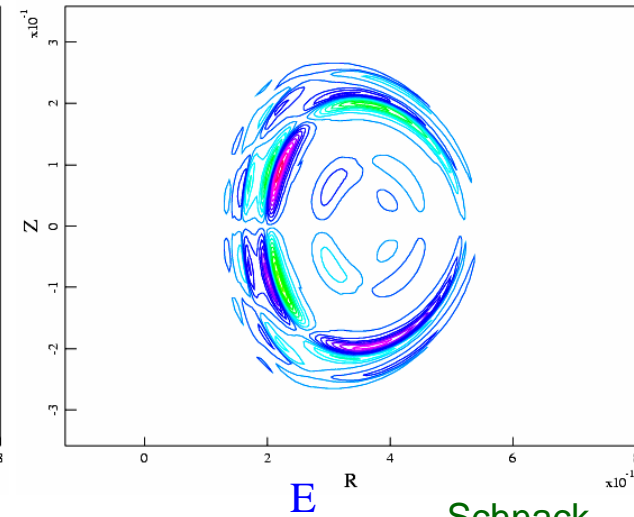
Re JPhi



Re JPhi

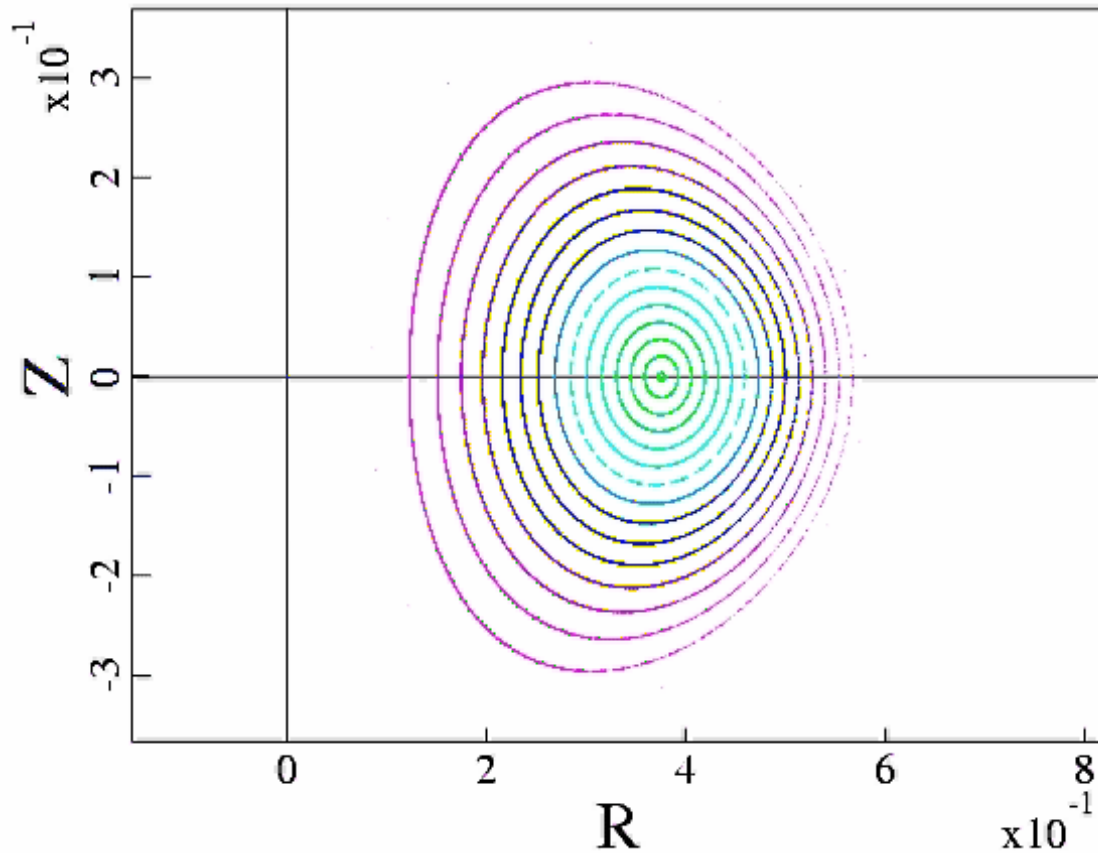


Re JPhi



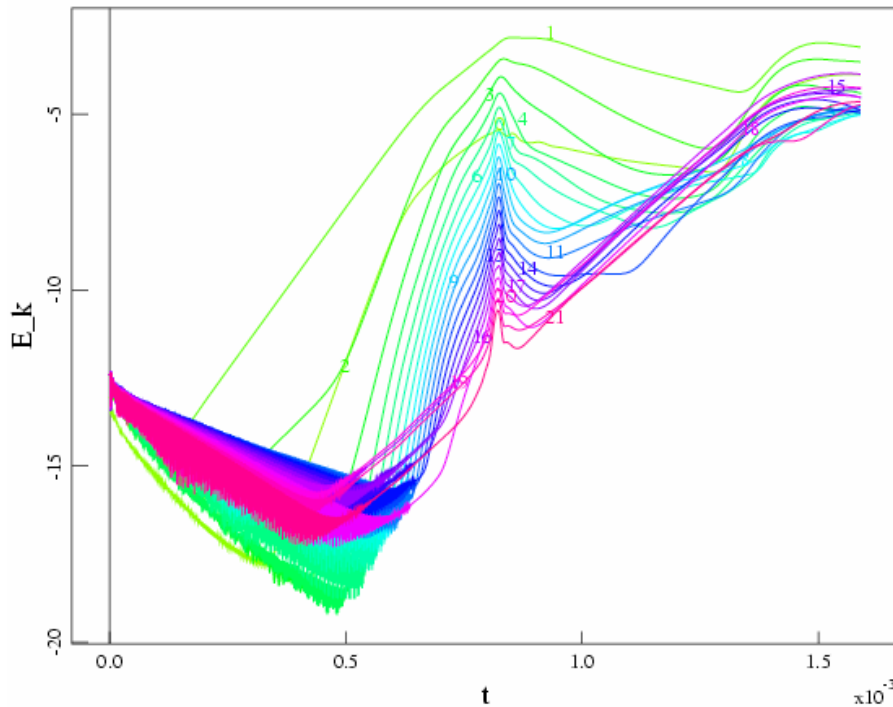
Poincare plots of NIMROD sawtooth cycle

Surface of Section

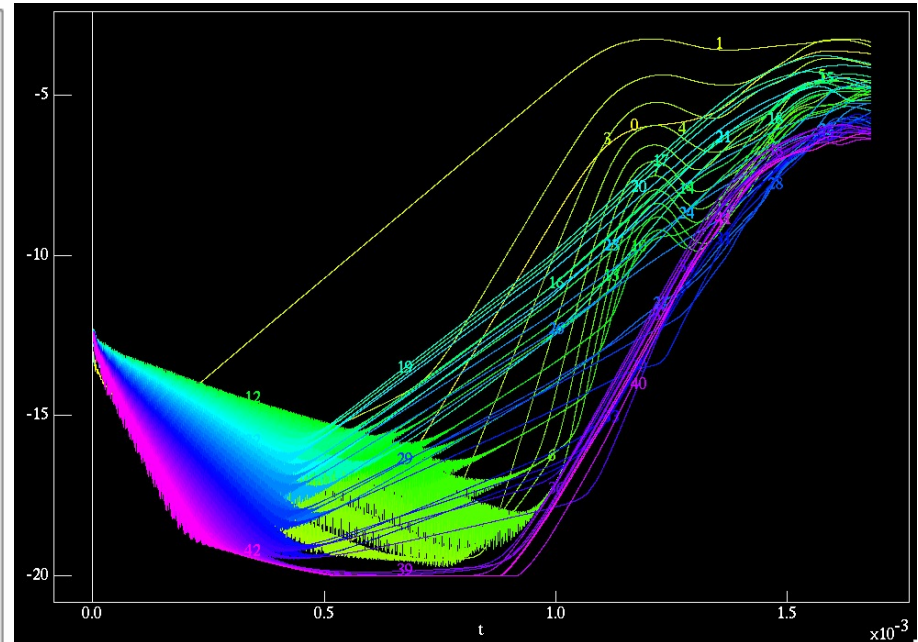


Calculation is being redone with 43 toroidal modes, and with $\kappa_{\perp}=200\text{m}^2/\text{s}$

Kinetic Energy vs. t



22 toroidal modes.



43 toroidal modes.

N=1 near full reconnection.

N=2-10 primarily nonlinearly driven

N=11-30 linearly unstable

N=31-43 nonlinearly driven

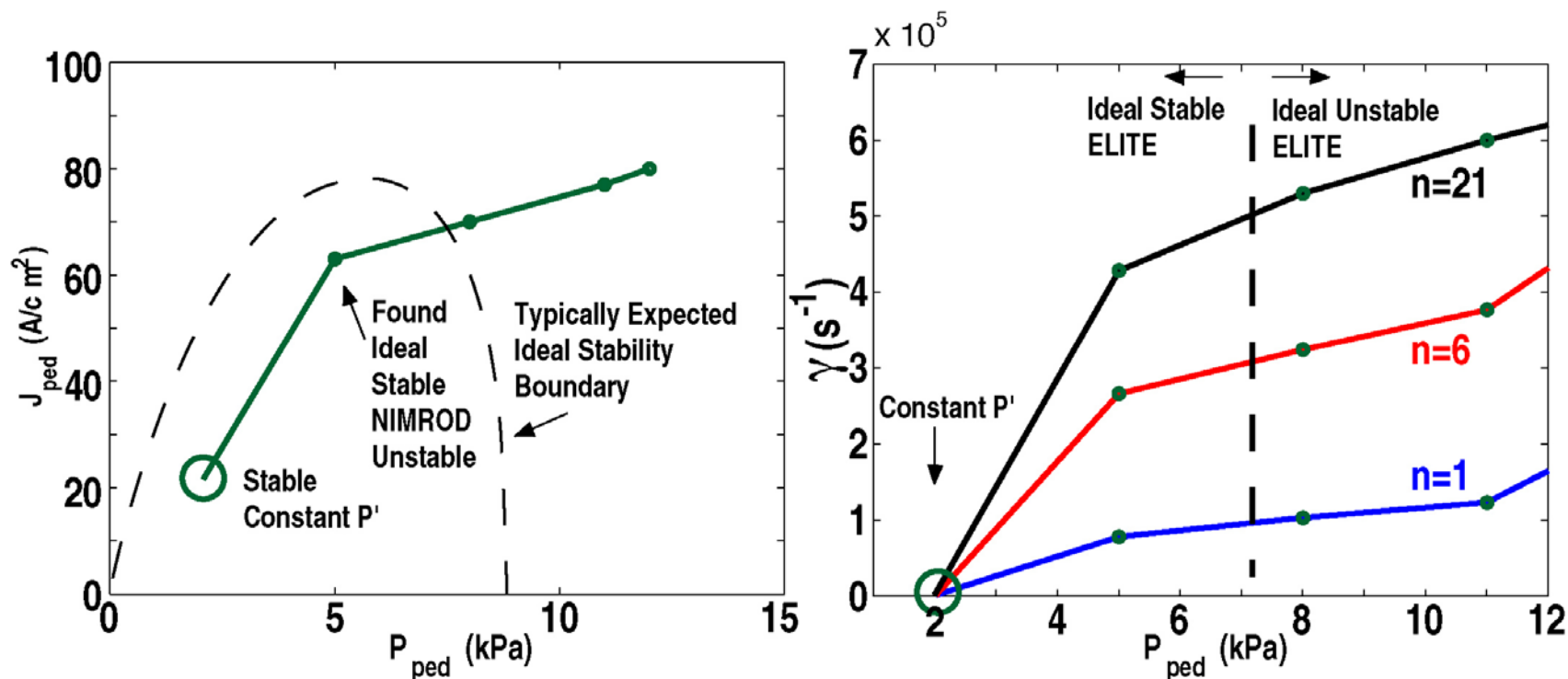
Conclusions of CDX-U Sawtooth Comparison

- Nonlinear MHD simulation with actual device parameters is capable of tracking evolution through repeated sawtooth reconnection cycles.
- M3D and NIMROD codes give same linear mode structures and growth rates, and qualitatively similar nonlinear behavior
- Quantitative comparisons with experimental data will require more careful attention to assumptions of the model.
 - Loop voltage (Ohmic) current drive in device vs. current source term in code.
 - Self-consistent Ohmic heating and evolving resistivity profile must be implemented.
 - Inclusion of two-fluid terms is likely to alter time and space scales of the sawtooth reconnection events.

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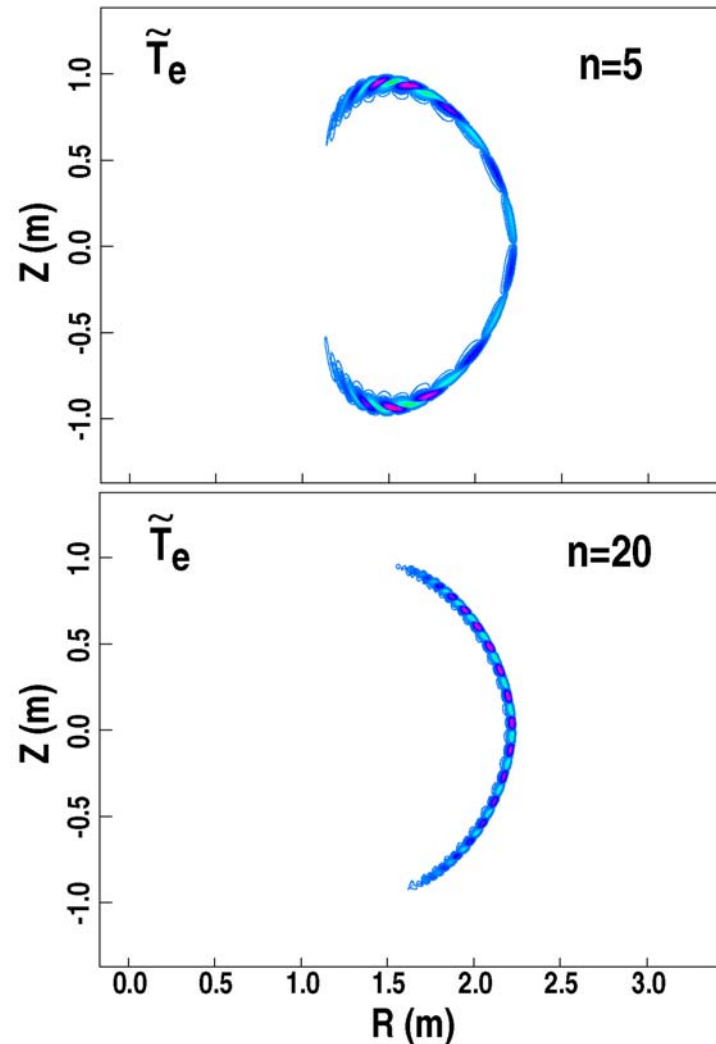
NIMROD has calculated linear and non-linear ELM evolution and compared with ELITE



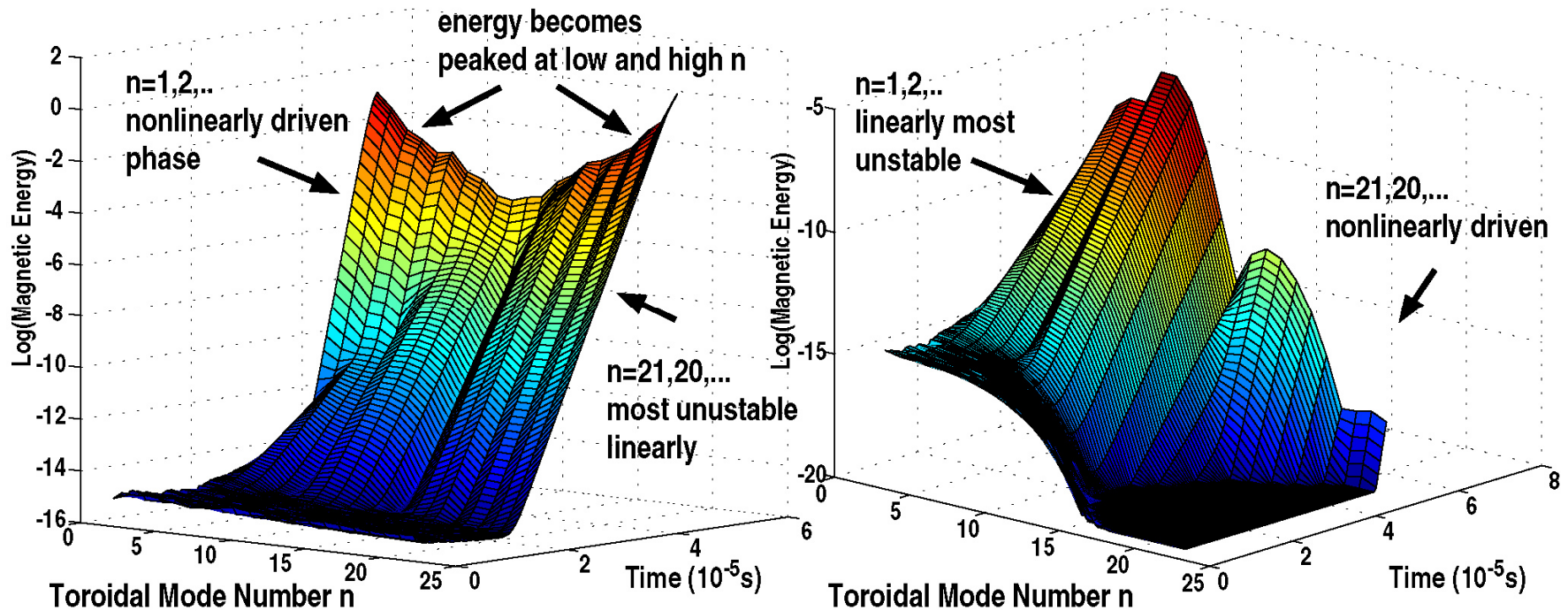
- NIMROD finds a “resistive” ELM unstable in the region ELITE finds stable
- Experiment resides near and crosses stability boundary during ELM cycle
- NIMROD → ELITE results when resistivity, viscosity → zero

Poloidal Eigenmode Distribution Varies with n

- Low n modes have structure peaking top and bottom
- High n modes peak outboard midplane
- These differences affect nonlinear evolution
- Good agreement with ELITE in mode structure



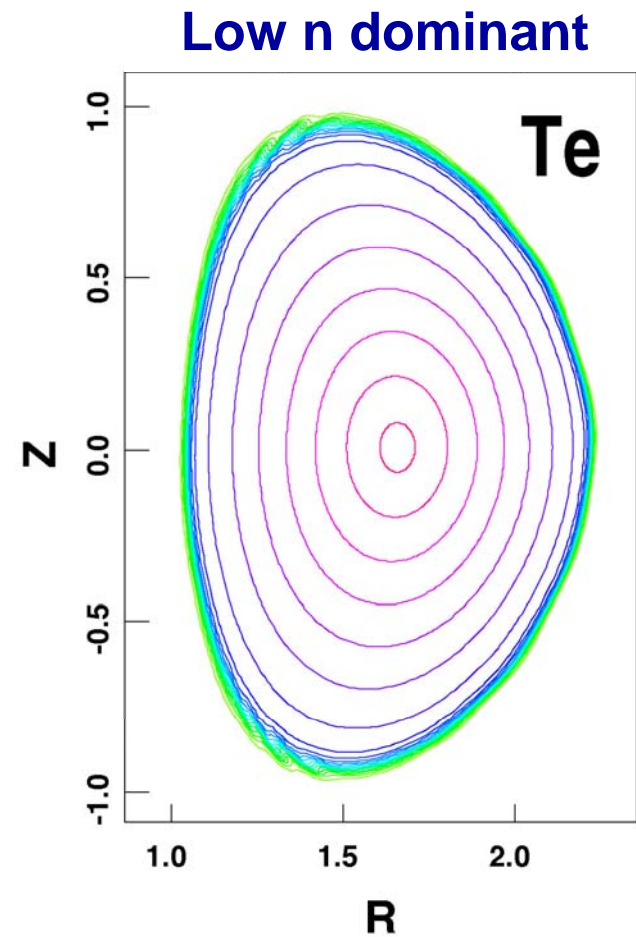
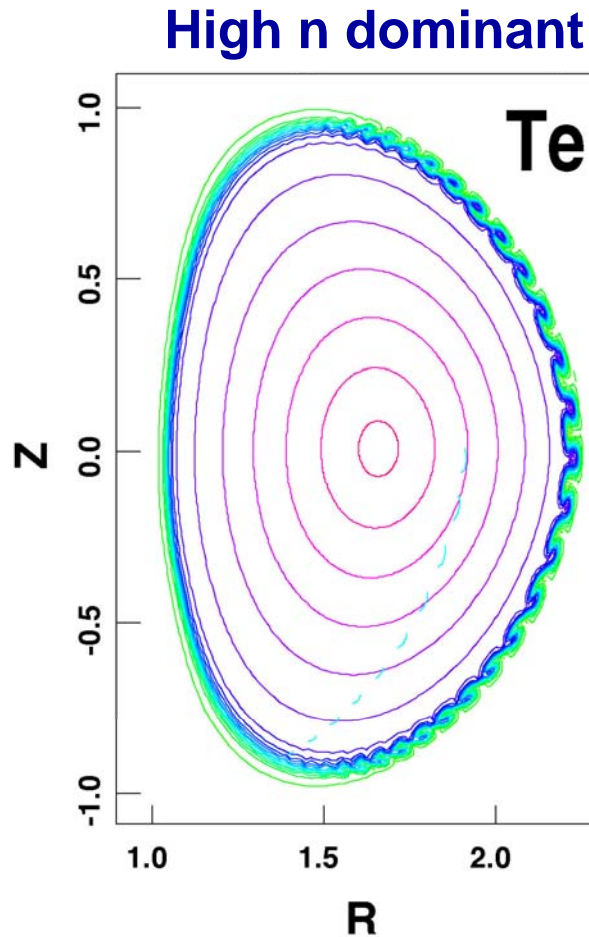
Nonlinear ELM Simulation



- ELM evolution depends sensitively on relative initial mode amplitudes
- Implies need for accurate determination of stability onset for each of the different modes.
- Note that if all modes are initialized at the same amplitude, the highest modes grow to the largest amplitude, and the calculation is not resolved...
 - indicates need for improved model at high-n and/or more resolution

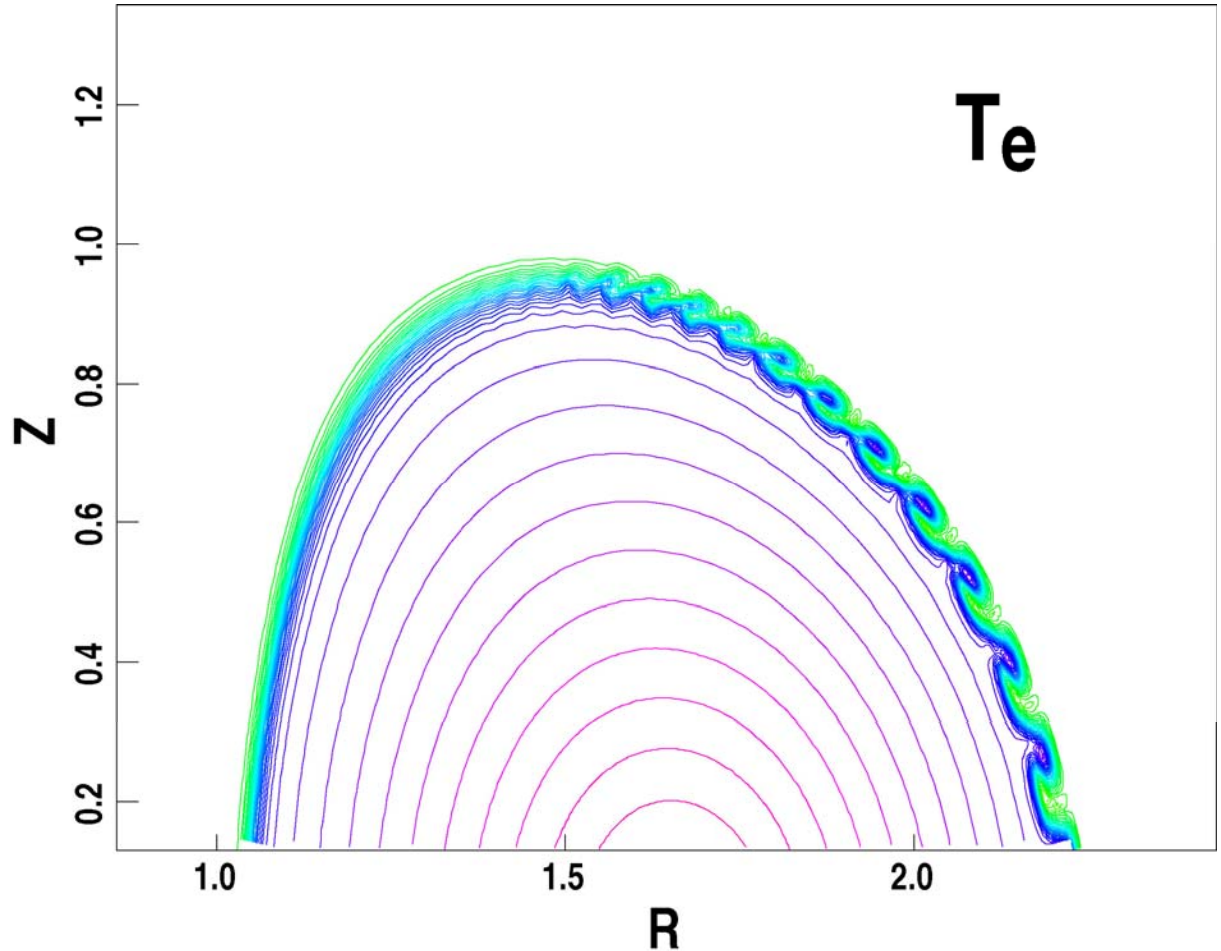
Resulting Nonlinear Perturbations Very Different Depending on Linear Spectrum

- With HIGH-n dominance, mode is peaked outboard midplane.
- With LOW-n dominance mode is peaked top and bottom



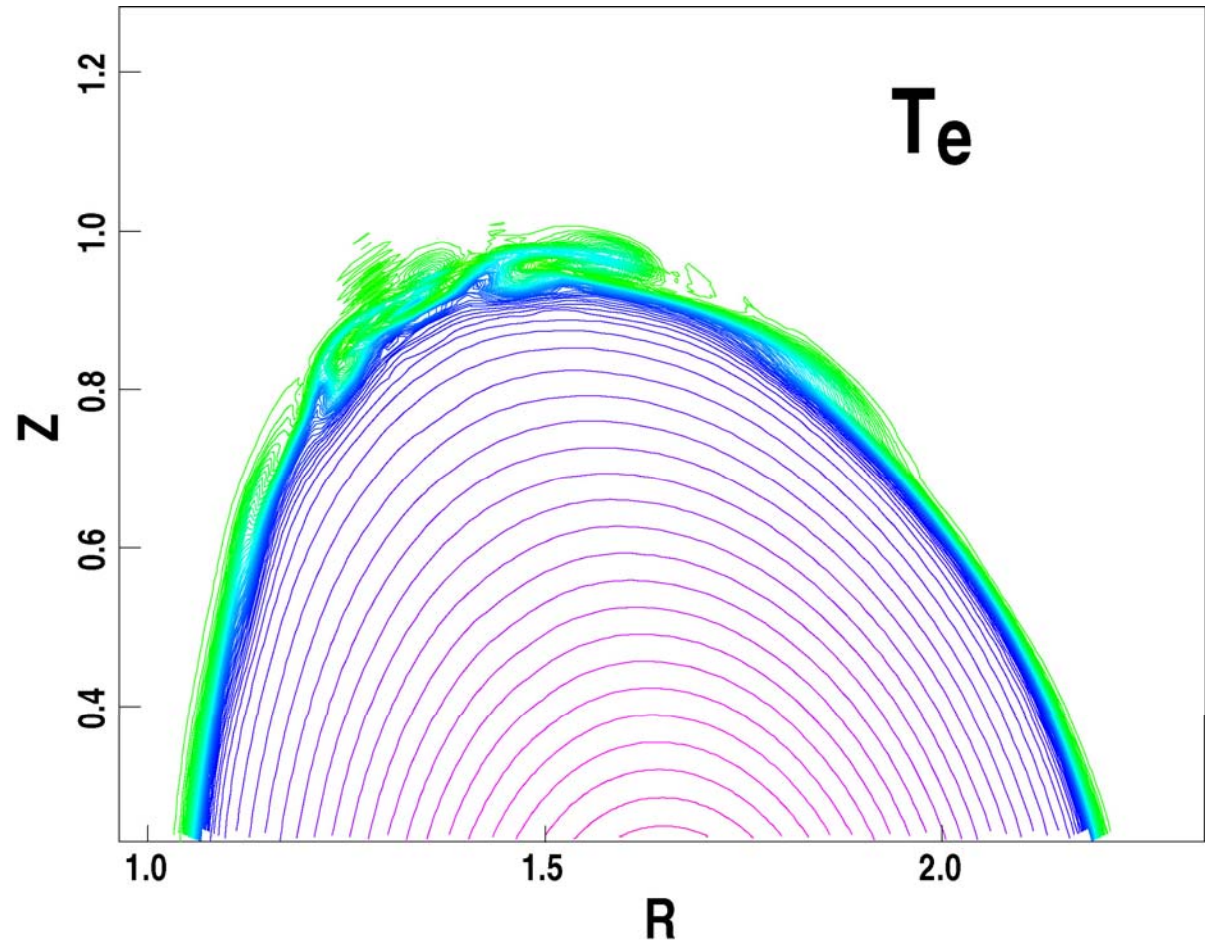
High- n dominated simulations show structure where high n linear modes peak

- The coupled modes form complex structures in flow velocity and Temperature, among other fields
- Areas of high temperature are seen flowing out and rotating, with blobs separating off on top and bottom



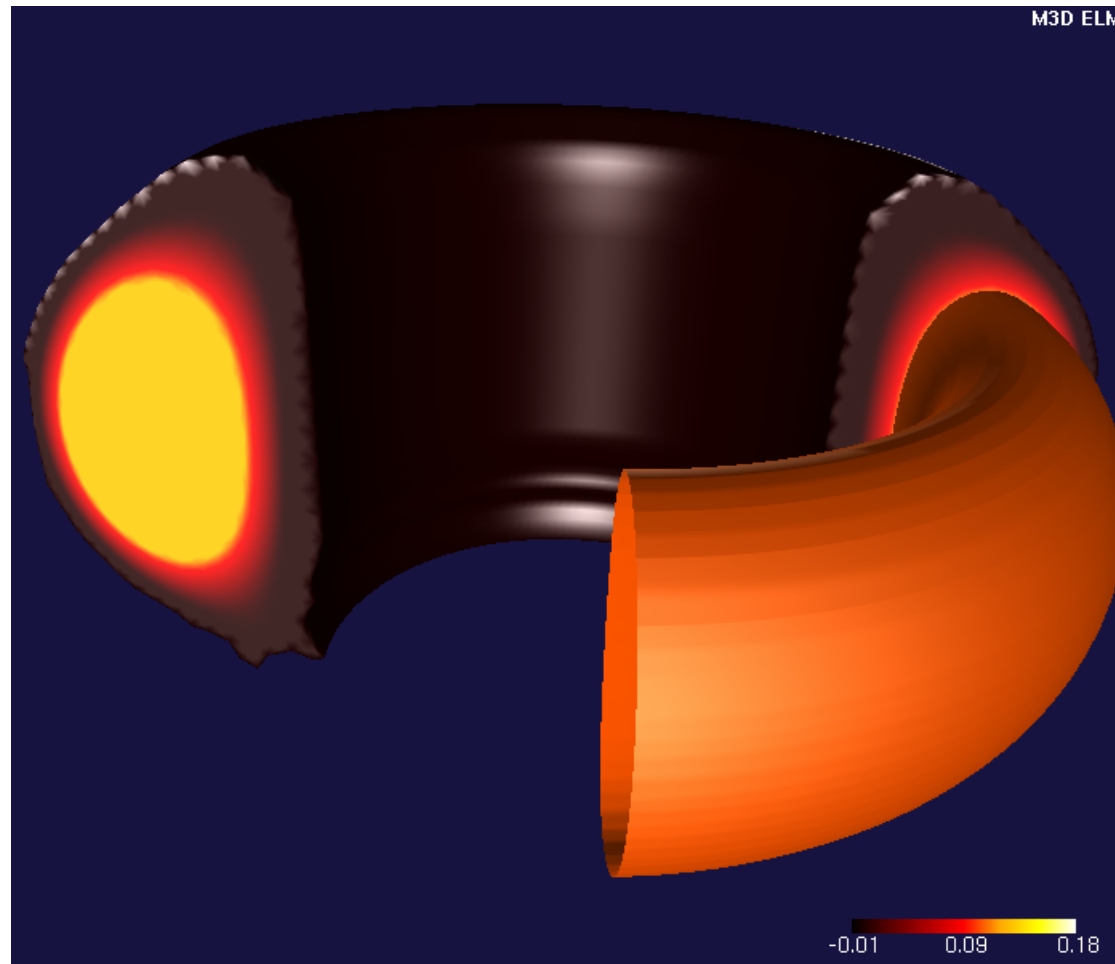
Low n dominated simulation shows structure where low-n linear modes peak

- Although low-n dominant, still challenging to simulate into late nonlinear phase.
- Short wavelength blob structures form and propagate radially and poloidally, slowing time advance



- Numerically challenging to accurately resolve short wavelength driven components late into the nonlinear phase

Nonlinear pressure evolution of an unstable ELM

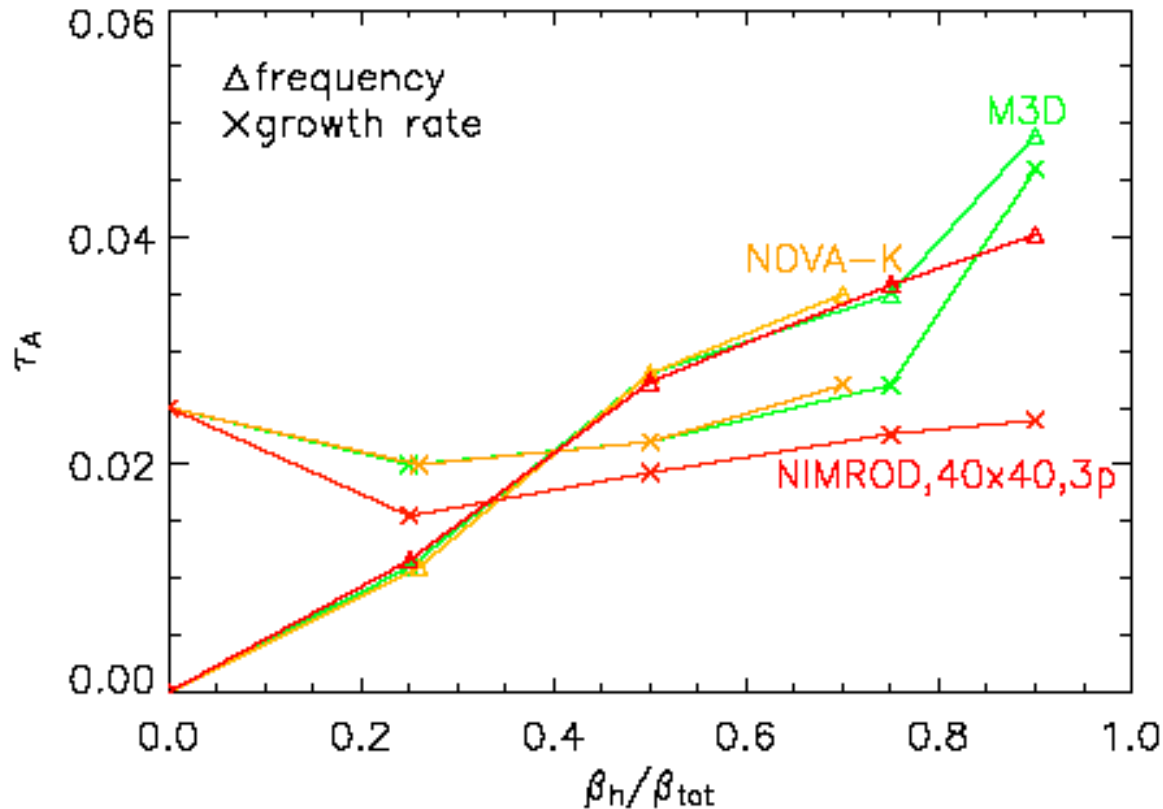


- M3D scoping runs were done with 16 planes, limited to $n < 8$. Uses 2nd order spectral finite elements.

Activity Areas

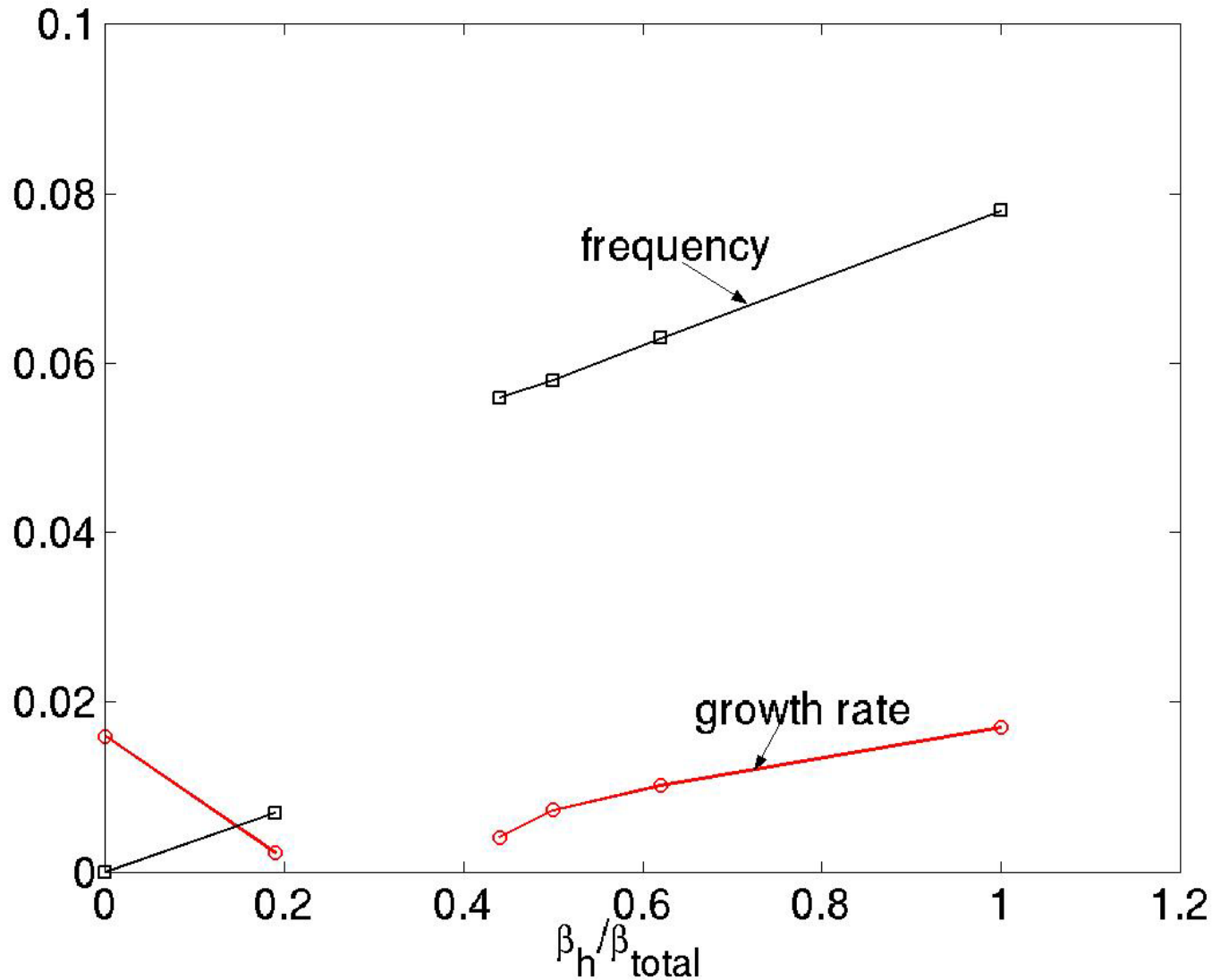
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NIMROD and M3D now agree for linear growth rate of energetic particle test case



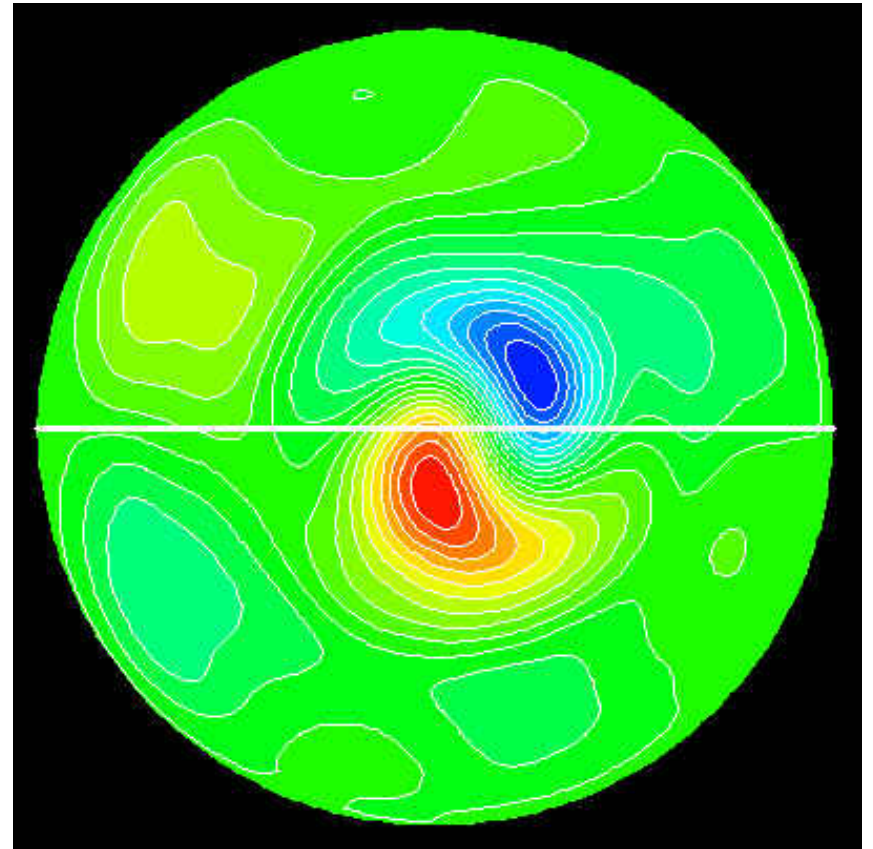
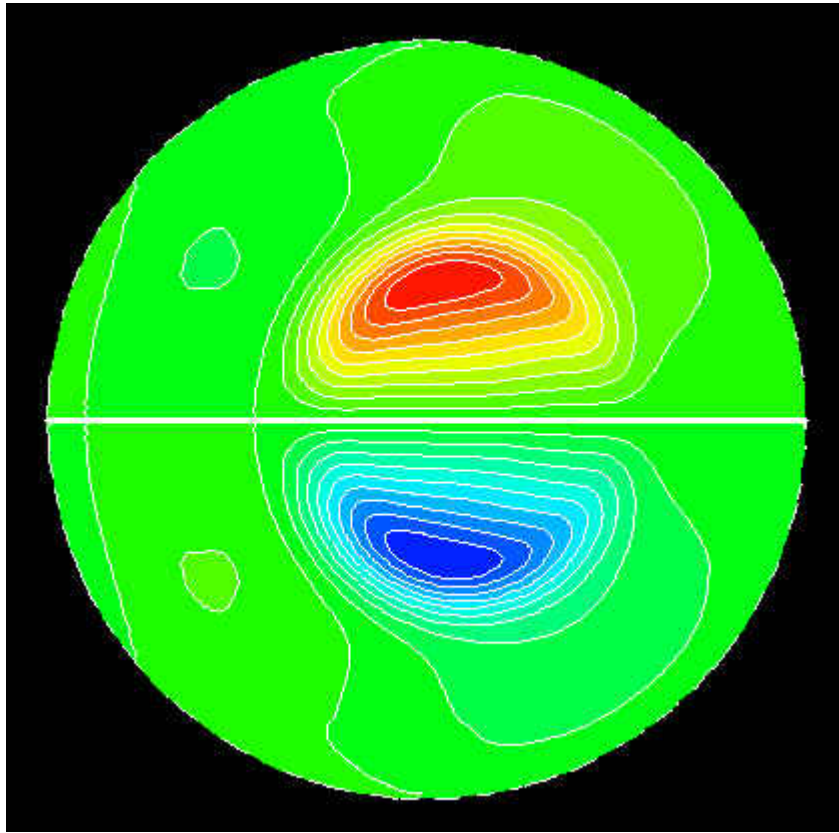
β_h varies at constant $\beta_T = \beta_h + \beta_P$

Excitation of Fishbone at high β_h

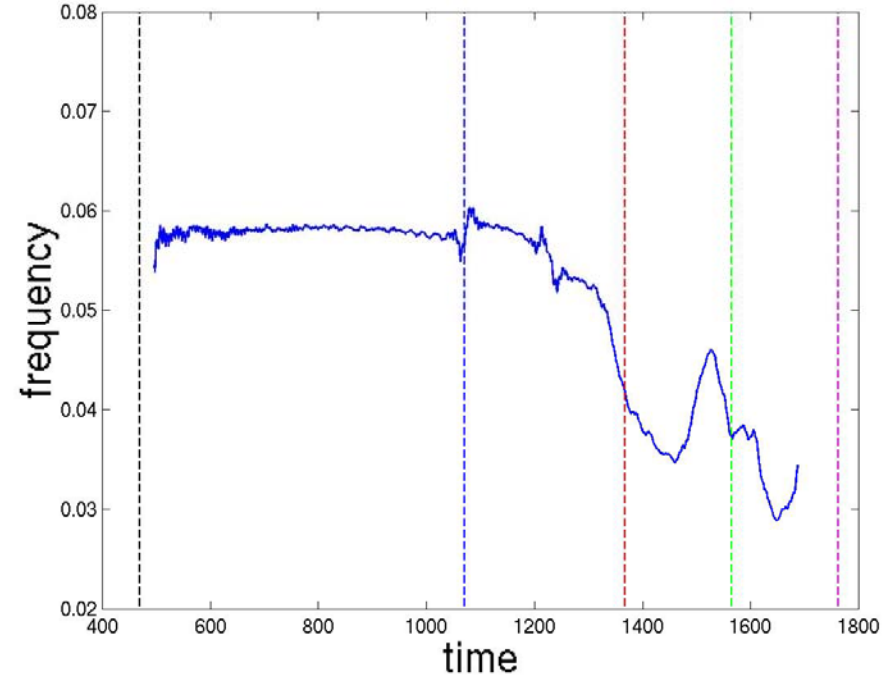
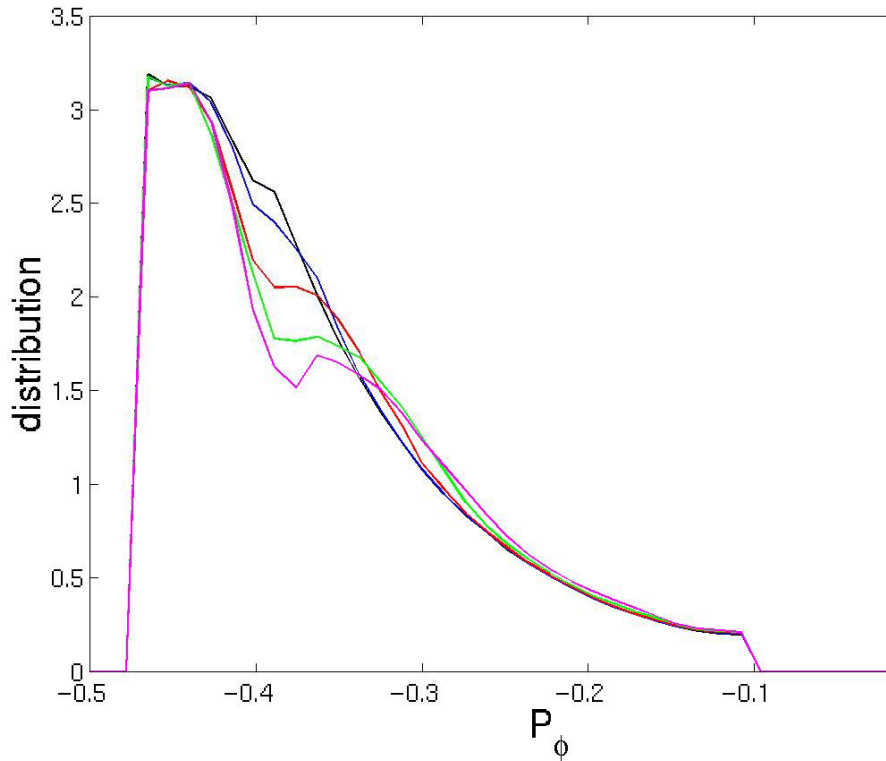


Circular
R/a=2.76
q(0)=0.9,
q(a)=2.5
 $\beta_-(0) = 5.7\%$

Mode Structure: Ideal Kink v.s. Fishbone

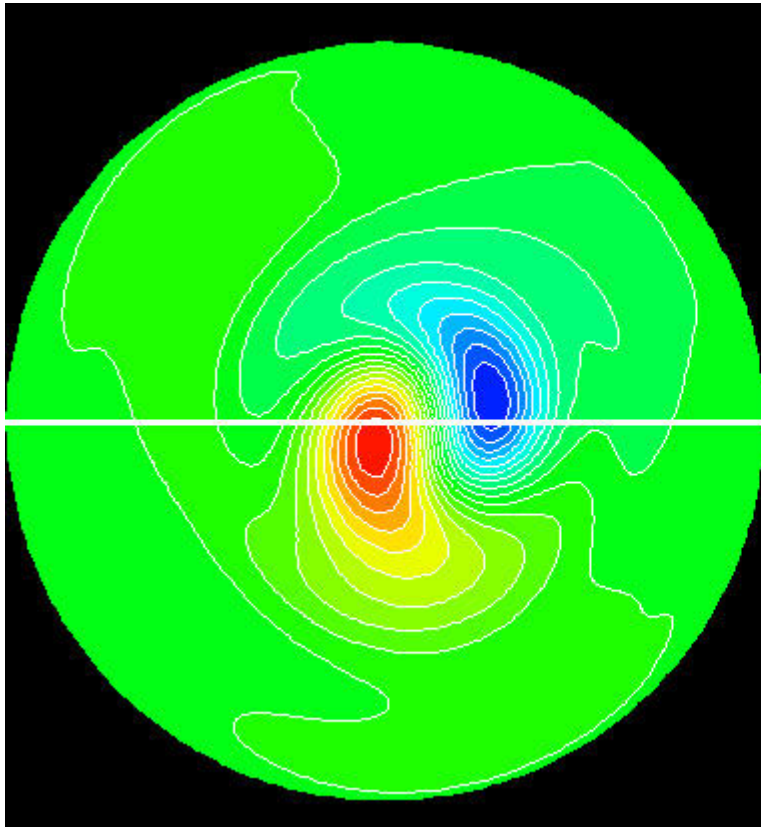


As flattening region of distribution function increases, the mode frequency chirps down.

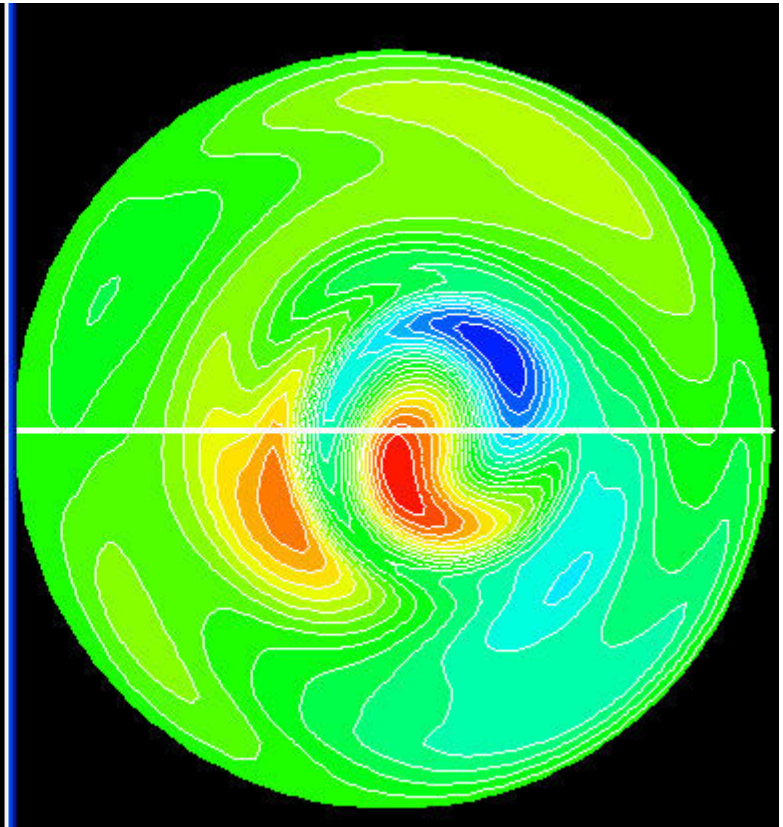


MHD nonlinearity changes mode structure significantly

Linear MHD



Nonlinear MHD



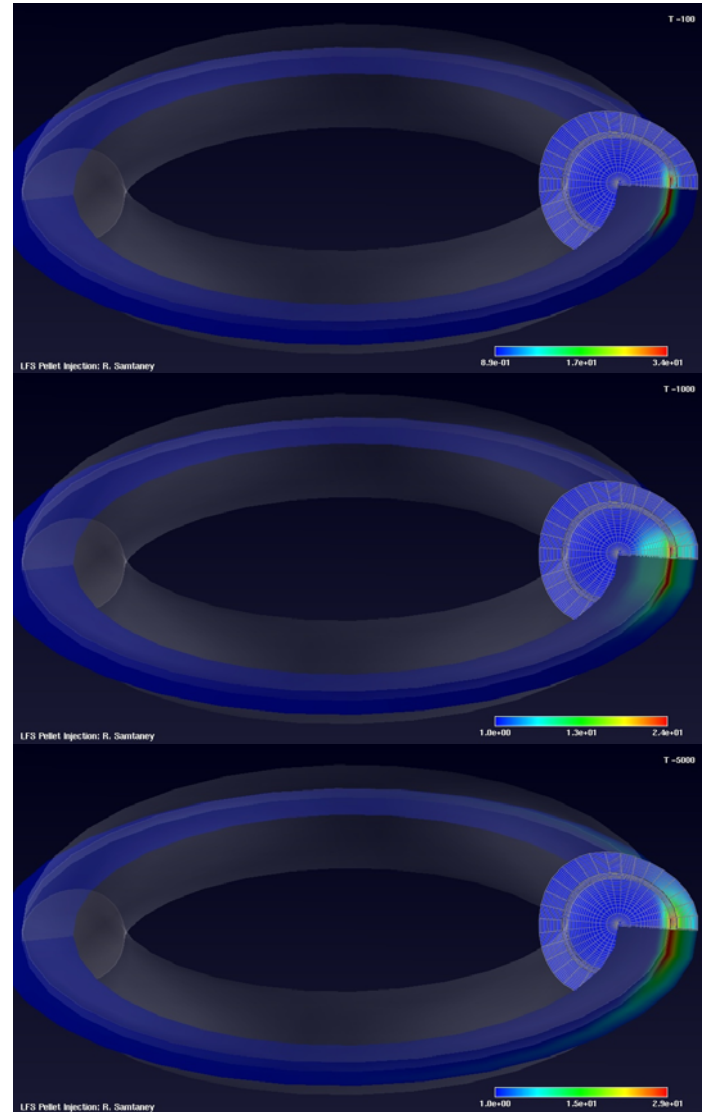
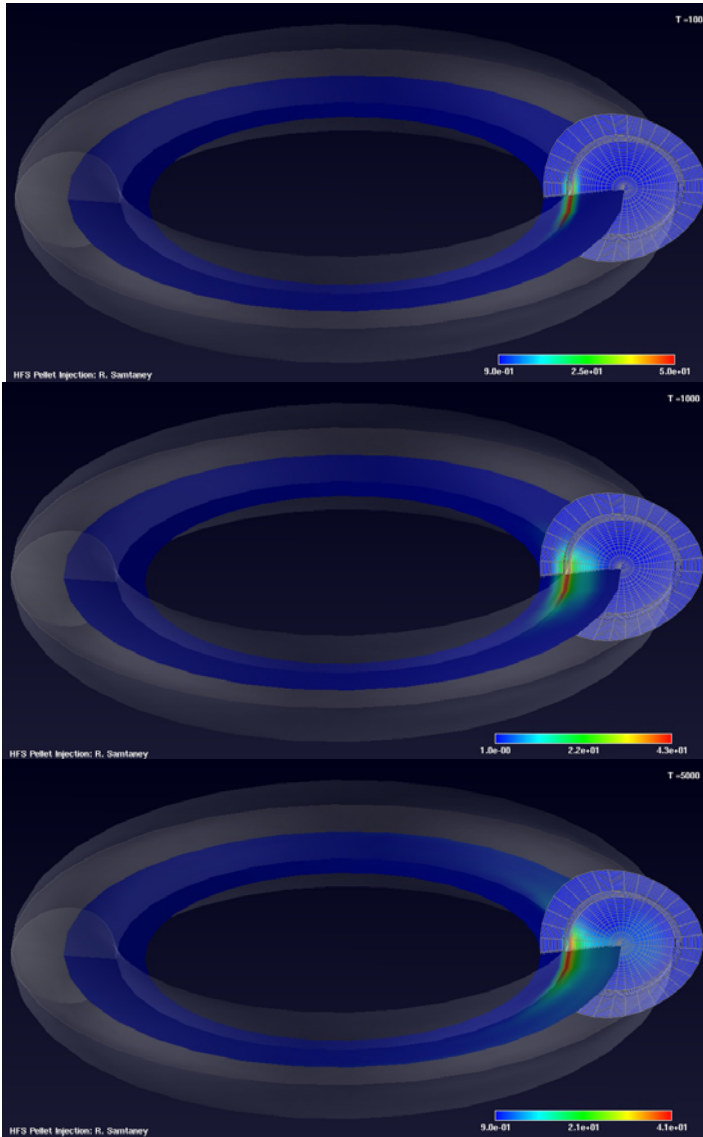
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AMR MHD Code: Recent Developments

- **We have implemented a non-orthogonal magnetic coordinate system in the AMR code**
 - Conservative finite volume upwind numerical method
 - The solenoidal condition on B is imposed using the *Central Difference* version of Constrained Transport (Toth JCP 161, 2000)
- **Handling of electron heat flux:**
 - Now have $\nabla_{\parallel} T=0$ (Equilibration of temperature on flux surface)
 - Electron heat flux model by Ishizaki, Parks et al. (Phys. Plasmas 2004) is currently being implemented
- **Initial Conditions:**
 - Initial state is an MHD equilibrium obtained from JSOLVER equilibrium code
 - Input equilibrium for finest level and compute the metric terms
- **Boundary Conditions:**
 - Perfectly conducting for $\xi=\xi_0$, zero flux (due to zero area) at $\xi=\xi_i$, and periodic in θ and ϕ
 - Implementation results in preservation of volume and face areas of hexahedra upon refinement or coarsening
- **Pellet Injection:**
 - Ablation model of Kuteev (Nucl. Fusion 1995) used.
 - Supersonic gas jet injection being looked at.

Pellet Injection: HFS vs LFS Launch



Density

R. Samtaney

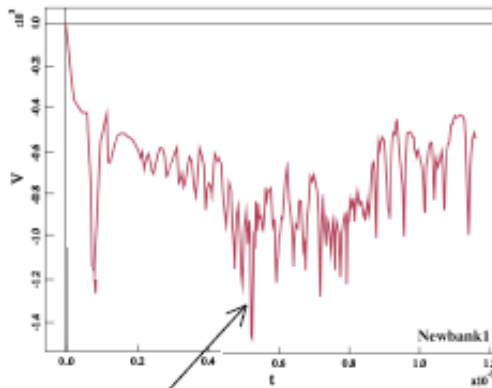
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Success in the modeling of SPX with NIMROD has led to the use of NIMROD to model a proposed capacitor bank upgrade

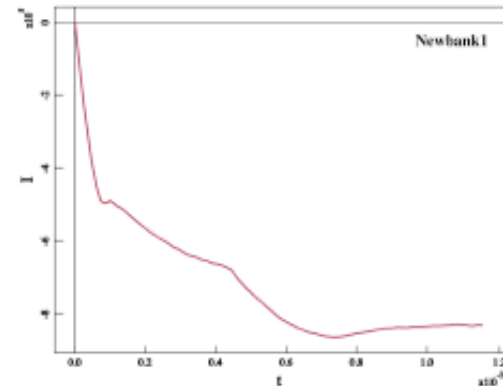
Gun voltage

Applied injector Voltage vs. t



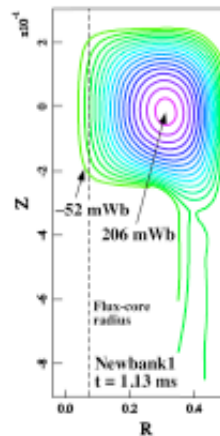
Gun current

Injector Current vs. t



Voltage spikes are generated by magnetic reconnection events

Poloidal flux



Azimuthally-averaged poloidal flux

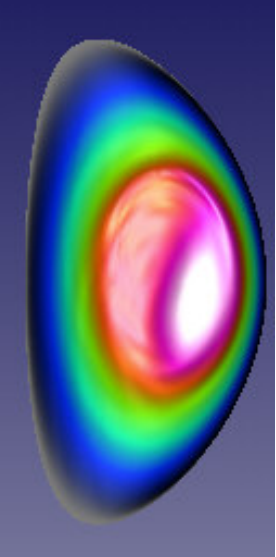
Azimuthally-averaged poloidal flux is developed during this process, and a good mean-field spheromak has been produced

(Poloidal flux shown at t = 1.13 ms)

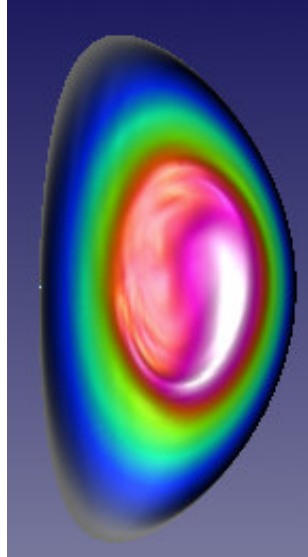
Detailed circuit equations included

Activity Areas

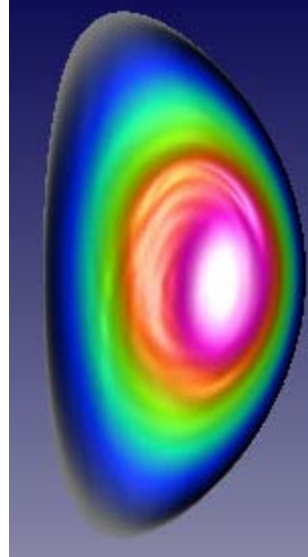
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MHD
 $M_A = + - 0.3$



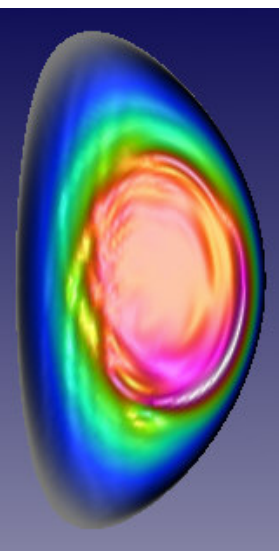
Counter 2Fluids
 $M_A = - 0.3$



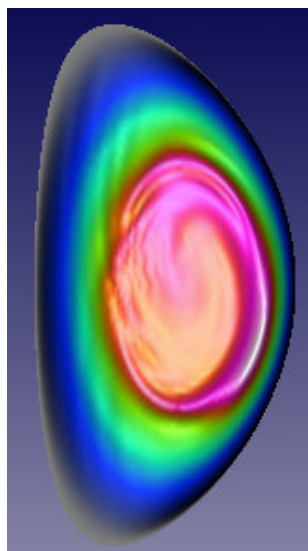
Co 2Fluids
 $M_A = + 0.3$

Temperature

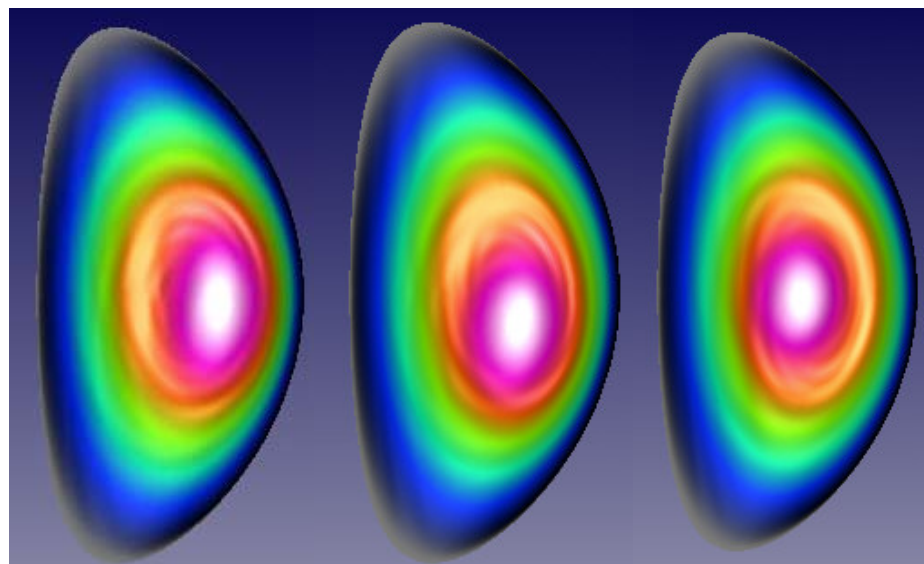
2-fluid modeling with strong toroidal rotation is in qualitative agreement with recent NSTX results: long-lived saturated $n=1$ mode with co-injection



Crash



Crash faster than MHD case



Saturation with hot spot pulled away from x-point

M3D simulations examining role of η_{plasma} and rotation

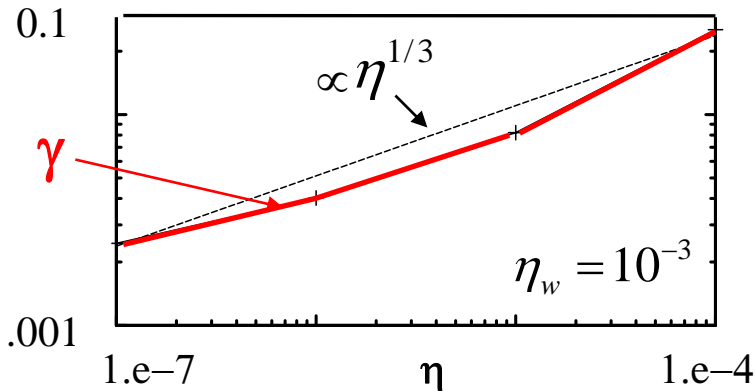
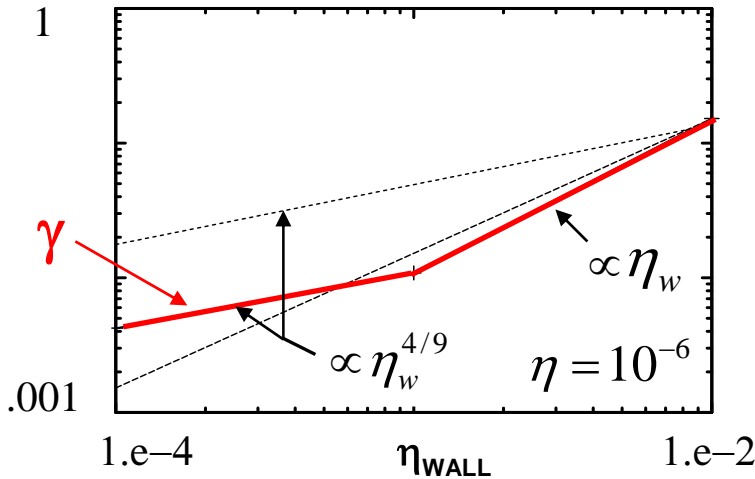


Resistive plasma / resistive wall mode
(RPRWM) growth rate scaling:

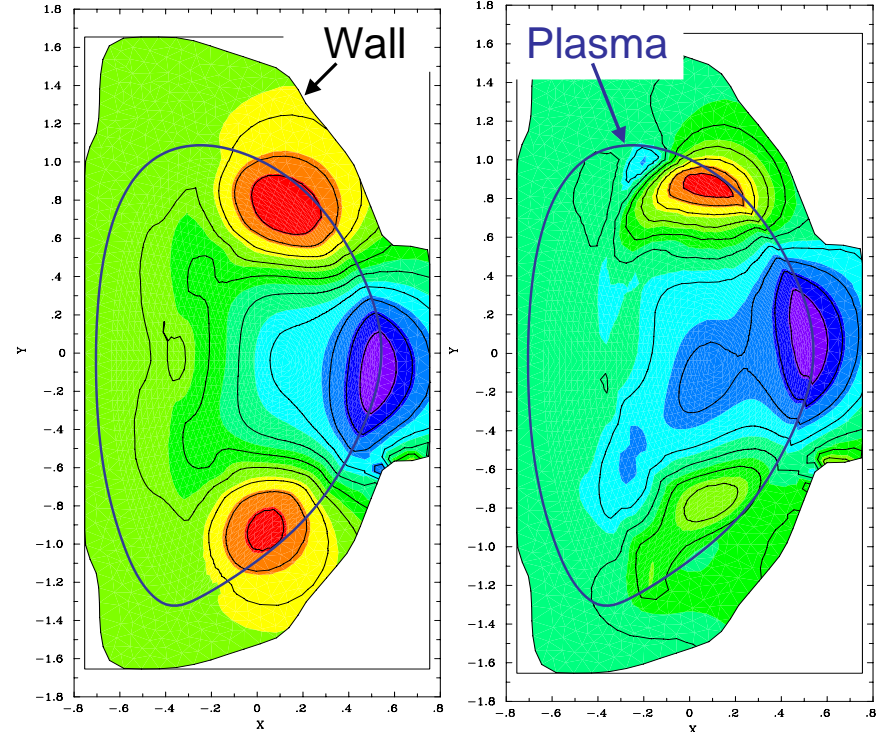
$$\gamma \sim \eta^{1/3} \eta_w^{4/9} \quad \text{similar to analytic scaling}$$

Finn 1995; Betti 1998

$$\beta_N = 5, q_0 = 1.7$$



RWM interacts w/ tearing / EM η -ballooning mode



Perturbed
Poloidal flux
at $\Omega = 0$

Saturates at
 $\Omega = 0.05 \frac{v_A}{R}$

w/ collisional viscosity

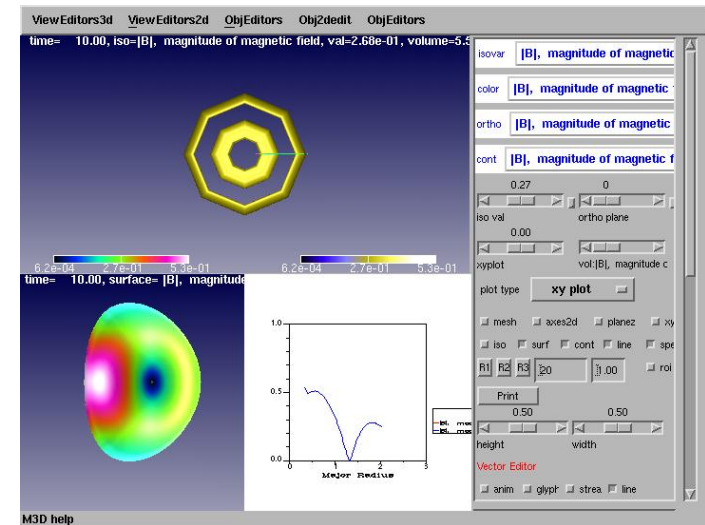
Better dissipation models needed

Activity Areas

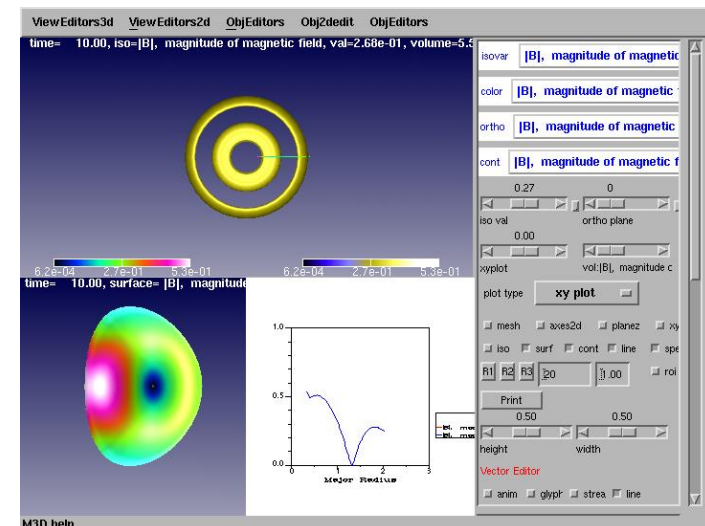
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CEMM Visualization highlights

- Made the Integrated Visualization Development Environment more robust.
- Improved user interface
- Support more platforms (Altix, 64-bit linux, 32-bit linux, windows, MAC).
 - drop down menus, scrollbars, better tick marks, more colormaps, ...)
- Multiple bug fixes
- New routines: toroidal geometry recognition, ...



Without toroidal geometry recognition

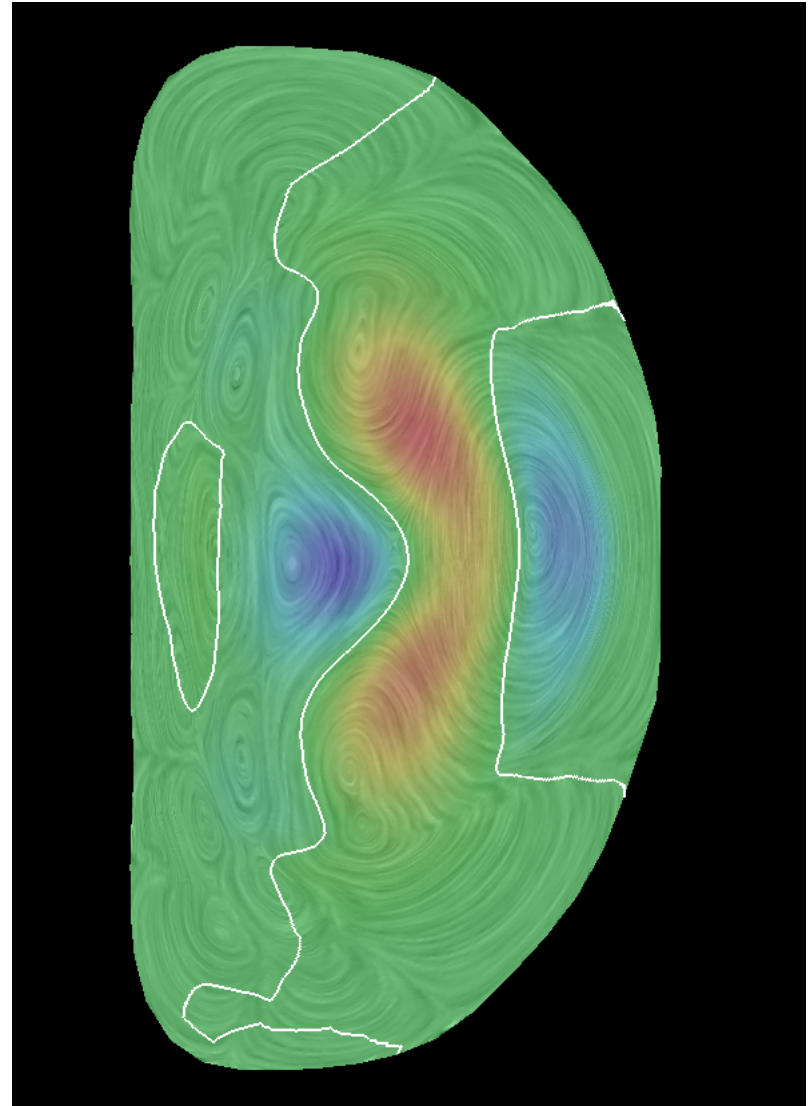


Advanced Viz. Research Topics

- Detection of critical points
 - (B Field and velocity).
 - Tracking of critical points
 - (B Field and velocity).
 - Detection of closed field lines
 - (B Field only).
-
- Tasked for completion at one per year.

Critical Points - Plasma Velocity

- LIC - Line Integral Convolution in the plane shows the swirling nature of the flow.
- Color mapping shows the flow into (red) and out of (blue) the plane.
- White contours are locations where the flow is solely in the plane.



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- 2-fluid NSTX modeling
- Visualization
- Misc.

Other Activities

TSTT Collaboration:

- Working with the SCOREC Center at RPI to interface an adaptive meshing algorithm with the M3D-C¹ code

A. Bauer, M. Sheppard

TOPS Collaboration:

- Have sped up M3D by a factor of 2 by further analysis of the 13 sparse matrix solves that are performed each time step.
 - Different operators and boundary conditions
 - Now use different methods on different equations:
 - Conjugate gradient with Jacobi preconditioner
 - Conjugate gradient with hypre (multi-grid) preconditioner
 - GMRES with ILU preconditioner

Mark Adams, Jin Chen, David Keyes

Future Activities

- Closure workshops and activities
 - Summer 2-day closure meeting attached to NIMROD meeting
 - Expanded (1 ½ day) pre-APS CEMM meeting
 - Larger workshop Spring 2006
 - Goal is to identify sequence of test problems
- Working towards burning plasma problems
 - 7 critical problems identified that are of interest to ITER
 - (sawtooth, NTM, RWM, EPM, ELM, VDE, fueling)
- Improve infrastructure
 - Further expand common visualization packages
 - Unified data management system
- Integration Activities
 - Integrated calculation with RF group
 - Hybrid calculation of neoclassical closures
 - Interaction with Edge FII