

# Computation of Outer Region Matching Data for Resistive Instabilities with DCON

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Alan H. Glasser  
PSI Center, University of Washington

Zhirui Wang and Jong-Kyu Park  
Princeton Plasma Physics Laboratory

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# Application of DCON to Resistive Instabilities

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- DCON is widely used for computing the ideal MHD stability of axisymmetric toroidal plasmas.
- It is thoroughly verified and validated, robust, reliable, easy to use.
- It has also been applied to determination of ideal region matching conditions for resistive and related singular modes,  $\Delta'$ -like quantities. But despite many efforts, the matching data are noisy and unreliable.
- The cause of this problem has recently been identified: the method used is similar to a shooting method, and is subject to a numerical instability.
- We are replacing this with the method of Pletzer & Dewar, using a Galerkin basis function expansion to discretize the  $\psi$  dimension and compute the matching data by linear system solution.
- The new method makes extensive use of the existing DCON code.



# Ideal DCON

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- Axisymmetric toroidal plasma, linear ideal MHD perturbations: 2D PDE.
  - Previous codes, *e.g.* PEST, ERATO, GATO: expand in 2D basis functions, convert to large matrix eigenvalue problem.
  - Problems: resolution near singular surfaces and separatrix, slow convergence, excessive human and computer time.
  - Newcomb, 1960: marginal ideal internal stability of cylindrical plasma reduced to numerical solution of 2nd-order ODE, initial value problem, crossing condition.
  - DCON: generalization of Newcomb to axisymmetric toroidal plasma, numerical solution of 2M-order ODE. 5 seconds on a fast workstation for toroidal mode number  $n=1$ , high  $\beta$ , tight aspect ratio, separatrix.
- Extension to free-boundary modes, plasma + vacuum, Morrell Chance.
- Interfaces to 28 Grad-Shafranov solvers, both direct and inverse, fit to bicubic splines.
- Reports equilibrium properties, Mercier & high- $n$  ballooning stability, fixed and free boundary ideal MHD modes.
- Widely used around the world, extensively verified and validated.



# Formulation of Ideal MHD DCON

## Ideal MHD Energy Principle

$$\delta W = \frac{1}{2} \int_{\Omega} dx [Q^2 + \mathbf{J} \cdot \xi \times \mathbf{Q} + (\xi \cdot \nabla P)(\nabla \cdot \xi) + \gamma P(\nabla \cdot \xi)^2]$$

## Fourier Representation

$$\xi \cdot \nabla \psi(\psi, \theta, \zeta) = \sum_{m=m_{\text{low}}}^{m_{\text{high}}} \xi_m(\psi) e^{i(m\theta - n\zeta)}$$

$$\Xi(\psi) \equiv \{\xi_m(\psi) \mid m \in [m_{\text{min}}, m_{\text{max}}]\}$$

## Euler-Lagrange Equation

$$\delta W = \frac{1}{2} \int_0^1 d\psi [\Xi'^{\dagger} \mathbf{F} \Xi' + \Xi'^{\dagger} \mathbf{K} \Xi + \Xi^{\dagger} \mathbf{K}^{\dagger} \Xi' + \Xi^{\dagger} \mathbf{G} \Xi]$$

$$\mathbf{L} \Xi = -(\mathbf{F} \Xi' + \mathbf{K} \Xi)' + (\mathbf{K}^{\dagger} \Xi' + \mathbf{G} \Xi) = 0$$

## Ordinary Differential Equation

$$\mathbf{u} = \begin{pmatrix} \Xi \\ \mathbf{F} \Xi' + \mathbf{K} \Xi \end{pmatrix}, \quad \mathbf{M} = \begin{pmatrix} -\mathbf{F}^{-1} \mathbf{K} & \mathbf{F}^{-1} \\ \mathbf{G} - \mathbf{K}^{\dagger} \mathbf{F}^{-1} \mathbf{K} & \mathbf{K}^{\dagger} \mathbf{F}^{-1} \end{pmatrix}, \quad \mathbf{u}' = \mathbf{M} \mathbf{u}$$

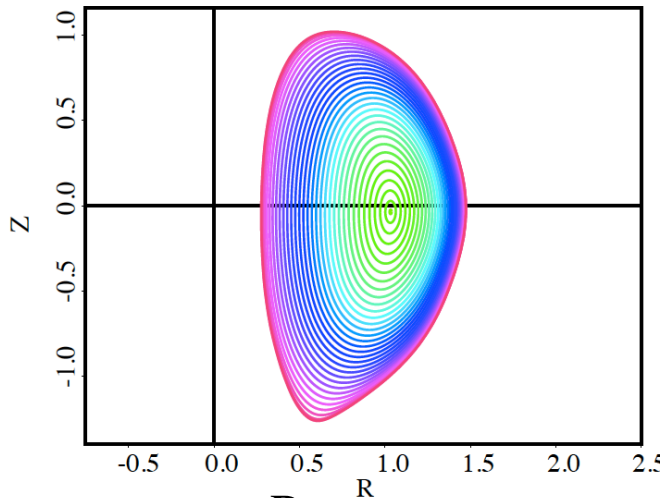
Glasser, Resistive DCON, CEMM/Sherwood 2013 Slide 3



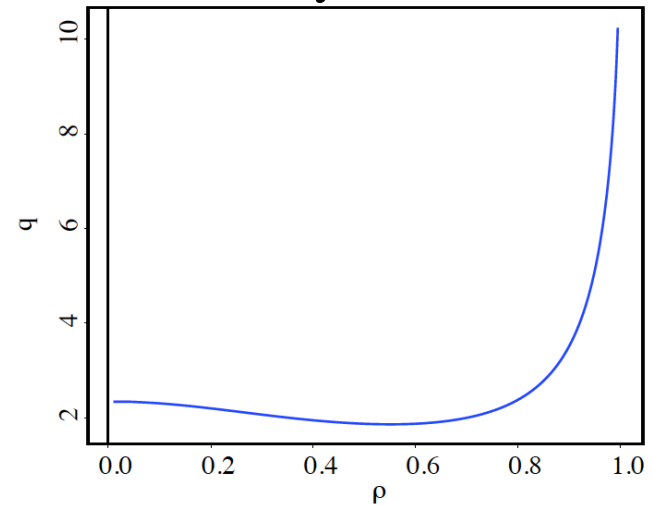
# Ideal MHD DCON, NSTX Equilibrium

Aspect ratio = 1.46,  $\beta_n=5.6$ , mpert = 35, cpu = 6 seconds

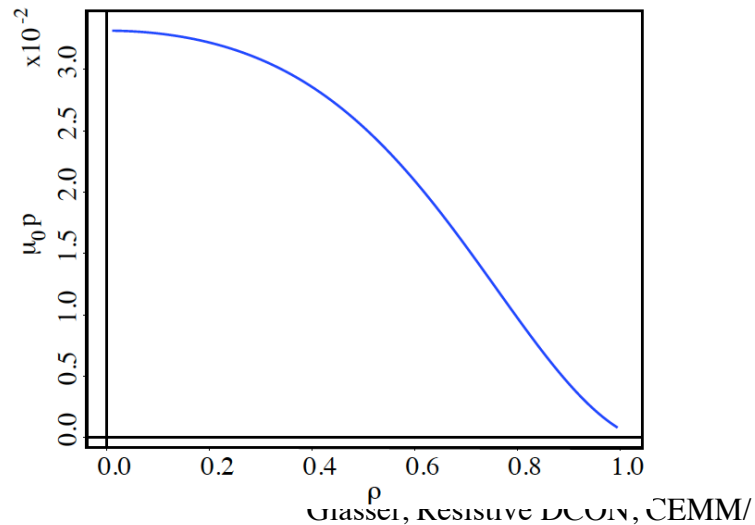
### Flux Surfaces



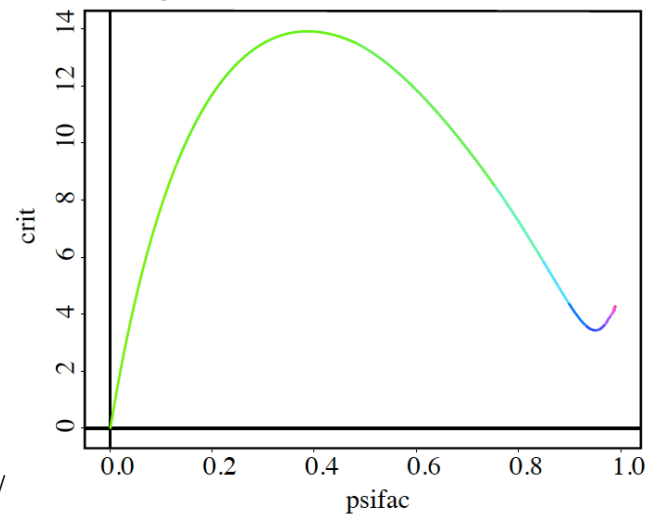
### Safety Factor



### Pressure



### Critical Determinant



# Frobenius Expansion

## Singular Surface Equations

$$\mathbf{u} \equiv \begin{pmatrix} \Xi \\ \mathbf{F}\Xi' + \mathbf{K}\Xi \end{pmatrix} \quad \mathbf{L} \equiv \begin{pmatrix} -\mathbf{F}^{-1}\mathbf{K} & \mathbf{F}^{-1} \\ \mathbf{G} - \mathbf{K}^\dagger\mathbf{F}^{-1}\mathbf{K} & \mathbf{K}^\dagger\mathbf{F}^{-1} \end{pmatrix} \quad \mathbf{u}' = \mathbf{L}\mathbf{u}$$

$$Q_{m,m'} = (m - nq)\delta_{m,m'}, \quad \mathbf{F} = \mathbf{Q}\bar{\mathbf{F}}\mathbf{Q}, \quad \mathbf{G} = \bar{\mathbf{G}}, \quad \mathbf{K} = \mathbf{Q}\bar{\mathbf{K}}$$

$$m_R - nq(\psi_R) = 0, \quad z \equiv \psi - \psi_R$$

$$\mathbf{F}^{-1} \sim z^{-2}, \quad \mathbf{F}^{-1}\mathbf{K} \sim \mathbf{K}^\dagger\mathbf{F}^{-1} \sim z^{-1}, \quad \mathbf{G} \sim \mathbf{K}^\dagger\mathbf{F}^{-1}\mathbf{K} \sim 1$$

## Convergent Power Series Expansion

$$\Xi = z^p \sum_{n=0}^N \xi_n z^n$$

$$p = -\frac{1}{2} \pm \sqrt{-D_I}, \quad \text{large and small Mercier resonant powers}$$

$$p = 0, \quad \text{nonresonant powers}$$

Solved to arbitrarily high order  $N$ ; automated using matrix formulation.  
Essential for larger values of  $|D_I|$ ; generally improves convergence.

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# Asymptotic Coefficients

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## Numerical Solution

$$\mathbf{U}' = \mathbf{L}\mathbf{U}$$

## Power Series Solutions

$$\text{As } \psi \rightarrow \psi_R, \quad \mathbf{U}'_A \rightarrow \mathbf{L}\mathbf{U}_A$$

## Asymptotic Coefficients

$$\mathbf{U} = \mathbf{U}_A \mathbf{C}_A, \quad \mathbf{C}_A = \mathbf{U}_A^{-1} \mathbf{U}$$

$$\text{As } \psi \rightarrow \psi_R, \quad \mathbf{C}'_A \rightarrow \mathbf{0}$$

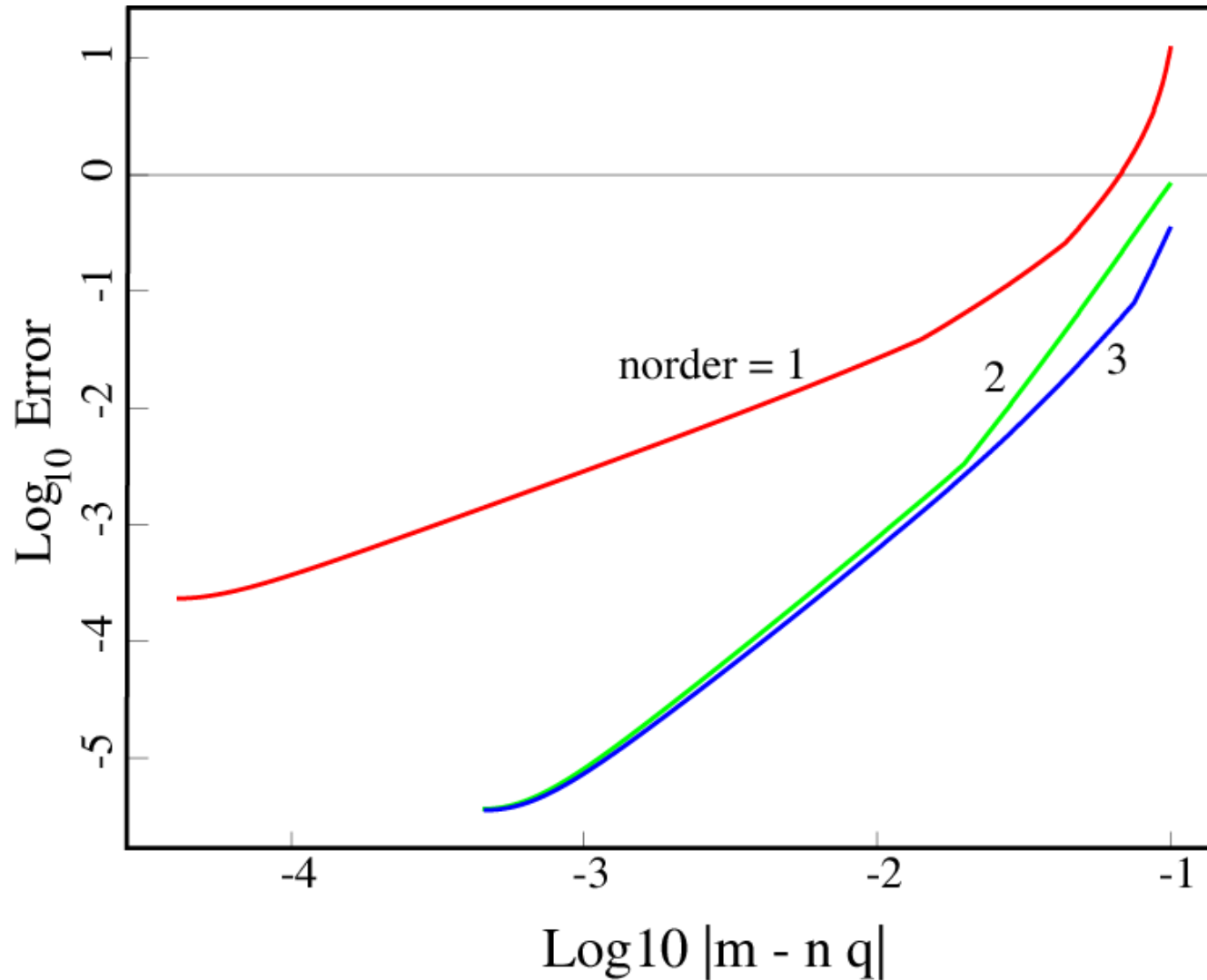
Asymptotic coefficients are used to construct matching conditions.



# Effect of Increasing Power Series Order

## Convergence of Asymptotic Coefficient Near Singular Surface

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# Initial Conditions at the Axis

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- The equations have a regular singular point at the axis  $\psi = 0$ , just as they do at each resonant surface.
- DCON uses a numerical Grad-Shafranov solution fit to bicubic splines, with one edge of the bicubic splines near the origin. This introduces noise and inaccuracy into the ODEs.
- Newcomb proves a theorem that the small solution at the axis is the limit a simpler initial condition at a point near the axis, in the limit as that point approaches the axis.
- DCON uses Newcomb's procedure and gets clean, accurate results for ideal MHD stability.



# Fixups

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- Each independent solution grows from the axis as  $r^m \sim \psi^{m/2}$ .
- $r^{20}$  grows much faster than  $r^1$ .
- If nothing is done about this, the higher  $m$ 's swamp the lower  $m$ 's. Instead of following  $M$  solutions, we follow 1 solution  $M$  times.
- Determinants approach zero, results turn to mush.
- Fixups
  - ❖ Keep track of the factor by which each independent solution grows.
  - ❖ Let  $unorm$  = ratio of the fastest to the slowest growth.
  - ❖ When  $unorm$  exceeds a specified threshold  $ucrit$ :
    - Subtract a multiple of the fastest-growing solution from each other solution
    - Repeat for each successively smaller solution
- Similar to Gaussian elimination. Triangularizes solution matrix, maintains linear independence.
- If  $ucrit$  is too large, noise develops. If it is small enough, the solutions are clean.



# Crossing a Resonant Surface

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- On approach to each resonant surface, each of the  $M$  independent solutions contains a linear combination of large, small, and non-resonant solutions.
- For ideal MHD, DCON eliminates the large resonant solution and restarts a new small resonant solution. This can be done with a fixup and without the need to evaluate asymptotic coefficients. After crossing, there are again  $M$  independent solutions.
- For resistive MHD, DCON evaluates the asymptotic coefficients. It imposes continuity on all non-resonant displacements and launches two new resonant solutions, large and small. After crossing, there are  $M+2$  independent solutions.
- The resistive crossing procedure provides just enough additional degrees of freedom to match to arbitrary inner-region solutions *a posteriori*.



# Convergence Problems

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- DCON solves an initial value problem to compute ideal MHD stability, requiring only outward integration, and fixups to maintain linear independence of solutions.
- Resistive stability calculation requires matching across the whole domain, unwinding the fixups. This converts it from an initial-value problem into a 2-point boundary value problem, solved by a shooting method.
- Such methods are known to be numerically unstable because of excessive sensitivity to initial conditions.
- This explains the failure of resistive DCON to find reliable and accurate values of the matching data.
- Solution: replace the shooting method with a the method of Dewar & Pletzer, a Galerkin expansion in basis functions, solve matrix equation for matching data.



# Dewar References

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- A. D. Miller & R. L. Dewar, “Galerkin method for differential equations with singular points,” *J. Comp. Phys.* **66**, 356-390 (1986).  
Introduces Galerkin method for singular ODEs, solves test problems.
- R. L. Dewar & A. Pletzer, “Two-dimensional generalization of the Newcomb equation,” *J. Plasma. Phys.* **43**, 2, 291-310 (1990).  
Derives 2D Newcomb equations, equivalent to DCON equation.
- A. Pletzer & R. L. Dewar, “Non-ideal Variational method for determination of the outer-region matching data,” *J. Plasma Phys.* **45**, 3, 427-451 (1991).  
Solves cylindrical problem with non-monotonic  $q$  profile.
- A. Pletzer, A. Bondeson, and R. L. Dewar, “Linear stability of resistive MHD modes: axisymmetric toroidal computation of the outer region matching data,” *J. Comp. Phys.* **115**, 530-549 (1994).  
Solves toroidal problem, PEST 3, verified against MARS code.



# Galerkin Expansion

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## Euler-Lagrange Equation

$$\mathbf{L}\Xi = -(\mathbf{F}\Xi' + \mathbf{K}\Xi)' + (\mathbf{K}^\dagger\Xi' + \mathbf{G}\Xi) = 0$$

## Galerkin Expansion

$$(u, v) \equiv \int_0^1 u^\dagger(\psi)v(\psi)d\psi$$

$$\Xi(\psi) = \sum_{i=0}^N \Xi_i \alpha_i(\psi)$$

$$(\alpha_i, \mathbf{L}\Xi) = (\alpha_i, \mathbf{L}\alpha_j)\Xi_j = 0$$

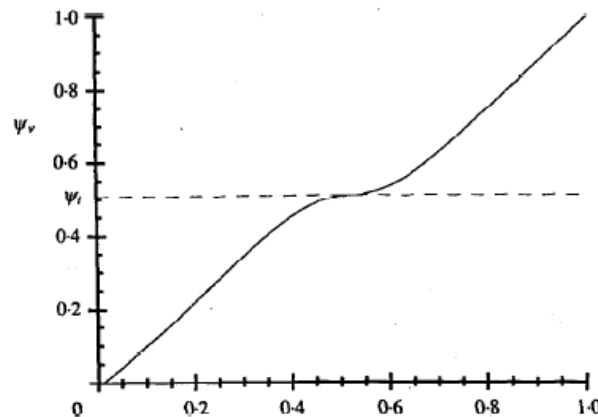
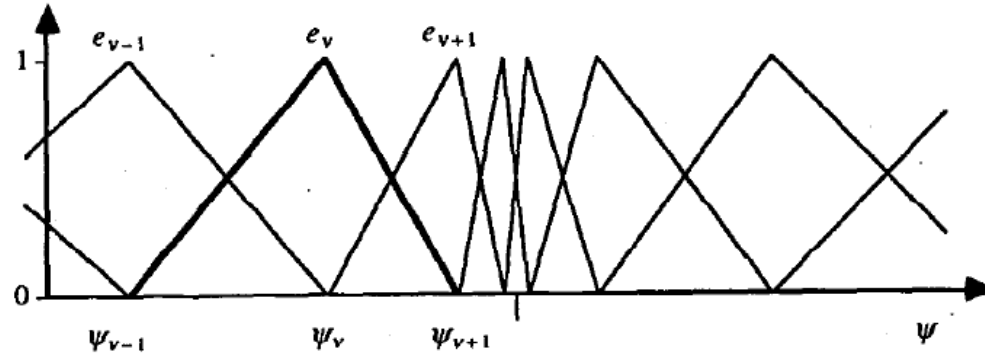
$$\mathbf{L}_{ij} = (\alpha'_i, \mathbf{F}\alpha'_j) + (\alpha'_i, \mathbf{K}\alpha_j) + (\alpha_i, \mathbf{K}^\dagger\alpha'_j) + (\alpha_i, \mathbf{G}\alpha_j)$$

## Finite-Energy Response Driven by Large Solution

$$L_{ij}\check{\Xi}_j = -(\alpha_i, L\hat{\Xi})$$



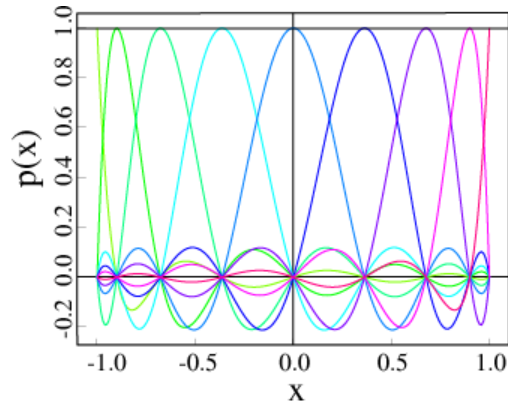
# Dewar and Pletzer: Linear Finite Elements on a Packed Grid



The choice of basis functions determines  
the rate of convergence.

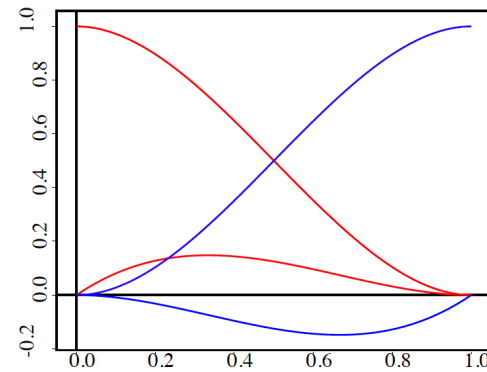
# Higher-Order Basis Functions

## $C^0$ Jacobi Nodal Basis



- Lagrange interpolatory polynomials
- Nodes at roots of  $(1-x^2)P_n^{(0,0)'}(x)$
- Diagonally dominant

## $C^1$ Hermite Cubics



- Cubic polynomials on  $(0,1)$ .
- $C^1$  continuity: function values and first derivatives
- Useful for nonresonant solutions across the singular surface.



# Adjustable Grid Packing: Equations

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## Grid Packing Function

$$\lambda(a) = \coth a = \frac{e^a + 1}{e^a - 1}, \quad a(\lambda) = \operatorname{acoth} \lambda = \ln \left( \frac{1 + \lambda}{1 - \lambda} \right)$$

$$x(\xi, \lambda) = \frac{\tanh a\xi}{\lambda} = \frac{1}{\lambda} \left( \frac{e^{a\xi} - 1}{e^{a\xi} + 1} \right)$$

$$\lim_{\lambda \rightarrow 0} a(\lambda) = 2\lambda, \quad \lim_{\lambda \rightarrow 0} x(\xi, \lambda) = \xi$$

## Center and Edge Grid Densities

$$\frac{\partial x}{\partial \xi} = \frac{1}{\lambda} \frac{2ae^{a\xi}}{(e^{a\xi} + 1)^2} = \frac{1}{\lambda} \frac{2ae^{-a\xi}}{(e^{-a\xi} + 1)^2}$$

$$\left. \frac{\partial x}{\partial \xi} \right|_{\xi=0} = \frac{a}{2\lambda}$$

$$\left. \frac{\partial x}{\partial \xi} \right|_{\xi=\pm 1} = \frac{a}{2\lambda} (1 - \lambda^2)$$

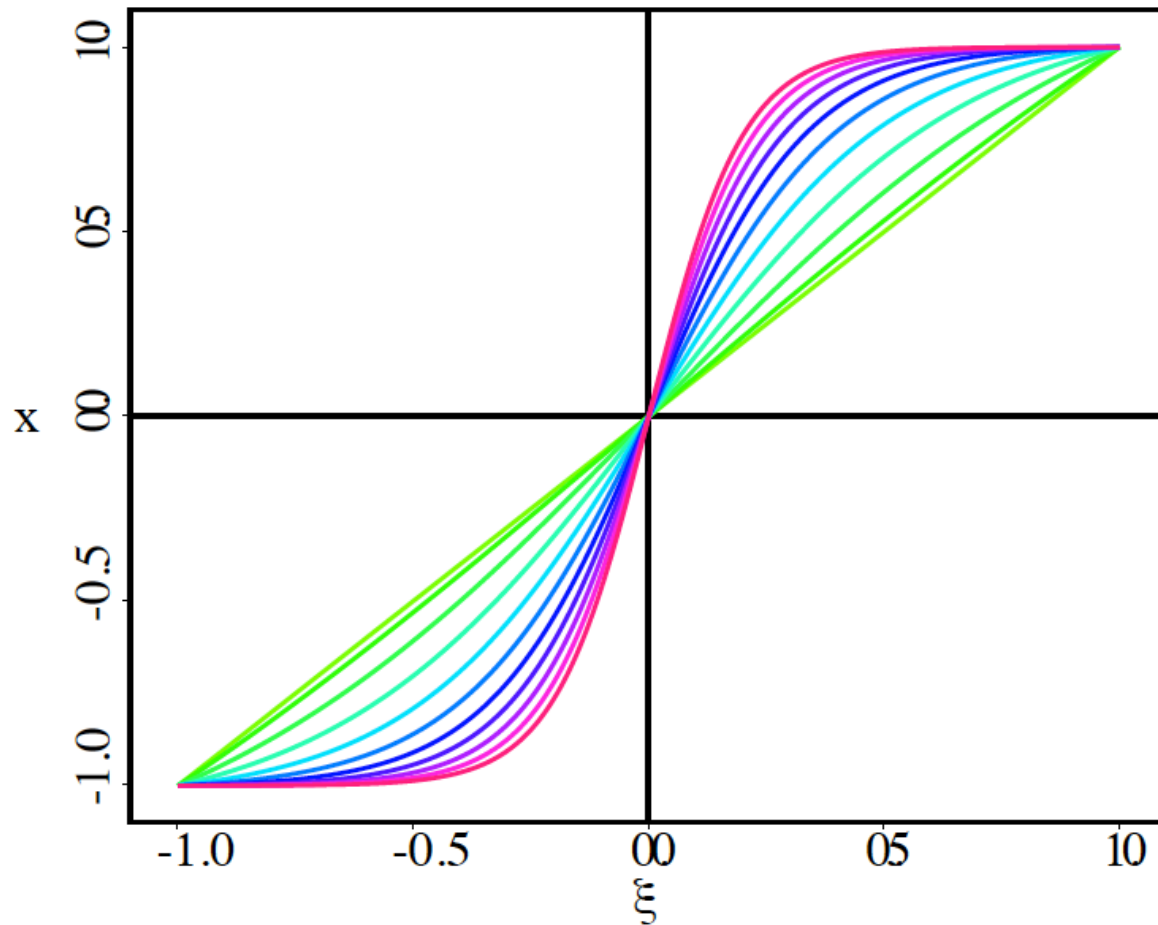
## Packing Ratio

$$P(\lambda) \equiv \frac{\partial x / \partial \xi|_{\xi=\pm 1}}{\partial x / \partial \xi|_{\xi=0}} = 1 - \lambda^2$$



# Adjustable Grid Packing: Graphs

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# Singular Elements

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- Weierstrass Convergence Theorem:  
Polynomial approximation uniformly convergent for analytic functions.
- Big and small resonant solutions are non-analytic near the singular surface.
- Supplement polynomial basis with small resonant solution near singular surface.
- DCON fits equilibrium data to Fourier series and cubic splines, computes resonant power series to arbitrarily high order.
- Convergence requires that the large solution be computed to at least  $n = 2*\sqrt{-di}$  terms. PEST 3 is limited to  $n = 1$ .



# Status and Plans

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- DCON processes data from 28 different Grad-Shafranov solvers, diagnoses them, computes the **F**, **G**, and **K** matrices, and compute power series about singular surfaces. It accurately and reliably computes ideal Mercier, ballooning, and low- $n$  free and fixed boundary modes.
- We have supplemented the existing DCON infrastructure with the method of Dewar & Pletzer, solving a set of inhomogeneous matrix equations for the outer region matching data, using the existing **F**, **G**, and **K** matrices, solved with a complex banded LAPACK routine.
- Improved choice of Galerkin basis functions and packing algorithm should result in faster, more reliable convergence, greater ease of use, compared to PEST 3.
- Solutions look good, but we have not yet achieved convergence with respect to the the rhs cutoff function. We have successfully reproduced the test cases in Miller & Dewar 1986.
- We are working with Dylan Brennan to validate resistive DCON against PEST 3.
- A separate code DELTAR implements the inner region resistive MHD equations of Glasser, Greene & Johnson, using the Fourier transform method of Glasser, Jardin & Tesauro, taking 35 microseconds of cpu time.
- Inner and out region solutions must be matched to form global eigenvalues and eigenfunctions.
- Future research will be devoted to improving the inner region model.

