

# Gyrokinetic $\delta f$ particles in NIMROD

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## Coupling Particles to FE fields

- assume that the density of hot particles is negligible compared to the bulk MHD density
- **but** allow  $\beta_{hot} \sim \beta_{bulk}$ .
- particles coupled to the fields through  $\mathbf{\Pi}_{hot}$

$$\rho \left( \frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla \right) \mathbf{V} = \mathbf{J} \times \mathbf{B} - \nabla \cdot \mathbf{\Pi} - \nabla \cdot \mathbf{\Pi}_{hot}$$

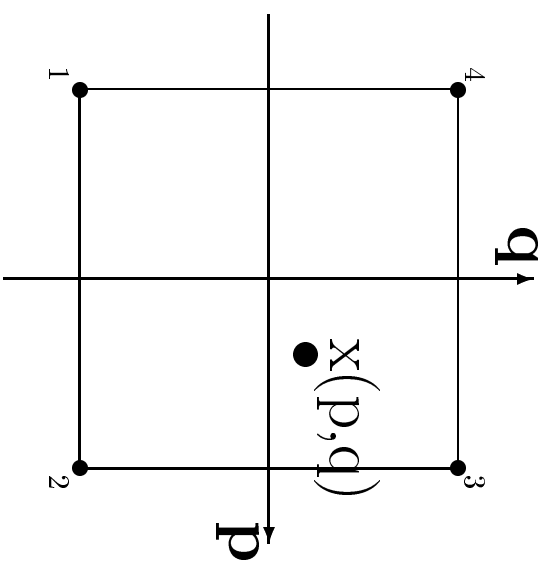
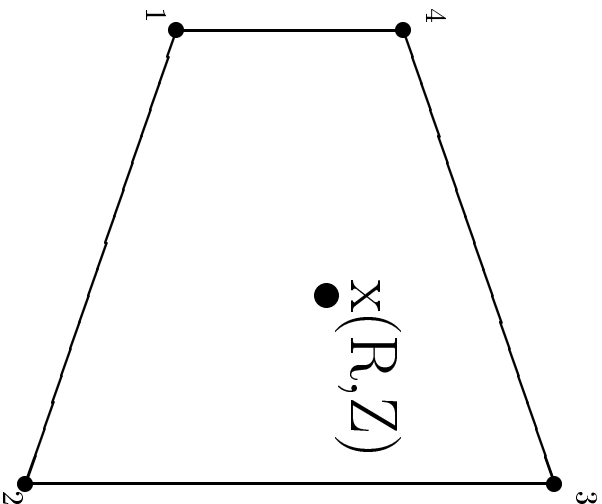
where

$$\begin{aligned} \mathbf{\Pi}_{hot} &= \int m \mathbf{v}' \mathbf{v}' \delta f \, d\mathbf{v} \\ \mathbf{v}' &= \mathbf{v} - \mathbf{V} \end{aligned}$$

- also can couple through  $\mathbf{J}$

## Define shape functions in logical space $(p, q)$ <sup>1</sup>

$$N_1(p, q) = \frac{1}{4}(1-p)(1-q) \quad N_2(p, q) = \frac{1}{4}(1+p)(1-q)$$
$$N_3(p, q) = \frac{1}{4}(1+p)(1+q) \quad N_4(p, q) = \frac{1}{4}(1-p)(1+q)$$



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<sup>1</sup> Alejandro Allievi and Rodolfo Bernejo, JCP, 132, (1997)

where  $-1 \leq p, q \leq 1$

Use Newton method to solve for  $(p, q)$  given  $(R, Z)$

$$\begin{Bmatrix} p^{k+1} \\ q^{k+1} \end{Bmatrix} = \begin{Bmatrix} p^k \\ q^k \end{Bmatrix} + \frac{1}{\Delta^k} \begin{bmatrix} b_2 + b_3 p^k & -a_2 - a_3 p^k \\ -b_1 - b_3 q^k & a_1 + a + 3q^k \end{bmatrix} \begin{Bmatrix} R_p - R_p^k \\ Z_p - Z_p^k \end{Bmatrix}$$

where

$$R_p^k = \sum_{i=1}^4 R_i N_i(p^k, q^k), \quad Z_p^k = \sum_{i=1}^4 Z_i N_i(p^k, q^k),$$

$$a_1 = \frac{1}{4}(R_2 - R_1 + R_3 - R_4), \quad b_1 = \frac{1}{4}(Z_2 - Z_1 + Z_3 - Z_4),$$

$$a_2 = \frac{1}{4}(R_3 - R_1 + R_4 - R_2), \quad b_2 = \frac{1}{4}(Z_3 - Z_1 + Z_4 - Z_2),$$

$$a_3 = \frac{1}{4}(R_1 - R_2 + R_3 - R_4), \quad b_3 = \frac{1}{4}(Z_1 - Z_2 + Z_3 - Z_4),$$

$$\Delta^k = (a_1 b_2 - a_2 b_1) + (a_1 b_3 - a_3 b_1) p^k + (a_3 b_2 - a_2 b_3) q^k$$

- matrix on **rhs** is inverse of the Jacobian relating the logical coordinates to the real coordinates

$$\frac{1}{\Delta^k} \begin{bmatrix} b_2 + b_3 p^k & -a_2 - a_3 p^k \\ -b_1 - b_3 q^k & a_1 + a + 3q^k \end{bmatrix} = \begin{pmatrix} \frac{\partial R}{\partial p} & \frac{\partial R}{\partial q} \\ \frac{\partial Z}{\partial p} & \frac{\partial Z}{\partial q} \end{pmatrix}^{-1}$$

- this is used in computation of derivatives on the finite elements.
- iterate until  $\sqrt{(R_p - R_p^k)^2 + (Z_p - Z_p^k)^2} < \epsilon$
- if  $-1 \leq p, q \leq 1$  is not true, then the particle is not in this element, and another element needs to be searched
- new element to be searched is determined by the value of  $(p, q)$ , left if  $p < -1$ , right if  $p > 1$ , down if  $q < -1$ , up if  $q > 1$ , and combinations thereof.

## Equations of motion

$$m \frac{d\mathbf{u}}{dt} = -\hat{b} \cdot (\mu \nabla B + e \nabla \psi)$$

$$\frac{d\mathbf{x}}{dt} = \mathbf{u} + \frac{m}{eB^4} \left( u^2 + \frac{v_{\perp}^2}{2} \right) \left( \mathbf{B} \times \nabla \frac{B^2}{2} \right) + \frac{\mathbf{E} \times \mathbf{B}}{B^2}$$

$$\begin{aligned} \frac{dw}{dt} &= -\dot{z}_1 \cdot \nabla f_0 \\ &= -\tilde{v}_D \left( \frac{\nabla n}{n} + \frac{\nabla T}{T} \left( \frac{3}{2} - \frac{v^2}{v_{th}^2} \right) \right) + \frac{2q\tilde{E}v}{mv_{th}^2} \end{aligned}$$

- need gradient quantities
- take the derivative of the shape functions

$$\frac{\partial B}{\partial R} = \sum_{i=1}^4 B_i \frac{\partial N_i(p, q)}{\partial R} = \sum_{i=1}^4 B_i \left( \frac{\partial N_i}{\partial p} \frac{\partial p}{\partial R} + \frac{\partial N_i}{\partial q} \frac{\partial q}{\partial R} \right)$$

- similarly for  $Z$ .

- from the inverse function theorem

$$\begin{bmatrix} \frac{\partial p}{\partial R} & \frac{\partial p}{\partial Z} \\ \frac{\partial q}{\partial R} & \frac{\partial q}{\partial Z} \end{bmatrix} = \begin{bmatrix} \frac{\partial R}{\partial p} & \frac{\partial R}{\partial q} \\ \frac{\partial Z}{\partial p} & \frac{\partial Z}{\partial q} \end{bmatrix}^{-1}$$

- right hand matrix is easy to compute if one recalls that

$$R = \sum_{i=1}^4 R_i N_i(p, q)$$

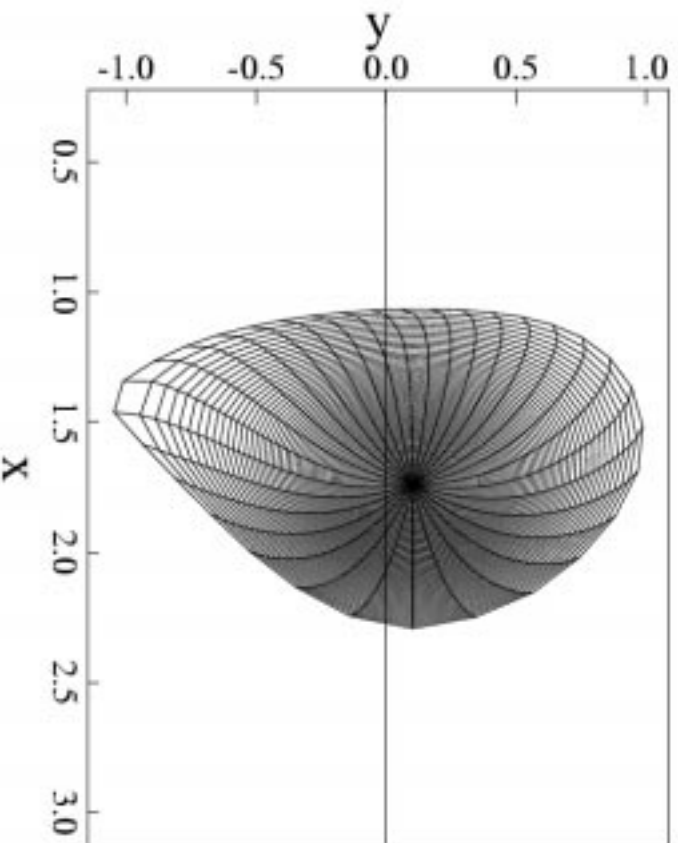
$$\begin{aligned} \frac{\partial R}{\partial p} &= \sum_{i=1}^4 R_i \frac{\partial N_i}{\partial p} & \frac{\partial R}{\partial q} &= \sum_{i=1}^4 R_i \frac{\partial N_i}{\partial q} \\ \frac{\partial Z}{\partial p} &= \sum_{i=1}^4 Z_i \frac{\partial N_i}{\partial p} & \frac{\partial Z}{\partial q} &= \sum_{i=1}^4 Z_i \frac{\partial N_i}{\partial q} \end{aligned}$$

- already computed for Newton Method

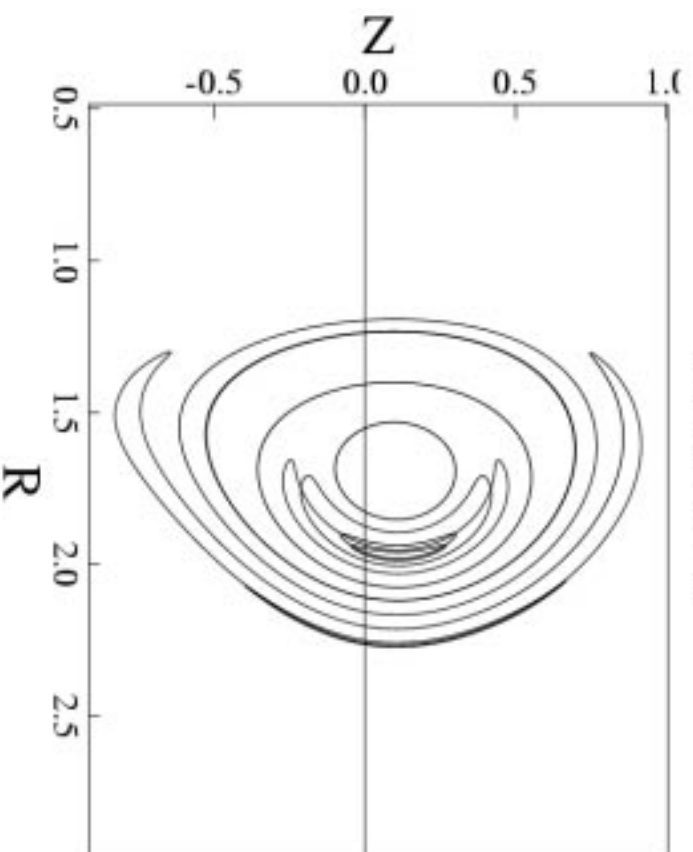
## Test Case

Particles trace field lines and execute bounce motion for the simplified test case.

### NIMROD Grid



### Particles



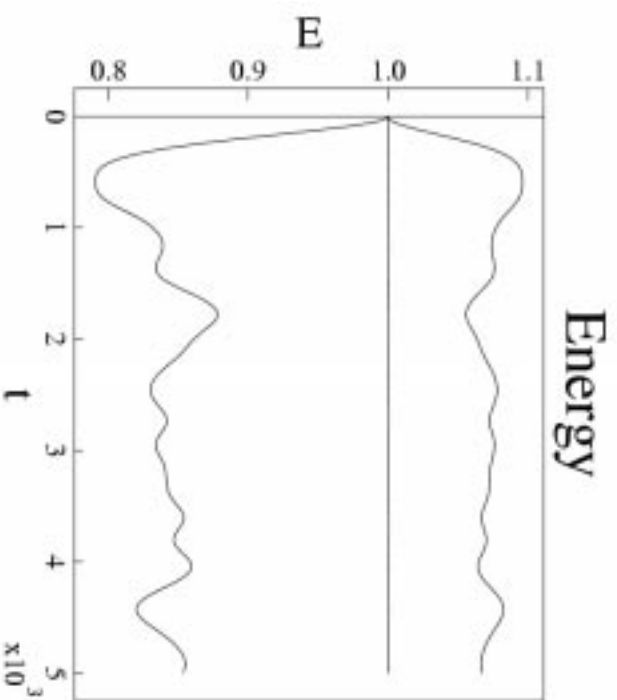


To test the method, a reduced equation of motion is used,

$$\begin{aligned}
 m\dot{\mathbf{u}} &= -\frac{\mu}{B} \left( B_R \frac{\partial B}{\partial R} + B_Z \frac{\partial B}{\partial Z} \right) \\
 \dot{R} &= \mathbf{u} \cdot \hat{R} + v_D (-B_\phi) \frac{\partial B}{\partial Z} \\
 \dot{Z} &= \mathbf{u} \cdot \hat{Z} + v_D (-B_\phi) \frac{\partial B}{\partial R} \\
 \dot{\phi} &= \mathbf{u} \cdot \hat{\phi} + v_D \left( B_R \frac{\partial B}{\partial Z} - B_Z \frac{\partial B}{\partial R} \right),
 \end{aligned}$$

where  $v_D = \frac{m}{eB^3} \left( u^2 + \frac{v_\perp^2}{2} \right)$ , assume axisymmetry, cylindrical geometry, and no **E**-field.

For the simple test case, energy conservation is excellent, to a few parts in  $10^4$  or better depending on  $\epsilon$ , the stopping criterion. The performance is 10's of  $\mu s$  per particle, per timestep. This also varies with  $\epsilon$ .



## Parallelization

- two levels of parallelization - fourier layers and rblocks
- for fourier layer, use domain cloning
  - divide particles evenly among fourier layers
  - each layer evolves own set of particles
  - global sum required to gather particle information
  - particles are never passed between layers
- rblocks is domain decomposition
  - generate map from global grid to rblock-decomposed grid
  - sort particles on global grid
  - use map to pass particles to appropriate rblock
  - sorting allows optimization by reducing field evaluation

## Sorted PIC

- sort particles into respective cell
- gather/scatter done cell by cell instead of particle by particle
- reduce field evaluation to once per cell instead of once per particle
- allows for alternative particle deposition

## Minimal Implementation

- assume some  $\kappa$  profile
- for a single linear mode use energy conservation to observe effects of kinetic particles

$$(\delta W_{MHD}^{n+1} - \delta W_{MHD}^n) + (\delta W_{KE}^{n+1} - \delta W_{KE}^n) = 0$$

- scale amplitude of  $\delta W_{MHD}$  to maintain energy conservation

$$\delta W_{MHD}^{n+1} = \alpha \delta W_{MHD}^n$$

- solve for  $\alpha$

$$\alpha \delta W_{MHD}^n - \delta W_{MHD}^n + \delta W_{KE}^{n+1} - \delta W_{KE}^n = 0$$

$$\alpha = 1 + \frac{\delta W_{KE}^n - \delta W_{KE}^{n+1}}{\delta W_{MHD}^n}$$