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## *Role of Deputy Director for Code Architecture and Strategy for Integration of Advanced Computing R&D*

*Andrew Siegel*

*FSP Deputy Director for Code Architecture*

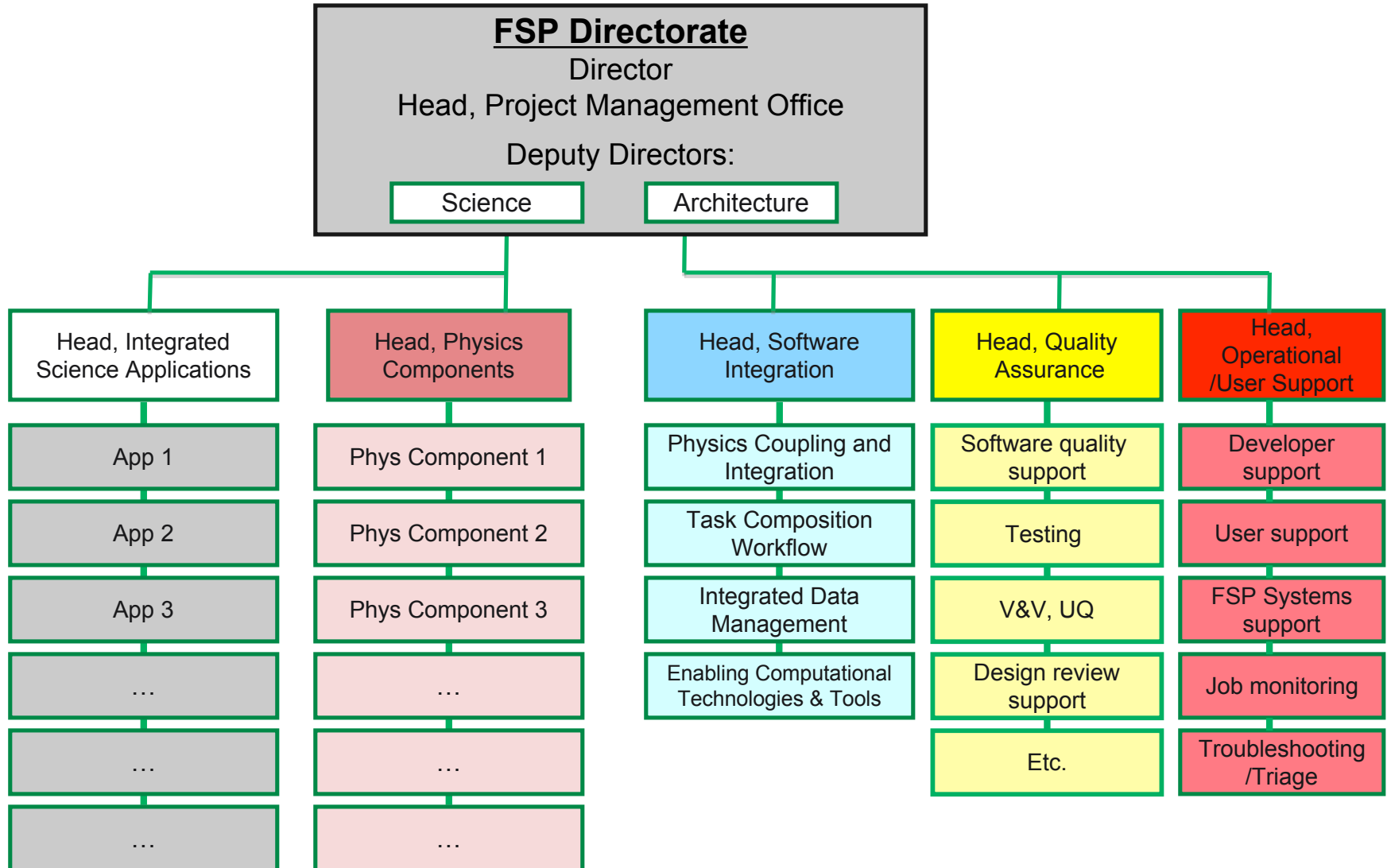
## *Outline*

- ✓ Responsibilities of Deputy Director for Code Architecture
- ✓ High-level organization of FSP code development activities
- ✓ Strategy for incorporation of ASCR R&D
- ✓ FSP Computing architectures

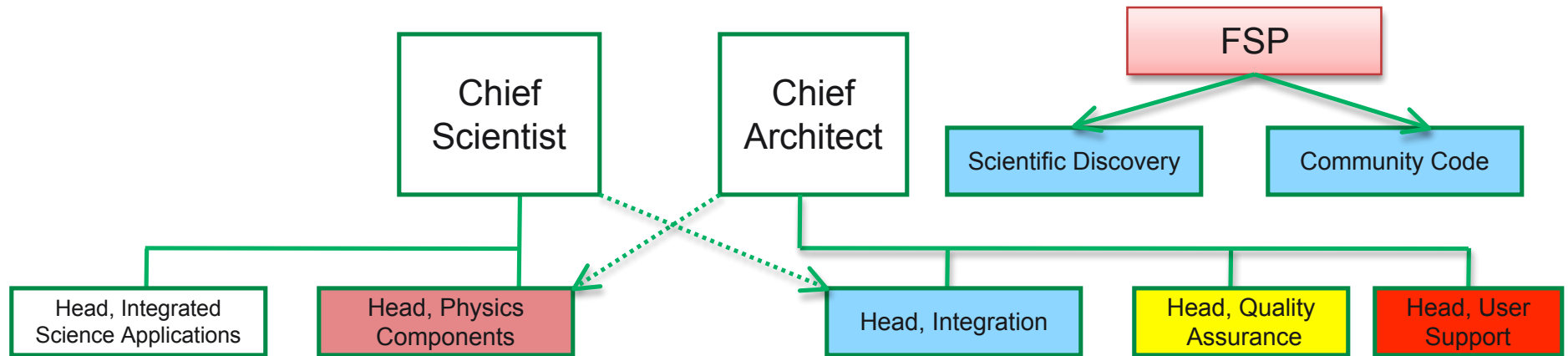
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# FSP Management Organization Chart



# Overall Responsibilities of Chief Architect



1. Oversees all aspects of code development
  - Software componentization of physics working with Chief Scientist
  - Software integration
  - Enabling computational technologies
  - Facilities support: user support, developer support, testing, etc.
1. Serves as ASCR Program Office contact for embedded applied math/CS Research & Development activities
1. Oversees strategy for migration of codes to future computing architectures

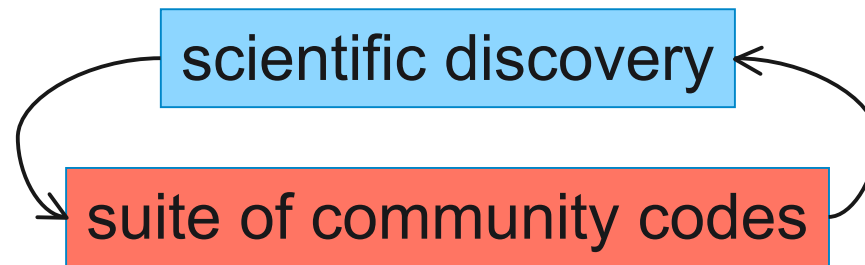
## ***Responsibilities: Oversight of software integration***

Deputy Director for Code Architecture:

- ✓ Constantly refines strategies to enable horizontal integration of FSP tools
  - application projects built off of common FSP physics components that form basis of integrated whole device model
  - application projects move toward common infrastructure/standards
  - application projects live under common software lifecycle
- ✓ Works with area leads to adopt processes that advance these goals without overly constraining integrated application teams in short-term.
- ✓ Leverage partnerships with ongoing DOE programs with track record of successful developments (e.g. Visit, Cubit, etc.)
- ✓ Combines knowledge of software architecture, physics, and numerics

## *Responsibilities: Oversight of User Support*

- ✓ FSP will produce



- ✓ Process managed as relatively mature software process (integration talk)
  - Complex release, versioning, and repo management issues
  - Heavy emphasis on documentation
  - Provenance/pedigree ...
  - Usability
- ✓ Deputy Director oversees delicate balance to ensure that these processes work smoothly with overall integration and research goals

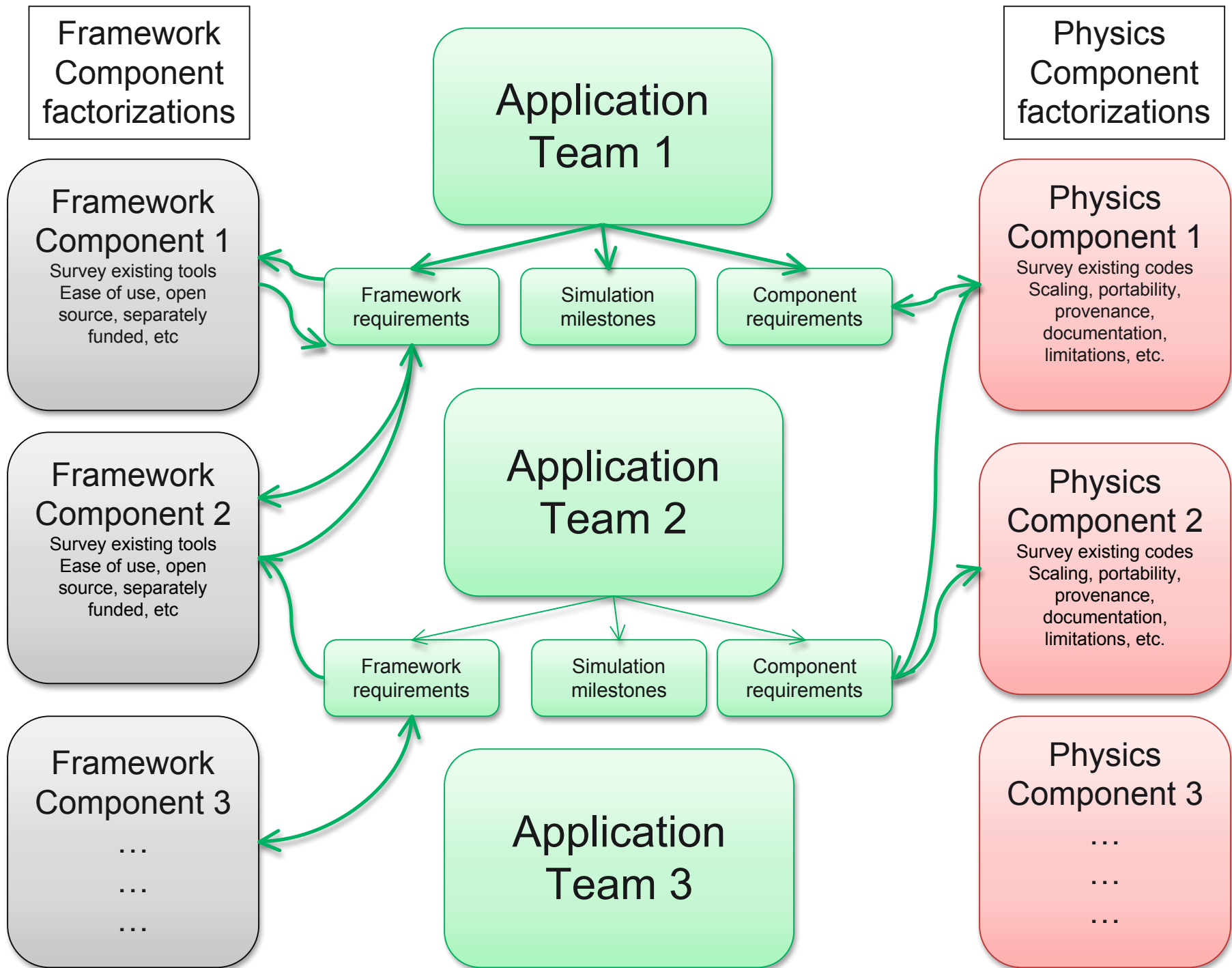
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## Partnership with ASCR

- ✓ ASCR supports research that dedicates efforts across disciplines to critical issues that underline simulation of complex systems.
- ✓ Significant progress in last decade working in "embedded mode" within application groups -- tools not built completely in the abstract
- ✓ Proto-FSPs modeled this way -- have examples of success in numerical methods, software engineering, visualization
- ✓ Must be careful not to separate embedded R&D topics with facilities support and technical expertise.

## Areas of ASCR Research

- ✓ Innovative software engineering
  - CCA, ITAPS, ...
- ✓ Numerical methods, algorithms, solvers
  - Apdec, TOPS
- ✓ Data analysis and Visualization
  - VACETS
- ✓ UQ and Stochastic Systems
- ✓ Mesh generation, mesh representation
  - ITAPS
- ✓ programming models/future architectures
  - Exascale Centers

How to move from general strategy to concrete to meet FSP research needs?

# *Process for incorporation of ASCR research*

- ✓ In next stage of planning phase
  - Establish small crosscut team and require each application area to specify abstractly initial requirements for coupling, i/o, computing resources, physics components, etc. (end of September)
  
  - Key finding from proto-FSP review: “interdisciplinary teams required in each major management area ...”
  
  - Translate into concrete embedded ASCR R&D activities
    - *enabling technologies: meshing, visualization, software coupling, etc.*
    - *linear/non-linear solvers, coupling methods*
  
- ✓ At implementation phase
  - Require that appropriate individuals/teams are brought on board to execute apps project.
  - Give integrated application leads flexibility to choose established collaborators
  - Allow application teams to bootstrap existing tools (e.g. from proto-FSPs).

## *Some issues raised Proto-FSPs: Applied Math*

- ✓ Extending governing equations into new regimes of applicability
  - e.g. gyrokinetic equations into the edge
- ✓ Hybrid algorithms
  - e.g. kinetic models and continuum models through the pedestal
- ✓ Accuracy and stability of various coupling strategies
  - one-way coupling, boundary/interface coupling, operator-splittings
- ✓ Error estimation and uncertainty quantification for coupled models involving deterministic and Monte Carlo components and deterministic and statistical analysis; if we're coupling PIC in the core to a continuum model in the edge, how do we estimate the error in each and how do we combine these estimates to quantify the overall uncertainty?

## ***Some issues raised with Proto-FSPs: CS***

- ✓ portable workflow models
- ✓ data provenance capture
- ✓ different physics codes using different parallelism models interacting
- ✓ Blue Gene specific portability issues and impact on code architecture
- ✓ dynamic load balancing across and within components

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## *Existing and future HPC architectures*

- ✓ Required computing resources dictated by science drivers
- ✓ Targeting a class of problems where physics fidelity benefits from next generation LCCs
  - Report: “Fusion Energy Sciences and the Role of Computing at the Extreme Scale”
- ✓ Leadership architectures rapidly moving away from one MPI process per core
  - MPI + ? Needed to take advantage of very high level node parallelism
  - Move from bulk synchronous to multitasking, etc. etc.
- ✓ Need to define software approach which ensures transition
  - Strong partnerships with exascale Center(s)