BEYOND LINEAR POLARIZATION IN GYROKINETIC THEORY

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Polarization effects play a crucial role in the nonlinear gyrokinetic description of turbulent magnetized plasmas

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OUTLINE

- Physics of Polarization and Magnetization
 - High-frequency Oscillation-center Polarization
- Top-down Approach: Variational Formulation
 - Reduced Hamiltonian
- Bottom-up Approach: Push-forward Formulation
 - Near-identity Transformation
- Guiding-center Polarization and Magnetization
- Linear and Nonlinear Gyrocenter Polarization

PHYSICS OF POLARIZATION AND MAGNETIZATION

- Macroscopic Description of Electromagnetic Fields
- Microscopic $(E,B) \rightarrow$ Macroscopic (D,H)

 $\mathbf{D} \equiv \mathbf{E}$ + $4\pi \ \mathbf{P}$ and $\mathbf{H} \equiv \mathbf{B}$ - $4\pi \ \mathbf{M}$

• Microscopic & Macroscopic Charge and Current

$$\ensuremath{arrho} \equiv \ensuremath{arrho}_R \ - \
abla \cdot \mathbf{P} \ \mbox{and} \ \ \mathbf{J} \equiv \mathbf{J}_R \ + \ rac{\partial \mathbf{P}}{\partial t} \ + \ c \
abla imes \mathbf{M}$$

• Macroscopic Maxwell Equations

$$\nabla \cdot \mathbf{D} = 4\pi \varrho_R \qquad \nabla \cdot \mathbf{B} = \mathbf{0}$$

$$abla imes \mathbf{H} - \frac{1}{c} \frac{\partial \mathbf{D}}{\partial t} = 4\pi \mathbf{J}_R \qquad \nabla \times \mathbf{E} + \frac{1}{c} \frac{\partial \mathbf{B}}{\partial t} = \mathbf{0}$$

- Oscillation-center Polarization & Magnetization (Brizard, 2009) → Laser-plasma interactions
- Eikonal Representation ($\omega \equiv -\partial_t \Theta, \ \mathbf{k} \equiv \nabla \Theta$)

$$(\mathbf{E}_1, \mathbf{B}_1) = \left(\overline{\mathbf{E}}_1, \overline{\mathbf{B}}_1\right) \exp\left(\epsilon^{-1} i\Theta(\epsilon \mathbf{r}, \epsilon t)\right) + \text{c.c.}$$

• Oscillation-center Displacement ($\omega' \equiv \omega - \mathbf{k} \cdot \mathbf{v}$)

$$\overline{\xi}_1 \equiv \frac{-e}{m\,\omega'^2} \Big(\overline{\mathbf{E}}_1 \,+\, \frac{\mathbf{v}}{c} \times \overline{\mathbf{B}}_1\Big)$$

• Oscillation-center Polarization & Magnetization

$$\begin{pmatrix} \overline{\pi}_{2\text{oc}} \\ \overline{\mu}_{2\text{oc}} \end{pmatrix} = \begin{pmatrix} e \,\mathbf{k} \times \left(i \,\overline{\xi}_1 \times \overline{\xi}_1^* \right) \\ \\ \frac{e}{c} \,\omega' \, \left(i \,\overline{\xi}_1 \times \overline{\xi}_1^* \right) \end{pmatrix}$$

$$\begin{pmatrix} \overline{\mathbf{P}}_{2\text{oc}} \\ \overline{\mathbf{M}}_{2\text{oc}} \end{pmatrix} = \sum \int d^3 \overline{p} \,\overline{F} \begin{pmatrix} \overline{\pi}_{2\text{oc}} \\ \overline{\mu}_{2\text{oc}} + \overline{\pi}_{2\text{oc}} \times \overline{\mathbf{v}}/c \end{pmatrix}$$

TOP-DOWN APPROACH: VARIATIONAL FORMULATION

• Reduced Lagrangian Density

$$\mathcal{L} = \frac{1}{8\pi} (|\mathbf{E}|^2 - |\mathbf{B}|^2) + \underbrace{\mathcal{L}_R(\cdots; \Phi, \mathbf{A}; \mathbf{E}, \mathbf{B}, \cdots)}_{\text{Reduced plasma dynamics}}$$

• Euler-Poincaré Equations

$$\nabla \cdot \left(\frac{\partial \mathcal{L}}{\partial \mathbf{E}}\right) + \frac{\partial \mathcal{L}_R}{\partial \Phi} = 0 = \frac{1}{c} \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial \mathbf{E}}\right) + \nabla \times \left(\frac{\partial \mathcal{L}}{\partial \mathbf{B}}\right) + \frac{\partial \mathcal{L}_R}{\partial \mathbf{A}}$$

• Reduced (Dipole) Polarization and Magnetization

$$\left(\mathbf{P}, \mathbf{M}\right) \equiv \left(\frac{\partial \mathcal{L}_R}{\partial \mathbf{E}}, \frac{\partial \mathcal{L}_R}{\partial \mathbf{B}}\right)$$

• Reduced Charge and Current Densities

$$\left(
ho_R, \, \frac{1}{c} \mathbf{J}_R
ight) \, \equiv \, \left(-\, \frac{\partial \mathcal{L}_R}{\partial \mathbf{\Phi}}, \, \frac{\partial \mathcal{L}_R}{\partial \mathbf{A}}
ight)$$

- Oscillation-center (Quadratic) Hamiltonian
- **Canonical Transformation** (weak background $\epsilon_0 \ll 1$)

$$-i\,\omega'\,\overline{S}_1 + \epsilon_0\,\frac{e}{m}\left(\mathbf{E}_0 + \frac{\mathbf{v}}{c}\times\mathbf{B}_0\right)\cdot\frac{\partial S_1}{\partial \mathbf{v}} = e\left(\overline{\Phi}_1 - \frac{\mathbf{v}}{c}\cdot\overline{\mathbf{A}}_1\right)$$

• Oscillation-center Hamiltonian

$$\overline{H}_{2\text{oc}} = -\frac{e}{2m} \left\langle \left(\mathbf{E}_{1} + \frac{\overline{\mathbf{v}}}{c} \times \mathbf{B}_{1} \right) \cdot \frac{\partial S_{1}}{\partial \overline{\mathbf{v}}} \right\rangle$$
$$= m \, \omega'^{2} \, |\overline{\boldsymbol{\xi}}_{1}|^{2} - \epsilon_{0} \left[\mathbf{E}_{0} \cdot \overline{\boldsymbol{\pi}}_{2\text{oc}} + \mathbf{B}_{0} \cdot \left(\overline{\boldsymbol{\mu}}_{2\text{oc}} + \overline{\boldsymbol{\pi}}_{2\text{oc}} \times \frac{\overline{\mathbf{v}}}{c} \right) \right]$$

• Oscillation-center Polarization & Magnetization

$$\begin{pmatrix} \overline{\mathbf{P}}_{2\text{oc}} \\ \overline{\mathbf{M}}_{2\text{oc}} \end{pmatrix} = -\epsilon_0^{-1} \sum \int d^3 \overline{p} \, \overline{F} \begin{pmatrix} \partial \overline{H}_{2\text{oc}} / \partial \mathbf{E}_0 \\ \partial \overline{H}_{2\text{oc}} / \partial \mathbf{B}_0 \end{pmatrix}$$

BOTTOM-UP APPROACH: PUSH-FORWARD FORMULATION

- Dynamical Reduction by Near-identity Phase-space Transformation
- **Transformation** $T_{\epsilon} : \mathcal{Z} \to \overline{\mathcal{Z}}(\mathcal{Z}; \epsilon) \equiv T_{\epsilon}\mathcal{Z}$

 \rightarrow Pull-back operator $T_{\epsilon}: \overline{\mathcal{F}} \rightarrow \mathcal{F} \equiv T_{\epsilon} \overline{\mathcal{F}}$

• Inverse Transformation $\mathcal{T}_{\epsilon}^{-1}: \overline{\mathcal{Z}} \to \mathcal{Z}(\overline{\mathcal{Z}}; \epsilon) \equiv \mathcal{T}_{\epsilon}^{-1}\overline{\mathcal{Z}}$

 \rightarrow Push-forward operator T_{ϵ}^{-1} : $\mathcal{F} \rightarrow \overline{\mathcal{F}} \equiv T_{\epsilon}^{-1}\mathcal{F}$

• Pull-back and Push-forward Operators



• Pull-back Operation: Iterative Vlasov Solver

• Push-forward Operation: Reduced Displacement

- Reduced Polarization and Magnetization
- **Displacement** $\rho_{\epsilon} \equiv T_{\epsilon}^{-1}x \overline{x}$ (e.g., gyroradius)

$$\boldsymbol{\rho}_{\epsilon} = -\epsilon G_{1}^{\mathbf{x}} - \epsilon^{2} \left(G_{2}^{\mathbf{x}} - \frac{1}{2} \mathsf{G}_{1} \cdot \mathsf{d} G_{1}^{\mathbf{x}} \right) + \cdots$$

• Push-forward representation for four-current

$$J^{\mu}(\mathbf{r}) = \sum e \int_{x,p} v^{\mu} \delta^{3}(\mathbf{x} - \mathbf{r}) \mathcal{F} \equiv \sum e \int_{x,p} (c, \mathbf{v}) \delta^{3}(\mathbf{x} - \mathbf{r}) \mathcal{F}$$
$$= \sum e \int_{\overline{x},\overline{p}} \left(\mathsf{T}_{\epsilon}^{-1} v^{\mu}\right) \delta^{3}(\overline{\mathbf{x}} + \rho_{\epsilon} - \mathbf{r}) \overline{\mathcal{F}}$$
$$= \sum e \int_{\overline{p}} \left[\left(\mathsf{T}_{\epsilon}^{-1} v^{\mu}\right) \overline{\mathcal{F}} - \nabla \cdot \left(\rho_{\epsilon} \mathsf{T}_{\epsilon}^{-1} v^{\mu} \overline{\mathcal{F}}\right) + \cdots \right]$$

• Push-forward of Particle Velocity

$$\mathsf{T}_{\epsilon}^{-1}\mathbf{v} = \mathsf{T}_{\epsilon}^{-1}\left(\frac{d\mathbf{x}}{dt}\right) = \left[\mathsf{T}_{\epsilon}^{-1}\frac{d}{dt}\mathsf{T}_{\epsilon}\right]\left(\mathsf{T}_{\epsilon}^{-1}\mathbf{x}\right) \equiv \frac{d_{\epsilon}\overline{\mathbf{x}}}{dt} + \frac{d_{\epsilon}\boldsymbol{\rho}_{\epsilon}}{dt}$$

• Charge-current Push-forward

$$\rho \equiv \overline{\rho} - \nabla \cdot \mathbf{P}_{\epsilon} \text{ and } \mathbf{J} = \overline{\mathbf{J}} + \frac{\partial \mathbf{P}_{\epsilon}}{\partial t} + c \, \nabla \times \mathbf{M}_{\epsilon}$$

* Reduced Polarization

$$\begin{aligned} \mathbf{P}_{\epsilon} &= \sum e \, \int_{\overline{p}} \left[\, \rho_{\epsilon} \, \overline{\mathcal{F}} \, - \, \frac{1}{2} \, \nabla \cdot \left(\rho_{\epsilon} \, \rho_{\epsilon} \, \overline{\mathcal{F}} \right) \, + \, \cdots \right] \\ &\equiv \sum \, \int_{\overline{p}} \, \pi_{\epsilon} \, \overline{\mathcal{F}} \, + \, \cdots \end{aligned}$$

* Reduced Magnetization

$$\mathbf{M}_{\epsilon} = \sum \frac{e}{c} \int_{\overline{p}} \left[\rho_{\epsilon} \times \left(\frac{1}{2} \frac{d_{\epsilon} \rho_{\epsilon}}{dt} + \frac{d_{\epsilon} \overline{\mathbf{x}}}{dt} \right) + \cdots \right] \overline{\mathcal{F}}$$
$$\equiv \sum \int_{\overline{p}} \left(\mu_{\epsilon} + \pi_{\epsilon} \times \frac{1}{c} \frac{d_{\epsilon} \overline{\mathbf{x}}}{dt} \right) \overline{\mathcal{F}}$$

• Oscillation-center Displacement

$$\rho_{\epsilon} \equiv \epsilon \xi + \frac{\epsilon^2}{2} \left(\xi \cdot \nabla \xi + m \frac{d\xi}{dt} \cdot \frac{\partial \xi}{\partial \mathbf{p}} \right) - \epsilon^2 G_2^{\mathbf{x}} + \cdots$$

• Eikonal-averaged Electric-dipole Moment

$$e \langle \boldsymbol{\rho}_{\epsilon} \rangle = \epsilon^2 \, \overline{\pi}_{2\text{oc}} = \epsilon^2 \, e \, \mathbf{k} \times \left(i \, \overline{\boldsymbol{\xi}}_1 \times \overline{\boldsymbol{\xi}}_1^* \right)$$

• Eikonal-averaged Magnetic-dipole Moment

$$\frac{e}{2c} \left\langle \boldsymbol{\rho}_{\epsilon} \times \frac{d_{\epsilon} \boldsymbol{\rho}_{\epsilon}}{dt} \right\rangle = \epsilon^{2} \,\overline{\boldsymbol{\mu}}_{2\text{oc}} = \epsilon^{2} \,\frac{e}{c} \,\omega' \,\left(i \,\overline{\boldsymbol{\xi}}_{1} \times \overline{\boldsymbol{\xi}}_{1}^{*} \right)$$

GUIDING-CENTER

POLARIZATION AND MAGNETIZATION

- Variational Formulation
- Perturbed Particle Phase-space Lagrangian

$$\Lambda_1 \equiv (e/c) \mathbf{A}_1 \cdot \mathsf{d} \mathbf{x} - e \, \Phi_1 \, \mathsf{d} t$$

• Perturbed Guiding-center Phase-space Lagrangian

$$\Lambda_{1\text{gc}} \equiv \mathsf{T}_{\text{gc}}^{-1} \Lambda_{1} + \mathsf{d}\sigma_{1}$$
$$= \frac{e}{c} \mathsf{A}_{1}(\mathbf{X} + \rho_{\text{gc}}, t) \cdot \left(\mathsf{d}\mathbf{X} + \mathsf{d}\rho_{\text{gc}}\right)$$
$$- e \,\Phi_{1}(\mathbf{X} + \rho_{\text{gc}}, t) \,\mathsf{d}t + \mathsf{d}\sigma_{1}$$

• Guiding-center Displacement

$$\rho_{\rm gc} = \rho_0 + \epsilon_B \, \rho_1 + \cdots$$

★ Dipole expansion

$$\begin{split} \Lambda_{1\text{gc}} &= \frac{e}{c} \left(\mathbf{A}_{1} + \rho_{\text{gc}} \cdot \nabla \mathbf{A}_{1} + \cdots \right) \cdot \left(\mathsf{d}\mathbf{X} + \mathsf{d}\rho_{\text{gc}} \right) \\ &- e \left(\Phi_{1} + \rho_{\text{gc}} \cdot \nabla \Phi_{1} + \cdots \right) \, \mathsf{d}t + \mathsf{d}\sigma_{1} \\ &= \frac{e}{c} \, \mathbf{A}_{1} \cdot \mathsf{d}\mathbf{X} - e \, \Phi_{1} \, \mathsf{d}t \\ &+ e \, \rho_{\text{gc}} \cdot \left[\mathbf{E}_{1} \, \mathsf{d}t + \frac{1}{c} \left(\mathsf{d}\mathbf{X} + \frac{1}{2} \mathsf{d}\rho_{\text{gc}} \right) \times \mathbf{B}_{1} \right] \end{split}$$

where

$$\sigma_1 = -\frac{e}{c} \mathbf{A}_1 \cdot \boldsymbol{\rho}_{gc} - \frac{e}{2c} \boldsymbol{\rho}_{gc} \cdot \nabla \mathbf{A}_1 \cdot \boldsymbol{\rho}_{gc}$$

* Hamiltonian representation ($\Lambda_{1gc} \equiv -H_{1gc} dt$)

$$H_{1gc} = e \left(\phi_1 - \frac{1}{c} \mathbf{A}_1 \cdot \frac{dgc \mathbf{X}}{dt} \right) \\ - e \rho_{gc} \cdot \left[\mathbf{E}_1 + \frac{1}{c} \left(\frac{dgc \mathbf{X}}{dt} + \frac{1}{2} \frac{dgc \rho_{gc}}{dt} \right) \times \mathbf{B}_1 \right]$$

* First-order gyrocenter Hamiltonian $H_{1gy} \equiv \langle H_{1gc} \rangle$

$$H_{1gy} = e\left(\phi_{1} - \frac{1}{c}\mathbf{A}_{1} \cdot \frac{d_{gc}\mathbf{X}}{dt}\right)$$
$$- e\left\langle\rho_{gc}\right\rangle \cdot \left(\mathbf{E}_{1} + \frac{1}{c}\frac{d_{gc}\mathbf{X}}{dt} \times \mathbf{B}_{1}\right)$$
$$- \frac{e}{2c}\left\langle\rho_{gc} \times \frac{d_{gc}\rho_{gc}}{dt}\right\rangle \cdot \mathbf{B}_{1}$$

• Guiding-center Electric-dipole Moment

$$\pi_{ extsf{gc}} \equiv -rac{\partial H_{1 extsf{gy}}}{\partial extsf{E}_1} = e \left<
ho_{ extsf{gc}}
ight>$$

• Guiding-center Magnetic-dipole Moment

$$\mu_{\rm gc} \equiv -\frac{\partial H_{\rm 1gy}}{\partial B_{\rm 1}} = \frac{e}{c} \langle \rho_{\rm gc} \rangle \times \frac{d_{\rm gc} \mathbf{X}}{dt} + \frac{e}{2c} \left\langle \rho_{\rm gc} \times \frac{d_{\rm gc} \rho_{\rm gc}}{dt} \right\rangle$$

- Push-Forward Formulation
- Guiding-center Polarization

$$\mathbf{P}_{gc} \equiv \sum e \int \overline{F} \langle \boldsymbol{\rho}_{gc} \rangle d^{3}P - \nabla \cdot \left[\sum \frac{e}{2} \int \overline{F} \left\langle \boldsymbol{\rho}_{gc} \boldsymbol{\rho}_{gc} \right\rangle d^{3}P \right] + \cdots$$

 \star Lowest-order contribution

$$\mathbf{P}_{gc}^{(1)} = \epsilon_B \sum e \int \overline{F} \left[\langle \boldsymbol{\rho}_1 \rangle - \nabla \cdot \left(\frac{1}{2} \langle \boldsymbol{\rho}_0 \boldsymbol{\rho}_0 \rangle \right) \right] d^3 P$$
$$- \epsilon_F \sum \frac{e}{2} \int \left\langle \boldsymbol{\rho}_0 \boldsymbol{\rho}_0 \right\rangle \cdot \nabla \overline{F} d^3 P$$

* Lie-transform perturbation analysis

$$\langle \boldsymbol{\rho}_1 \rangle \ - \ \nabla \cdot \left(\frac{1}{2} \left\langle \boldsymbol{\rho}_0 \, \boldsymbol{\rho}_0 \right\rangle \right) \ = \ \frac{\widehat{\mathbf{b}}}{\Omega} \times \left[\frac{d_1 \mathbf{X}}{dt} \ - \ \frac{c}{e} \, \nabla \times \left(\frac{1}{2} \, \mu \, \widehat{\mathbf{b}} \right) \right]$$

* Guiding-center Polarization

$$\mathbf{P}_{gc}^{(1)} \equiv \sum \frac{\widehat{\mathbf{b}}}{\Omega} \times \left[\int \overline{F} \left(e \frac{d_1 \mathbf{X}}{dt} \right) d^3 P - c \nabla \times \left(\frac{1}{2} \int \mu \widehat{\mathbf{b}} \, \overline{F} \, d^3 P \right) \right]$$

Guiding-center polarization is often ignored in standard gyrokinetic theory.

• Guiding-center Magnetization

$$\mathbf{M}_{gc} \equiv \sum \frac{e}{c} \int \overline{F} \left(\frac{1}{2} \left\langle \rho_{gc} \times \frac{d_{gc} \rho_{gc}}{dt} \right\rangle + \left\langle \rho_{gc} \right\rangle \times \frac{d_{gc} \mathbf{X}}{dt} \right) d^{3}P$$

* Standard parallel guiding-center magnetization

$$\mathbf{M}_{gc}^{(0)} \equiv -\left(\sum \int \overline{F} \,\mu \, d^{3}P\right) \,\widehat{\mathbf{b}}$$

LINEAR AND NONLINEAR GYROCENTER POLARIZATION

• Gyrocenter Hamiltonian (Mishchenko & Brizard, 2011)

$$H_{gy} = H_{gc} + \epsilon e \langle \Phi_{1gc} \rangle - \frac{\epsilon^2}{2} e \left\langle \left\{ S_1, \Phi_{1gc} \right\}_{gc} \right\rangle \\ + \epsilon^3 \left[\frac{e}{2} \left\langle \left\{ S_1, \{S_1, \langle \Phi_{1gc} \rangle \}_{gc} \right\}_{gc} \right\rangle \\ + \frac{e}{3} \left\langle \left\{ S_1, \{S_1, \{S_1, \widetilde{\Phi}_{1gc} \}_{gc} \right\}_{gc} \right\rangle \right] + \cdots \right.$$

• Gyrocenter Generating Functions

$$\frac{d_{gc}S_{1}}{dt} = e \widetilde{\Phi}_{1gc} \rightarrow S_{1} = \left(\frac{d_{0}}{dt}\right)^{-1} e \widetilde{\Phi}_{1gc} \simeq \frac{e}{\Omega} \int \widetilde{\Phi}_{1gc} d\theta$$
$$\frac{d_{gc}S_{2}}{dt} = -\frac{e}{2} \left(\left\{S_{1}, \Phi_{1gc}\right\}_{gc} - \left\langle\left\{S_{1}, \Phi_{1gc}\right\}_{gc}\right\rangle\right) - e \left\{S_{1}, \left\langle\Phi_{1gc}\right\rangle\right\}_{gc}$$

Variational Derivation

$$\epsilon^{-1} \frac{\delta H_{gy}}{\delta \Phi_{1}(\mathbf{r})} \equiv e \left\langle \mathsf{T}_{gy}^{-1} \delta_{gc}^{3} \right\rangle$$
$$= e \left\langle \delta_{gc}^{3} \right\rangle - \epsilon e \left\langle \left\{ S_{1}, \delta_{gc}^{3} \right\}_{gc} \right\rangle$$
$$- \epsilon^{2} \left[e \left\langle \left\{ S_{2}, \delta_{gc}^{3} \right\}_{gc} \right\rangle - \frac{e}{2} \left\langle \left\{ S_{1}, \{S_{1}, \delta_{gc}^{3}\}_{gc} \right\}_{gc} \right\rangle \right]$$

Guiding-center (1st Hamiltonian)
 + Linear gyrocenter (2nd Hamiltonian)
 + Nonlinear gyrocenter (3rd Hamiltonian)

• Linear (First-order) Displacement $(gc \leftrightarrow gy)$

$$\rho_{1gy} \equiv -\underbrace{\left\langle \left\{ S_{1}, \rho_{gc} \right\}_{gc} \right\rangle}_{\epsilon, \epsilon_{B} \epsilon, \cdots} \rightarrow -\frac{\partial}{\partial J} \left\langle \rho_{gc} \frac{\partial S_{1}}{\partial \theta} \right\rangle + \cdots \simeq \frac{e \operatorname{E}_{1 \perp}}{m \Omega^{2}}$$

• Cubic Gyrocenter Hamiltonian

$$H_{3gy} \rightarrow \frac{e^3}{2\Omega^2} \frac{\partial}{\partial J} \left\langle \left(\widetilde{\Phi}_{1gc}\right)^2 \frac{\partial \Phi_{1gc}}{\partial J} \right\rangle \simeq -\frac{e}{2} \mathbf{E}_{1\perp} \cdot \nabla_{\perp} \left(\frac{1}{2} |\boldsymbol{\rho}_{1gy}|^2\right)$$

• Nonlinear (Second-order) Polarization

$$\pi_{2gy} = -\frac{e}{2} \Big[\rho_{1gy} \big(\nabla_{\perp} \cdot \rho_{1gy} \big) - \rho_{1gy} \cdot \nabla_{\perp} \rho_{1gy} \Big]$$

• Eikonal-averaged Gyrocenter Polarization

$$\left\langle \pi_{2gy} \right\rangle_{\Theta} = e \, \mathbf{k}_{\perp} \times \left(i \, \overline{\rho}_{1gy} \times \overline{\rho}_{1gy}^{*} \right) \propto m^{2}$$

 \rightarrow Compare with Oscillation-center Polarization

$$\overline{\pi}_{2\text{oc}} = e \,\mathbf{k} \times \left(i \,\overline{\boldsymbol{\xi}}_1 \times \overline{\boldsymbol{\xi}}_1^*\right) \propto m^{-2}$$

SUMMARY

- Polarization and magnetization effects arise as a result of dynamical reduction by phase-space transformation.
- Guiding-center polarization was calculated from higherorder guiding-center Hamiltonian theory.
- Nonlinear gyrocenter polarization is homologous to oscillation-center polarization.

 Polarization effects in turbulent tokamak plasmas (Wang & Hahm, 2009)

