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CIPP

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a) $H = (m^2c^4 + c^2p^2)^{\frac{1}{2}} - e\phi(r)$

$$\frac{dH}{dt} = \frac{1}{2} (m^2c^4 + c^2p^2)^{-\frac{1}{2}} \cdot 2c^2 \cdot \vec{p} \cdot \frac{d\vec{p}}{dt} - e \frac{d\phi(r)}{dr} \cdot \frac{dr}{dt}$$

$$= c^2 (m^2c^4 + c^2p^2)^{-\frac{1}{2}} \cdot \vec{p} \cdot \frac{d\vec{p}}{dt} + e\dot{r}V_r$$

$$\frac{d\vec{p}}{dt} = -e \left[\dot{r} \vec{e}_r + \frac{\vec{v} \times \vec{B}}{c} \right]$$

$$\vec{p} \cdot \frac{d\vec{p}}{dt} = -e \gamma m_e \vec{v} \cdot \left[\dot{r} \vec{e}_r + \frac{\vec{v} \times \vec{B}}{c} \right]$$

$$= -e\dot{r} \gamma m_e v_r$$

$$\frac{dH}{dt} = c^2 (m^2c^4 + c^2p^2)^{-\frac{1}{2}} \cdot \vec{p} \cdot \frac{d\vec{p}}{dt} + e\dot{r}V_r$$

$$= -e\dot{r} \gamma m_e v_r + e\dot{r}V_r = 0$$

$$\frac{d\tilde{p}_\theta}{dt} = \frac{d}{dt} r \left(p_\theta - \frac{e}{c} A_\theta(r) \right)$$

\tilde{p}_θ means the canonical angular momentum

$$= r \frac{dp_\theta}{dt} + v_r p_\theta - \underbrace{\frac{e}{c} \cdot \frac{d}{dr} (r A_\theta(r))}_{-\frac{e}{c} r B_z(r)}$$

The tricky thing lies in the derivative of $\frac{dp_\theta}{dt}$, I should point out. $\left(\frac{d\vec{p}}{dt}\right)_\theta \neq \frac{dp_\theta}{dt}$, because in the cylindrical coordinates, $\hat{e}_r, \hat{e}_\theta$ are not constant,

$$\frac{d\hat{e}_r}{d\theta} = \hat{e}_\theta, \quad \frac{d\hat{e}_\theta}{d\theta} = -\hat{e}_r$$

$$\frac{d\hat{e}_r}{d\theta} \cdot \frac{d\theta}{dt} = v_\theta \hat{e}_\theta$$

$$\text{so } \left(\frac{d\vec{p}}{dt}\right)_\theta = \frac{dp_\theta}{dt} \hat{e}_\theta + v m_e v_r \frac{d\hat{e}_r}{dt} = \left(\frac{dp_\theta}{dt} + v m_e v_r v_\theta\right) \hat{e}_\theta$$

according to momentum equation.

$$\left(\frac{d\vec{p}}{dt}\right)_\theta = \frac{e}{c} v_r B_z(r)$$

$$\frac{dp_\theta}{dt} = \frac{e}{c} v_r B_z(r) - v m_e v_r v_\theta$$

$$\frac{d\vec{p}_\theta}{dt} = r \left(\frac{e}{c} v_r B_z(r) - v m_e v_r v_\theta \right) + r v m_e v_\theta v_r - \frac{e}{c} r v_r B_z(r)$$

$$= 0$$