

Jan 2004 #3 (QM)

In the S_z basis, $|\psi(0)\rangle \rightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ magnetic moment μ
 at $t=0$, $\vec{B} = B\hat{y}$ is turned on

a. $\langle \vec{S}(t) \rangle = \langle S_x \rangle \hat{x} + \langle S_y \rangle \hat{y} + \langle S_z \rangle \hat{z}$

method 1) Direct calculation of $|\psi(t)\rangle$ by using the S_y basis

$$H = -\vec{\mu} \cdot \vec{B} = -\gamma \vec{S} \cdot \vec{B}$$

$$H = -\gamma B S_y$$

$$S_y = \frac{\hbar}{2} \sigma_y = \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

Diagonalize S_y : $\begin{bmatrix} -\lambda & -i\frac{\hbar}{2} \\ i\frac{\hbar}{2} & -\lambda \end{bmatrix}$, $\lambda^2 - (\frac{\hbar}{2})^2 = 0$, $\lambda = \pm \frac{\hbar}{2}$

eigenvector with $\lambda = \frac{\hbar}{2}$: $-\frac{\hbar}{2}x_1 - i\frac{\hbar}{2}x_2 = 0$, $ix_2 = -x_1$, $x_2 = -ix_1$, $|\psi_{y+}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$

$|\psi_{y-}\rangle$: $x_1 - ix_2 = 0$, $x_2 = -ix_1$, $|\psi_{y-}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}$

$|\psi(0)\rangle = \frac{1}{\sqrt{2}} (|\psi_{y+}\rangle + |\psi_{y-}\rangle)$ energy of $|\psi_{y+}\rangle = -\frac{\gamma B \hbar}{2}$

$|\psi_{y-}\rangle = \frac{\gamma B \hbar}{2}$, $\omega = \gamma B$

$$|\psi(t)\rangle = \frac{1}{\sqrt{2}} (|\psi_{y+}\rangle e^{i\omega t/2} + |\psi_{y-}\rangle e^{-i\omega t/2})$$

$$\rightarrow \frac{1}{2} \left[\begin{pmatrix} e^{i\omega t/2} \\ i e^{i\omega t/2} \end{pmatrix} + \begin{pmatrix} e^{-i\omega t/2} \\ -i e^{-i\omega t/2} \end{pmatrix} \right] = \begin{bmatrix} \cos \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} \end{bmatrix}$$

method 2) Calculate $|\psi(t)\rangle$ using the Propagator in the S_z basis

$$U(t) = e^{-iHt/\hbar} = e^{i\gamma \vec{S} \cdot \vec{B} t/\hbar}$$

$\exp(-i\vec{\theta} \cdot \vec{S}/\hbar)$ is the operator that rotates by $\vec{\theta}$, so U rotates by angle

$$\vec{\theta} = -\gamma \vec{B} t$$

$$U(t) = \exp(i\gamma t S_y B/\hbar) = \exp(i\gamma t B \sigma_y/2)$$
 let $\omega = \gamma B$

$$\sigma_y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \quad \sigma_y^2 = I$$

$$U(t) = I + \frac{i\omega t \sigma_y}{2} + \frac{1}{2!} \left(\frac{\omega t}{2}\right)^2 - \frac{i}{3!} \left(\frac{\omega t}{2}\right)^3 + \dots$$

$$= I \left(1 - \frac{1}{2!} \left(\frac{\omega t}{2}\right)^2 + \dots\right) + i\sigma_y \left(\frac{\omega t}{2} - \frac{1}{3!} \left(\frac{\omega t}{2}\right)^3 + \dots\right)$$

$$|\psi(t)\rangle = \mathbb{I} \cos \frac{\omega t}{2} + i \sigma_y \sin \frac{\omega t}{2} \xrightarrow{S_z \text{ basis}} \begin{bmatrix} \cos \frac{\omega t}{2} & \sin \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} & \cos \frac{\omega t}{2} \end{bmatrix}$$

$$|\psi(t)\rangle = U(t) |\psi(0)\rangle$$

$$\rightarrow \begin{bmatrix} \cos \frac{\omega t}{2} & \sin \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} & \cos \frac{\omega t}{2} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} \end{bmatrix}$$

Now with $|\psi(t)\rangle$ known, it is simple to calculate $\langle \vec{S} \rangle$

$$\begin{aligned} \langle S_x \rangle &= \langle \psi | S_x | \psi \rangle = \frac{\hbar}{2} (\cos \frac{\omega t}{2} \quad -\sin \frac{\omega t}{2}) \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} \cos \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} \end{pmatrix} \\ &= \frac{\hbar}{2} (\cos \frac{\omega t}{2} \quad -\sin \frac{\omega t}{2}) \begin{pmatrix} -\sin \frac{\omega t}{2} \\ \cos \frac{\omega t}{2} \end{pmatrix} = -\frac{\hbar}{2} \cos \frac{\omega t}{2} \sin \frac{\omega t}{2} = -\frac{\hbar}{2} \sin \omega t \end{aligned}$$

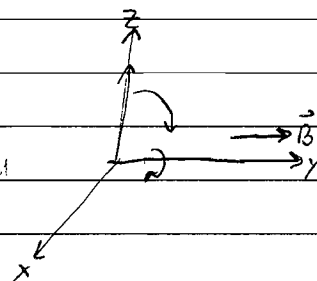
$$\langle S_y \rangle = \langle \psi | S_y | \psi \rangle = \frac{\hbar}{2} (\cos \frac{\omega t}{2} \quad -\sin \frac{\omega t}{2}) \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{pmatrix} \cos \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} \end{pmatrix} = 0$$

$$\begin{aligned} \langle S_z \rangle &= \langle \psi | S_z | \psi \rangle = \frac{\hbar}{2} (\cos \frac{\omega t}{2} \quad -\sin \frac{\omega t}{2}) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \frac{\omega t}{2} \\ -\sin \frac{\omega t}{2} \end{pmatrix} \\ &= \frac{\hbar}{2} (\cos \frac{\omega t}{2} \quad -\sin \frac{\omega t}{2}) \begin{pmatrix} \cos \frac{\omega t}{2} \\ \sin \frac{\omega t}{2} \end{pmatrix} = \frac{\hbar}{2} (\cos^2 \frac{\omega t}{2} - \sin^2 \frac{\omega t}{2}) \end{aligned}$$

$$= \frac{\hbar}{2} \cos \omega t$$

$$\langle \vec{S} \rangle = \frac{\hbar}{2} (\cos \omega t \hat{z} - \sin \omega t \hat{x})$$

Some precession: as classically predicted
($\vec{\tau} = -\vec{\mu} \times \vec{B}$)



$$b. P(\text{spin down}) = |\langle \psi_{z-} | \psi(t) \rangle|^2$$

$$\langle \psi_{z-} | \psi(t) \rangle = (0 \quad 1) \begin{pmatrix} \cos \frac{\omega T}{2} \\ -\sin \frac{\omega T}{2} \end{pmatrix} = -\sin \frac{\omega T}{2}$$

$$P = \sin^2 \frac{\omega T}{2}$$

$$c. \text{ at } t = \frac{T}{2}, \quad P(\text{spin up}) = \cos^2 \frac{\omega T}{4} \quad P(\text{spin down}) = \sin^2 \frac{\omega T}{4}$$

Probability that at $t=T$, spin is down?

$$P = P(\text{spin up at } \frac{T}{2}) \cdot P(\text{down at } T \mid \text{up at } \frac{T}{2}) + P(\text{down at } \frac{T}{2}) \cdot P(\text{down at } T \mid \text{down at } \frac{T}{2})$$

$$P(\text{down at } T \mid \text{up at } \frac{T}{2}):$$

$$|\psi(\frac{T}{2})\rangle \rightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\hookrightarrow |\psi(T)\rangle = U(T, \frac{T}{2}) |\psi(\frac{T}{2})\rangle$$

$$\text{and } U(T, \frac{T}{2}) = U(\frac{T}{2}, 0) \quad [H \text{ not dependent on time}]$$

$$\Rightarrow |\psi(T)\rangle \rightarrow \begin{pmatrix} \cos \frac{\omega T}{4} \\ -\sin \frac{\omega T}{4} \end{pmatrix}$$

$$P(\text{down at } T \mid \text{up at } \frac{T}{2}) = \sin^2 \frac{\omega T}{4}$$

$$P(\text{down at } T \mid \text{down at } \frac{T}{2})$$

$$|\psi(\frac{T}{2})\rangle \rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\hookrightarrow |\psi(T)\rangle = U(T, \frac{T}{2}) |\psi(\frac{T}{2})\rangle \rightarrow \begin{pmatrix} \cos \frac{\omega T}{4} & \sin \frac{\omega T}{4} \\ -\sin \frac{\omega T}{4} & \cos \frac{\omega T}{4} \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \sin \frac{\omega T}{4} \\ \cos \frac{\omega T}{4} \end{pmatrix}$$

$$P(\text{down at } T \mid \text{down at } \frac{T}{2}) = \cos^2 \frac{\omega T}{4}$$

$$P(\text{down at } T) = \cos^2 \frac{\omega T}{4} \cdot \sin^2 \frac{\omega T}{4} + \sin^2 \frac{\omega T}{4} \cdot \cos^2 \frac{\omega T}{4}$$

$$= 2 (\sin^2 \frac{\omega T}{4} \cos^2 \frac{\omega T}{4}) = \frac{1}{2} \sin^2 \frac{\omega T}{2}$$