Generals Exam 2007, Part II, Problem 2 The Rayleigh-Taylor Instability and the Energy Principle (MHD)

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The goal here is to analyze the stability of a slab-geometry plasma supported against a gravitational force by a magnetic field. In Cartesian coordinates, the gravitational force $\rho \mathbf{g}$ is defined to be x-directed such that

$$\rho \mathbf{g} = -\rho g \mathbf{\hat{e}}_x. \tag{1}$$

The magnetic field is perpendicular to the gravitational force. Thus, it is defined to be z-directed, and it is assumed to vary only along the direction of the gravitational force such that

$$\mathbf{B} = B(x)\hat{\mathbf{e}}_z.$$

Part (a)

Examine the momentum equation, which has been modified to include the gravitational force:

$$\rho \frac{d\mathbf{v}}{dt} = \mathbf{J} \times \mathbf{B} - \nabla p + \rho \mathbf{g}.$$
(3)

The pressure gradient is zero because the plasma is assumed to be cold (p = 0). In equilibrium the time derivative will vanish, leaving the simple equilibrium force balance equation

$$-\rho \mathbf{g} = \mathbf{J} \times \mathbf{B}.\tag{4}$$

Rewriting **J** using Ampère's Law ($\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$) and substituting for the gravitational force from Equation 1, the equilibrium force balance equation becomes

$$\rho \mathbf{g} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B} = -\frac{1}{\mu_0} \mathbf{B} \times \left[\left(\frac{\partial}{\partial x} \hat{\mathbf{e}}_x + \frac{\partial}{\partial y} \hat{\mathbf{e}}_y + \frac{\partial}{\partial z} \hat{\mathbf{e}}_z \right) \times B \hat{\mathbf{e}}_z \right] \\ = -\frac{1}{\mu_0} (B \hat{\mathbf{e}}_z) \times \left[-\frac{\partial B}{\partial x} \hat{\mathbf{e}}_y + \frac{\partial B}{\partial y} \hat{\mathbf{e}}_x \right] = \frac{1}{\mu_0} B B' \hat{\mathbf{e}}_x, \tag{5}$$

where the convention $\partial B/\partial x = B'$ has been adopted. Noting that this vector equation reduces to a scalar equation because $\mathbf{g} = -g\hat{\mathbf{e}}_x$, the final equilibrium force balance equation is simply

$$\rho g = -\frac{BB'}{\mu_0} \tag{6}$$

Part (b)

The energy principle integral modified to include the effect gravitational force is given in the problem to be

$$\delta W = \frac{1}{2} \int_{V} d^{3} \mathbf{r} \left[\gamma p |\nabla \cdot \boldsymbol{\xi}|^{2} - \boldsymbol{\xi}^{*} \cdot \nabla (\boldsymbol{\xi} \cdot \nabla p) + \frac{1}{\mu_{0}} |Q|^{2} - \boldsymbol{\xi}^{*} \cdot \mathbf{J} \times \mathbf{Q} + \boldsymbol{\xi}^{*} \cdot \mathbf{g} \nabla \cdot (\rho \boldsymbol{\xi}) \right], \quad (7)$$

where

$$\mathbf{Q} \equiv \nabla \times (\boldsymbol{\xi} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\boldsymbol{\xi} - \mathbf{B}(\nabla \cdot \boldsymbol{\xi}) - (\boldsymbol{\xi} \cdot \nabla)\mathbf{B}.$$
(8)

The necessary and sufficient condition for stability is $\delta W \ge 0$. The first two terms in Equation 7 vanish in the cold plasma limit because they both include a factor of p. This leaves the δW integral as

$$\delta W = \frac{1}{2} \int_{V} d^{3} \mathbf{r} \left[\frac{1}{\mu_{0}} |Q|^{2} - \boldsymbol{\xi}^{*} \cdot \mathbf{J} \times \mathbf{Q} + \boldsymbol{\xi}^{*} \cdot \mathbf{g} \nabla \cdot (\rho \boldsymbol{\xi}) \right].$$
(9)

The form of the most destabilizing displacement $\pmb{\xi}$ is given in the problem to be

$$\boldsymbol{\xi} = \tilde{\boldsymbol{\xi}}(x)e^{iky} \tag{10}$$

Note that this form of $\boldsymbol{\xi}$ is independent of z such that no energy from the displacement is expended in bending fieldlines. The mathematical equivalent of this no-fieldline-bending statement is that $(\mathbf{B} \cdot \nabla)\boldsymbol{\xi} = 0$. The expression for \mathbf{Q} now reduces to

$$\mathbf{Q} = -\mathbf{B}(\nabla \cdot \boldsymbol{\xi}) - (\boldsymbol{\xi} \cdot \nabla)\mathbf{B}.$$
(11)

To minimize δW , select the components of $\boldsymbol{\xi}$ such that $\mathbf{Q} = 0$. This ensures that the most possible free energy remains to drive the instability. Substituting Equations 2 and 10 into Equation 11 gives

$$\mathbf{Q} = -B\left[\frac{\partial\xi_x}{\partial x} + ik\xi_y\right]\hat{\mathbf{e}}_z - \xi_x\frac{\partial B}{\partial x}\hat{\mathbf{e}}_z = -\left[B(\xi'_x + ik\xi_y) + \xi_xB'\right]\hat{\mathbf{e}}_z = 0$$
(12)

Solving for ξ_y gives

$$\xi_y = -\frac{1}{ikB} \bigg[B\xi'_x + \xi_x B' \bigg] \tag{13}$$

With the assertion that $\mathbf{Q} = 0$, the energy principle integral reduces to

$$\delta W = \frac{1}{2} \int_{V} d^{3} \mathbf{r} \left[\boldsymbol{\xi}^{*} \cdot \mathbf{g} \nabla \cdot (\rho \boldsymbol{\xi}) \right].$$
(14)

Defining the integrand as \mathcal{I} and expanding gives

$$\mathcal{I} \equiv \boldsymbol{\xi}^* \cdot \mathbf{g} \nabla \cdot (\rho \boldsymbol{\xi}) = -\xi_x^* g \nabla \cdot (\rho \boldsymbol{\xi}) = -\xi_x^* \nabla \cdot (\rho g \boldsymbol{\xi}).$$
(15)

Substituting for ρg in the above expression from the equilibrium condition in Equation 6:

$$\mathcal{I} = -\xi_x^* \nabla \cdot \left(\rho g \boldsymbol{\xi}\right) = -\xi_x^* \nabla \cdot \left(-\frac{BB'}{\mu_0} \boldsymbol{\xi}\right) = \xi_x^* \left[\frac{\partial}{\partial x} \left(\frac{BB'}{\mu_0} \xi_x\right) + \frac{\partial}{\partial y} \left(\frac{BB'}{\mu_0} \xi_y\right)\right].$$
(16)

Breaking out the above equation and evaluating the individual terms gives

$$\frac{\partial}{\partial x} \left(\frac{BB'}{\mu_0} \xi_x \right) = \frac{1}{\mu_0} \left[(B')^2 \xi_x + BB'' \xi_x + BB' \xi'_x \right]$$
(17)

$$\frac{\partial}{\partial y} \left(\frac{BB'}{\mu_0} \xi_y \right) = \frac{1}{\mu_0} i k B B' \xi_y. \tag{18}$$

Substituting ξ_y from Equation 13 into the latter expression above gives

$$\frac{\partial}{\partial y} \left(\frac{BB'}{\mu_0} \xi_y \right) = \frac{1}{\mu_0} ikBB' \xi_y = \frac{B'}{\mu_0} ikB \left(-\frac{1}{ikB} \left[B\xi'_x + \xi_x B' \right] \right) = -\frac{1}{\mu_0} \left[BB' \xi'_x + \xi_x (B')^2 \right].$$
(19)

Folding Equations 17 and 19 back into Equation 16 gives

$$\mathcal{I} = \xi_x^* \left\{ \frac{1}{\mu_0} \left[(B')^2 \xi_x + BB'' \xi_x + BB'' \xi_x^{\prime} \right] - \frac{1}{\mu_0} \left[BB' \xi_x^{\prime} + \xi_x (B')^2 \right] \right\} = \frac{|\xi_x|^2}{\mu_0} BB''.$$
(20)

The condition that $\mathcal{I} \geq 0$ is equivalent to the energy principle condition for stability ($\delta W \geq 0$). Because $|\xi_x|^2 \geq 0$, the derived stability condition for the Rayleigh-Taylor instability is simply

$$BB'' \ge 0. \tag{21}$$

This condition can be placed in an alternate form using the equilibrium condition in Equation 6, which gives B' to be

$$B' = -\frac{\mu_0 \rho g}{B} \tag{22}$$

such that

$$B'' = \frac{\partial}{\partial x} \left(-\frac{\mu_0 \rho g}{B} \right) = -\frac{\mu_0 \rho g}{B} \left[\frac{\rho'}{\rho} - \frac{B'}{B} \right].$$
(23)

Substituting back into the stability condition in Equation 21 gives

$$BB'' = \mathscr{B}\left\{-\frac{\mu_0\rho g}{\mathscr{B}}\left[\frac{\rho'}{\rho} - \frac{B'}{B}\right]\right\} = -\mu_0\rho g\left[\frac{\rho'}{\rho} - \frac{B'}{B}\right] \ge 0$$
(24)

Noting that

$$\frac{\partial}{\partial x}\ln\left(\frac{\rho}{B}\right) = \frac{\rho'}{\rho} - \frac{B'}{B},\tag{25}$$

and that

$$\mathbf{g} \cdot \nabla = -g \frac{\partial}{\partial x},\tag{26}$$

the stability condition can be rewritten in its final form as

$$\mathbf{g} \cdot \nabla \ln\left(\frac{\rho}{B}\right) \ge 0.$$
 (27)