

$$1. \frac{\partial F(u)}{\partial x} = A \frac{\partial u}{\partial x} \quad U_j^* = U_j^n - \frac{\delta t}{\delta x} A [U_j^n - U_{j-1}^n]$$

$$\Rightarrow U_j^{n+1} = \frac{1}{2} \left\{ U_j^n + U_j^n - \frac{\delta t}{\delta x} A [U_j^n - U_{j-1}^n] - \frac{\delta t}{\delta x} A \left[ U_j^n - \frac{\delta t}{\delta x} A [U_j^n - U_{j-1}^n] - U_{j-1}^n + \frac{\delta t}{\delta x} A [U_{j-1}^n - U_{j-2}^n] \right] - \frac{\delta t}{\delta x} A [U_j^n - 2U_{j-1}^n + U_{j-2}^n] \right\}$$

$$U_j^{n+1} = U_j^n - \frac{\delta t}{2\delta x} A [3U_j^n - 4U_{j-1}^n + U_{j-2}^n] + \frac{1}{2} \left( \frac{\delta t}{\delta x} \right)^2 A^2 [U_j^n - 2U_{j-1}^n + U_{j-2}^n]$$

Truncation error:

$$U_j^{n+1} = U_j^n + \delta t \frac{\partial u}{\partial t} + \frac{1}{2} \delta t^2 \frac{\partial^2 u}{\partial t^2} + \frac{1}{6} \delta t^3 \frac{\partial^3 u}{\partial t^3} + \dots$$

$$U_{j-1}^n = U_j^n - \delta x \frac{\partial u}{\partial x} + \frac{1}{2} \delta x^2 \frac{\partial^2 u}{\partial x^2} - \frac{1}{6} \delta x^3 \frac{\partial^3 u}{\partial x^3} + \frac{1}{24} \delta x^4 \frac{\partial^4 u}{\partial x^4} + \dots$$

$$U_{j-2}^n = U_j^n - 2\delta x \frac{\partial u}{\partial x} + 2\delta x^2 \frac{\partial^2 u}{\partial x^2} - \frac{4}{3} \delta x^3 \frac{\partial^3 u}{\partial x^3} + \frac{2}{3} \delta x^4 \frac{\partial^4 u}{\partial x^4} + \dots$$

$$\frac{U_j^{n+1} - U_j^n}{\delta t} = \frac{\partial u}{\partial t} + \frac{1}{2} \delta t \frac{\partial^2 u}{\partial t^2} + \frac{1}{6} \delta t^2 \frac{\partial^3 u}{\partial t^3} + \dots$$

$$\frac{3U_j^n - 4U_{j-1}^n + U_{j-2}^n}{2\delta x} = \frac{\partial u}{\partial x} - \frac{1}{3} \delta x^2 \frac{\partial^3 u}{\partial x^3} + \dots$$

$$\frac{U_j^n - 2U_{j-1}^n + U_{j-2}^n}{\delta x^2} = \frac{\partial^2 u}{\partial x^2} - \delta x \frac{\partial^3 u}{\partial x^3} + \dots$$

Plugging these in, we have

$$\frac{\partial u}{\partial t} + \frac{1}{2} \delta t \frac{\partial^2 u}{\partial t^2} + \frac{1}{6} \delta t^2 \frac{\partial^3 u}{\partial t^3} + \dots = A \frac{\partial u}{\partial x} - \frac{1}{3} \delta x^2 A \frac{\partial^3 u}{\partial x^3} + A^2 \frac{1}{2} \delta t \frac{\partial^2 u}{\partial x^2} - A^2 \delta x \delta t \frac{\partial^3 u}{\partial x^3} + \dots$$

$$\frac{\partial u}{\partial t} = -A \frac{\partial u}{\partial x} \Rightarrow \frac{\partial^2 u}{\partial t^2} = -A \frac{\partial}{\partial x} \frac{\partial u}{\partial t} = A^2 \frac{\partial^2 u}{\partial x^2}$$

$\Rightarrow$  2nd order accurate in time & space

Cancellation of  $O(\delta t)$  term

2. Let  $s = \frac{\delta t}{\delta x} A$        $U_j^n \rightarrow r^n \tilde{U}_k e^{i j \theta}$

$$r = 1 - \frac{s}{2} [3 - 4e^{-i\theta} + e^{-2i\theta}] + \frac{s^2}{2} [1 - 2e^{-i\theta} + e^{-2i\theta}]$$

Require  $|r| < 1$  for stability. Check at  $\theta = 0, \frac{\pi}{2}, \pi$  {this always works as far as I know}

at  $\theta = 0$ :  $r = 1 - \frac{s}{2} [3 - 4 + 1] + \frac{s^2}{2} [1 - 2 + 1]$        $r = 1$

at  $\theta = \frac{\pi}{2}$ :  $r = 1 - \frac{s}{2} [3 + 4i - 1] + \frac{s^2}{2} [1 + 2i - 1] = 1 - \frac{s}{2} [2 + 4i] + s^2 i$

$$r = 1 - s + i s (s - 2)$$

$$|r|^2 = (1 - s)^2 + s^2 (s - 2)^2$$

$$|r|^2 < 1: 1 - 2s + s^2 + s^4 - 4s^3 + 4s^2 < 1$$

$$s^3 - 4s^2 + 5s - 2 < 0$$

$$\Rightarrow (s-1)(s-1)(s-2) < 0 \Rightarrow (s-1)^2 (s-2) < 0$$

$$\rightarrow s < 2 \quad \text{or} \quad \delta t < \frac{2\delta x}{A}$$

at  $\theta = \pi$ :  $r = 1 - \frac{s}{2} [3 + 4 + 1] + \frac{s^2}{2} [1 + 2 + 1]$

$$r = 1 - 4s + 2s^2$$

$$r < 1: 1 - 4s + 2s^2 < 1$$

$$2s^2 - 4s < 0$$

$$s < 2$$

same condition

$$\boxed{\delta t < \frac{2\delta x}{A}}$$

3. advantages: explicit method, simple. 2<sup>nd</sup> order accurate

disadvantages: For stability, a small timestep is required at small  $\delta x$ .

But: at least it can be stable, as compared with FTCS which is unstable.