

$$\vec{J}_\perp \times \vec{B} = \vec{\nabla} P \rightarrow \vec{\nabla} \times (\vec{J}_\perp \times \vec{B}) = \vec{\nabla} \times (\vec{\nabla} P) = 0$$

$$\vec{J}_\perp (\vec{\nabla} \cdot \vec{B}) - \vec{B} (\vec{\nabla} \cdot \vec{J}_\perp) + (\vec{B} \cdot \vec{\nabla}) \vec{J}_\perp - (\vec{J}_\perp \cdot \vec{\nabla}) \vec{B} = 0$$

$$-\vec{B} (\vec{\nabla} \cdot \vec{J}_\perp) + \vec{\nabla} (\vec{J}_\perp \cdot \vec{B}) - \vec{J}_\perp \times (\vec{\nabla} \times \vec{B}) - \vec{B} \times (\vec{\nabla} \times \vec{J}_\perp) - 2(\vec{J}_\perp \cdot \vec{\nabla}) \vec{B} = 0$$

$$B^2 (\vec{\nabla} \cdot \vec{J}_\perp) = -\vec{B} \cdot [\vec{J}_\perp \times (\vec{\nabla} \times \vec{B})] - \vec{B} \cdot [\vec{B} \times (\vec{\nabla} \times \vec{J}_\perp)]$$

$$-2\vec{B} \cdot [(\vec{J}_\perp \cdot \vec{\nabla}) \vec{B}] = 0$$

$$B^2 (\vec{\nabla} \cdot \vec{J}_\perp) = -\vec{B} \cdot [\vec{J}_\perp \times \vec{J}_\parallel] - (\vec{\nabla} \times \vec{J}_\perp) \cdot (\vec{B} \times \vec{B}) - 2\vec{B} \cdot [(\vec{J}_\perp \cdot \vec{\nabla}) \vec{B}] = 0$$

$$\vec{\nabla} \cdot \vec{J}_\perp = -\frac{2\vec{B} \cdot [(\vec{J}_\perp \cdot \vec{\nabla}) \vec{B}]}{B^2}$$

$$\vec{B} = B_0 \vec{\nabla} \phi = \frac{B_0}{R} \hat{e}_\phi$$

$$\vec{\nabla} \vec{B} = \vec{\nabla} \left(\frac{B_0}{R} \hat{e}_\phi \right) = \vec{\nabla} \left(\frac{B_0}{R} \right) \hat{e}_\phi + \frac{B_0}{R} \vec{\nabla} \hat{e}_\phi$$

$$= -\frac{B_0}{R^2} \hat{e}_R \hat{e}_\phi + \frac{B_0}{R} \left[\frac{1}{R} \frac{\partial \hat{e}_\phi}{\partial \phi} \hat{e}_\phi \right] = -\frac{2B_0}{R^2} \hat{e}_R \hat{e}_\phi$$

$$\vec{J}_\perp = J_R \hat{e}_R + J_z \hat{e}_z \rightarrow \vec{J}_\perp \cdot \left[-\frac{2B_0}{R^2} \hat{e}_R \hat{e}_\phi \right] = -\frac{2B_0 J_R}{R^2} \hat{e}_\phi$$

$$\vec{\nabla} \cdot \vec{J}_1 = -\frac{2}{B^2} \vec{B} \cdot \left[\frac{-2B_0 J_R}{R^2} \hat{e}_\phi \right]$$

$$= -\frac{2}{B^2} \frac{B_0}{R} (\hat{e}_\phi \cdot \hat{e}_\phi) \frac{-2B_0 J_R}{R^2} = \frac{4B_0^2 J_R}{B^2 R^3}$$

$$= \frac{4B_0^2 J_R R^2}{R^3 B_0^2} \rightarrow \boxed{\vec{\nabla} \cdot \vec{J}_1 = \frac{4J_R}{R}}$$

$$\vec{\nabla} p = \vec{J}_\perp \times \vec{B} = \frac{1}{R} \begin{vmatrix} \hat{e}_r & R\hat{e}_\phi & \hat{e}_z \\ J_R & 0 & J_z \\ 0 & B_0 & 0 \end{vmatrix} = \left\langle -\frac{J_z B_0}{R}, 0, \frac{J_R B_0}{R} \right\rangle$$

$$= \left\langle \frac{\partial p}{\partial R}, 0, \frac{\partial p}{\partial z} \right\rangle$$

$$\frac{J_R B_0}{R} = \frac{\partial p}{\partial z}$$

$$\rightarrow \boxed{\vec{\nabla} \cdot \vec{J}_1 = \frac{4}{B_0} \frac{\partial p}{\partial z}}$$

$$\frac{\partial p}{\partial z} = -\frac{4}{B_0} \frac{\partial p}{\partial z}$$

$$\begin{array}{l} \frac{\partial p}{\partial z} < 0 \rightarrow \frac{\partial p}{\partial z} > 0 \\ \frac{\partial p}{\partial z} > 0 \rightarrow \frac{\partial p}{\partial z} < 0 \end{array}$$