

Proving the ISI algorithm

is symplectic for all iterations

1/7/2007
GWH

~~4/20~~
With Maple script, we show the argument of the
 $\sqrt{\quad}$ is the eigenvalue is!

$$\arg = (4rL\omega^2\Delta t^2 - r\omega^4\Delta t^4 + 16 + 16L)(4rL - r\omega^2\Delta t^2 - 4 - 4L)$$
$$\geq \arg_1 \arg_2$$

If we can show $\arg_1 > 0$ & $\arg_2 > 0$, then $\arg < 0$,
& ~~the~~ the eigenvalue is of the form

$$\lambda = c_1 \pm i\sqrt{|\arg|}$$

$$\text{it turns out } |\lambda|^2 = c_1^2 + |\arg| = 1$$

Start with \arg_1 !

$$\arg_1 = 4r \frac{1}{4} \omega^2 \Delta t^2 \omega^2 \Delta t^2 - r \omega^4 \Delta t^4 + 16 + 4 \omega^2 \Delta t^2$$

$$r = \lambda_1^p \quad \text{and} \quad -1 < \lambda_2 < 1 \quad \text{for convergence.}$$

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$$\lambda_2 = \frac{(\hat{\omega}^2 - \omega^2) \Delta t^2}{4 + \hat{\omega}^2 \Delta t^2}$$

$-1 < \lambda_2 < 1$ becomes:

$$-1 < \frac{(\hat{\omega}^2 - \omega^2) \Delta t^2}{4 + \hat{\omega}^2 \Delta t^2} < 1$$

$$-(4 + \hat{\omega}^2 \Delta t^2) < (\hat{\omega}^2 - \omega^2) \Delta t^2 < 4 + \hat{\omega}^2 \Delta t^2$$

This condition becomes!

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$$-\omega^2 \Delta t^2 < 4$$

which is always satisfied,

$$0 < 4 + (\hat{\omega}^2 - \omega^2) \Delta t^2 + \hat{\omega}^2 \Delta t^2$$

$$\boxed{0 < P + \hat{\omega}^2 \Delta t^2}$$

Therefore the condition that the 1st iteration be stable

$$\boxed{P = 4 + (\hat{\omega}^2 - \omega^2) \Delta t^2 > 0}$$

also ensures $|\lambda_2| < 1$ & $|r| < 1$

$$\begin{aligned}
\text{arg}_1 &= r \hat{\omega}^2 \Delta t^2 \omega^2 \Delta t^2 - r \omega^4 \Delta t^4 + 16 + 4 \hat{\omega}^2 \Delta t^2 \\
&= r \omega^2 \Delta t^2 (\hat{\omega}^2 \Delta t^2 - \omega^2 \Delta t^2) + 16 + 4 \hat{\omega}^2 \Delta t^2 \\
&= r \omega^2 \Delta t^2 (P - 4) + 16 + 4 \hat{\omega}^2 \Delta t^2 \\
&= r \omega^2 \Delta t^2 P + 16 + 4 (\hat{\omega}^2 \Delta t^2 - r \omega^2 \Delta t^2) \\
&= r \omega^2 \Delta t^2 P + 16 + 4 [P - 4 + \hat{\omega}^2 \Delta t^2 - r \omega^2 \Delta t^2] \\
&= r \omega^2 \Delta t^2 P + 4P + 4(1-r)\omega^2 \Delta t^2
\end{aligned}$$

for ~~0 < r < 1~~ $0 < r < 1$, this is clear that $\text{arg}_1 > 0$.
 (+ $P > 0$)

For $-1 < r < 0$, we have:

$$\text{arg}_1 = -|r| \omega^2 \Delta t^2 P + 4P + 4(1+|r|)\omega^2 \Delta t^2$$

However note that for $r < 0$, $\lambda_2 < 0$ there is a limit to how large P can be.

~~$$\lambda_2 = \frac{(\omega^2 \Delta t^2)^2}{\omega^2 \Delta t^2}$$~~

(4)

$$\lambda_2 = \frac{(\omega^2 - \omega^2) \Delta t^2}{4 + \omega^2 \Delta t^2} = \frac{P - 4}{P + \omega^2 \Delta t^2}$$

So if $\lambda_2 < 0$, the maximum value of P is 4!

This upper bound on P can be used to provide a lower bound on \arg_1 when $r < 0$:

~~lower bound~~ $\arg_1 \Rightarrow -|r| \omega^2 \Delta t^2 + 4P + 4(1+|r|) \omega^2 \Delta t^2$

$$\arg_1 > 4P + 4|r| \omega^2 \Delta t^2$$

So we have shown $P > 0$ is a sufficient condition for $\arg_1 > 0$ no matter what the sign of r

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Now have to prove ~~arg_z < 0~~ always.
sufficient conditions for which $\arg z < 0$.

$$\begin{aligned}\arg z &= 4rL - r\omega^2 \Delta t^2 - 4 - 4L \\ &= r\omega^2 \Delta t^2 - r\omega^2 \Delta t^2 - 4 - \omega^2 \Delta t^2 \\ &= r(P-4) - 4 - \omega^2 \Delta t^2 \\ &= r(P-4) - 4 - [P + 4 + \omega^2 \Delta t^2] \\ &= r(P-4) - P - \omega^2 \Delta t^2 \\ &= -(1-r)P - 4r - \omega^2 \Delta t^2\end{aligned}$$

Thus, if $0 < r < 1$, $P > 0$, then $\arg z < 0$.
However, for $-1 < r < 0$, we have:

$$\arg z = -(1+|r|)P + 4|r| - \omega^2 \Delta t^2$$

Since $|r| = |\lambda_2|^P \rightarrow 0$ as $P \rightarrow \infty$,
if there are enough iterations, then $\arg z < 0$.
But we ~~are~~ want a proof for arbitrary P ...

write $\arg z$ as:

$$\begin{aligned} \arg z &= -p - |r| \left[\sqrt{4 + \omega^2 \Delta t^2 - \omega^2 \Delta t^2} \right] + \cancel{4|r| - \omega^2 \Delta t^2} \\ &= -p - |r| \omega^2 \Delta t^2 - (1 - |r|) \omega^2 \Delta t^2 \end{aligned}$$

~~Thus~~ Thus $\arg z < 0$ as long as $|r| < 1$

Q.E.D.

The condition that the 1st iteration is symplectic, $4 + (\omega^2 - \omega^2) \Delta t^2 \geq 0$ is also a sufficient condition that all additional iterations are symplectic.