



### The MHD equilibrium problem in nonaxisymmetric toroidal plasma confinement systems (as a novel KAM problem)

R. L. Dewar<sup>1</sup>, M. J. Hole<sup>1</sup>, S. R. Hudson<sup>2</sup> M. McGann<sup>1</sup> R. Mills<sup>1</sup>

- [1] Research School of Physical Sciences and Engineering, Australian National University, ACT 0200, Australia
- [2] Princeton Plasma Physics Laboratory, New Jersey 08543, U.S.A.



Supported by Australian Research Council Grant DP0452728

### Contents

- 1. Introduction: 3D MHD toroidal equilibrium problem, coordinates & field-line Hamiltonian
- 2. Problems (chaos & singular currents ) and proposed solution: Stepped-pressure model with piecewise Beltrami fields
- 3. Sketches of two constructions
  - Surface potentials, radial continuation, and Hamilton–Jacobi extension across pressure barriers
  - Variational principle
- 4. Summary

### 1. Introduction



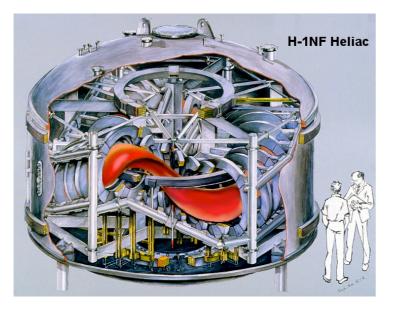
"Well, what <u>do</u> you say to a person who tells you he's working on a doughnut-shaped energy field?"

### 3D Toroidal plasma equilibrium

Good model for toroidal fusion plasma steady state is force balance for total pressure p combined with Ampère's law relating magnetic field **B** and current density **J**:

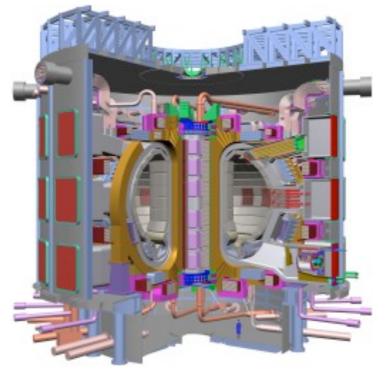
$$\nabla p = \mathbf{J} \times \mathbf{B}, \qquad \nabla \times \mathbf{B} = \mathbf{J},$$

EG Stellarators—intrinsically 3D, i.e. no continuous symmetry:



$$\nabla \cdot \mathbf{B} = 0$$

and Tokamaks, (*also* 3D due to coil ripple or instabilities):

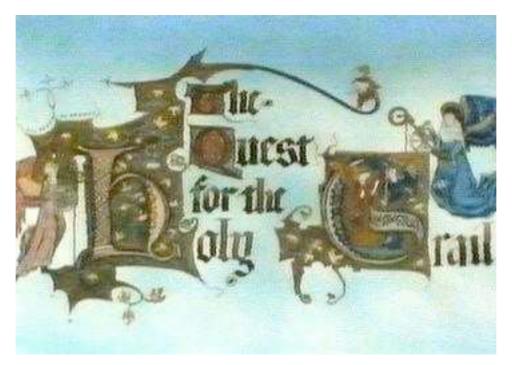


# Holy Grail — find constructive solution of 50-year-old problem

Toroidal Containment of a Plasma

HAROLD GRAD Phys. Fluids 10, 137 (1967) Courant Institute of Mathematical Sciences, New York University, New York, New York (Received 5 July 1966; final manuscript received 10 October 1966)

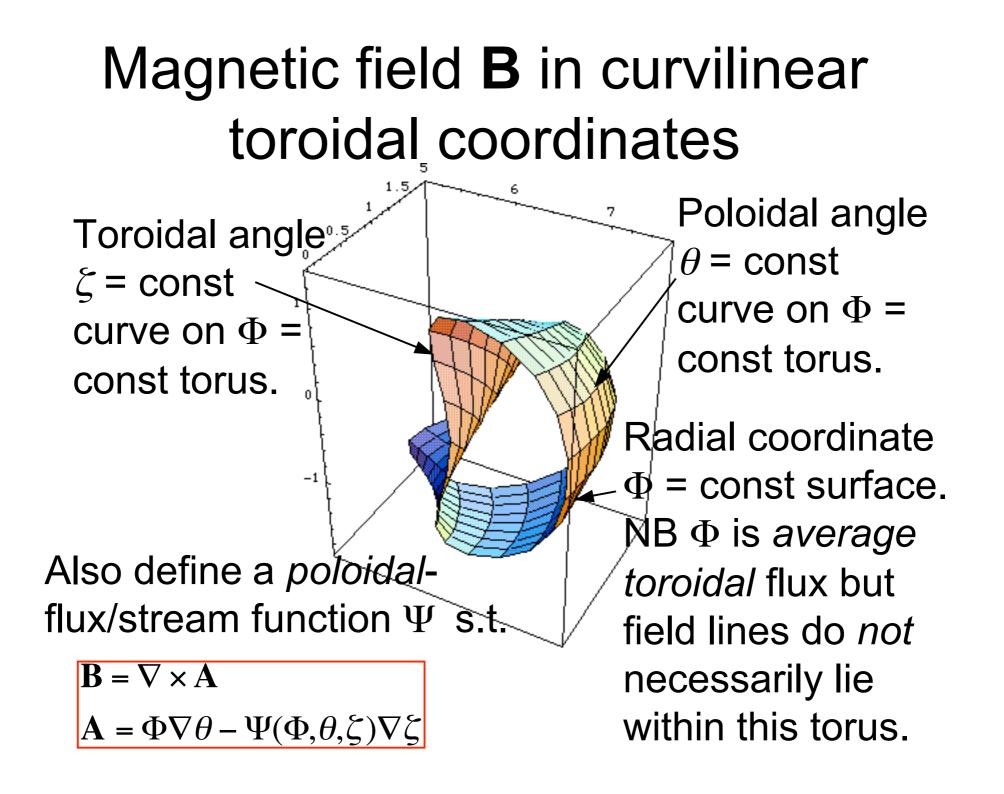
The question of plasma containment in a torus is much more complicated than in an open-ended mirror system. Serious questions arise of the nonexistence of flux surfaces, of noncontained particle drifts, and of nonexistence of self-consistent equilibria at small gyroradius.



### **Project Aims**

(1) design a convergent algorithm for constructing 3D equilibria,

- Find a mathematically well-posed formulation of problem and implement it numerically with aim to replace current unsatisfactory tools (e.g. VMEC code)
- Quantify relationship between magnitude of departure from axisymmetry and existence of 3D equilibria—both fundamental and practical problem
- Provide a better computational tool for rapid design and analysis
- (2) explore relationship between ideal MHD stability of multiple interface model and *internal transport barrier* formation



### Field-line flow as a 1<sup>1</sup>/<sub>2</sub> DoF Hamiltonian system

$$\frac{d\theta}{d\zeta} = \frac{\mathbf{B} \cdot \nabla \theta}{\mathbf{B} \cdot \nabla \zeta} = \frac{\partial \Psi}{\partial \Phi}$$

$$\frac{d\Phi}{d\zeta} = \frac{\mathbf{B} \cdot \nabla \Phi}{\mathbf{B} \cdot \nabla \zeta} = -\frac{\partial \Psi}{\partial \theta}$$

I.e. magnetic field-line flow is a *non-autonomous Hamiltonian system* with  $\Psi(\Phi, \theta, \zeta)$  the Hamiltonian,  $\theta$  the generalized coordinate,  $\Phi$  the canonically conjugate momentum, and  $\zeta$  the "time".

### 2. Problems with 3D equilibria Prob. I — they are generically *non-integrable*

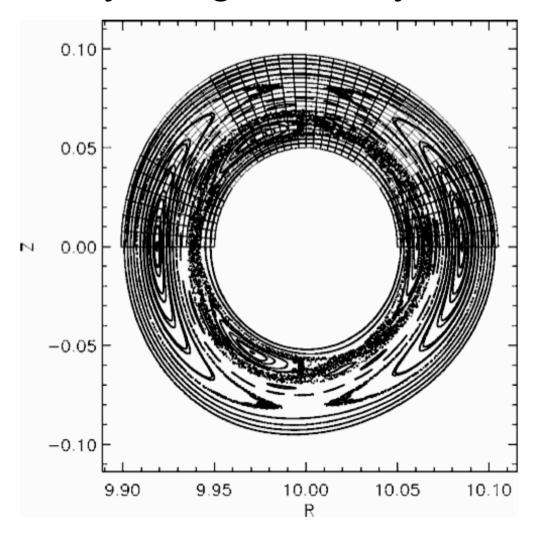


FIG. 7. Poincaré plot of Beltrami field: perturbation of outer boundary  $\delta$  =0.0030, with Fourier resolution *M*=7, *N*=2. Shown in the upper half plot is the coordinates.

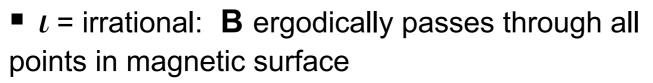
# But *design* so there exist some invariant tori (magnetic surfaces)

 $d\theta$ 

18

 $\theta$ 

- B field lines are everywhere tangential to a magnetic surface, winding around in a helical fashion
- Define winding number or rotational transform:  $\iota = \lim_{Z \to \infty} \frac{1}{7} \int_{-\pi}^{Z/2} \frac{d\theta}{d\xi} d\xi \equiv$



•  $\iota$  = rational (*m*/*n*) : **B** lines close on each other.

(In tokamaks, often define  $q = 1/\iota$ )

### Prob. II: 3D MHD equilibria have current singularities if $\nabla p \neq 0$

Current perp.to **B** is OK:  $\mathbf{J} \times \mathbf{B} = \nabla p \implies \mathbf{J}_{\perp} = \mathbf{B} \times \nabla p / B^2$ 

Problem is parallel current:  $J_{\parallel} \equiv \sigma B$ 

$$\nabla \cdot \mathbf{J} = 0 \implies \mathbf{B} \cdot \nabla \sigma = -\nabla \cdot \mathbf{J}_{\perp} = -\nabla \cdot (\mathbf{B} \times \nabla p / B^2)$$

Formal solution is:  $\sigma = \lambda - (\mathbf{B} \cdot \nabla)^{-1} \nabla \cdot (\mathbf{B} \times \nabla p / B^2)$ 

where  $\lambda$  is an arb. const. along field lines (e.g. over *finite volume* in a chaotic region, filled ergodically by single **B**-line).

**But** B. $\nabla$  is a very singular operator: for general 3D fields,  $\sigma$  blows up at each rational magnetic surface unless

$$\nabla \cdot \left( \mathbf{B} \times \nabla p / B^2 \right) = 0$$



### Proposed solution: Steppedpressure Beltrami equilibria

To ensure a mathematically well-defined  $J_{||}$ , we set  $\nabla p = 0$ over finite regions  $\Rightarrow \nabla \times B = \lambda B$ ,  $\lambda = \text{const}$  (*Beltrami field*) separated by assumed *invariant tori*.

Cf. Grad, *Toroidal Containment of plasma*, Phys. Plas. **10** (1967)

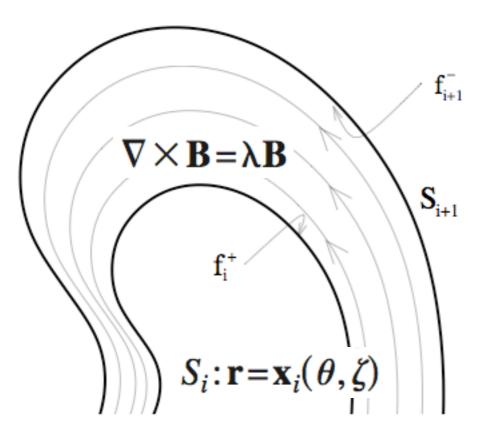
"In order to have a static (3D) equilibrium,  $p'(\Phi)$  must be zero in the neighborhood of <u>every</u> rational rotational transform, and *flux surfaces must* be relinquished"

- Pros
  - Beltrami eqn. is a linear elliptic PDE, solvable by variety of methods even if B has chaotic regions
  - Has already been partially investigated mathematically [e.g. Bruno & Laurence, Comm. Pure Appl. Math. XLIX, 717 (1996)]
- Cons (?)
  - Pressure profile not differentiable (**but** may approximate a smooth profile arbitrarily closely, limited only by existence of invariant tori)

### Force balance on invariant tori

- Pressure discontinuous:  $[[p]] \neq 0$  (where  $[[\cdot]]$  is jump across an invariant torus), but *total* pressure, magnetic plus kinetic, is continuous:  $[[p+B^2/2]] = 0$
- $\Rightarrow \delta$ -function  $\nabla p$
- $\Rightarrow$  sheet current  $\mathbf{J}_{\perp}$
- $\Rightarrow$  discontinuity in **B** (both magnitude & direction)
- $\Rightarrow$  winding number  $\iota$  not necessarily same on either side of invariant torus (*not* standard KAM problem)

### Equilibrium construction method I: A: solution of 3D Beltrami eqn. by method of lines/shooting method



#### **Coordinates:**

Assuming  $S_i$  and  $S_{i+1}$ are given, construct curvilinear coord. system, s,  $\theta$ ,  $\zeta$  where  $\theta$ ,  $\zeta$  are resp. gen. poloidal & toroidal angles and sinterpolates between  $S_i$  and  $S_{i+1}$  —

$$\mathbf{x} = s\mathbf{x}_{i+1} + (1-s)\mathbf{x}_i$$

 $\mathbf{x}_{j} = R_{j}(\theta, \zeta)\hat{r} + Z_{j}(\theta, \zeta)\hat{z}$ 

## IA contd.: radial integration of poloidal & toroidal components of **B**

Write **B** in covariant form:

$$\begin{split} \mathbf{B} &= B_s \, \nabla \, s + B_\theta \, \nabla \, \theta + B_\zeta \, \nabla \, \zeta \\ & \text{Can express } B_s \text{ in terms of } B_\theta \, \& \, B_\zeta \text{:} \\ B_s &= \frac{B^s - g^{s\theta} B_\theta - g^{s\zeta} B_\zeta}{g^{ss}} \quad \text{Where (if } \lambda \neq 0\text{):} \quad B^s = \frac{\partial_\theta B_\zeta - \partial_\zeta B_\theta}{\lambda \sqrt{g}} \\ & \text{So just need to solve for } \theta \, \& \, \zeta \text{ components. Can be} \\ & \text{done by integrating radially along curves } \theta, \, \zeta = \text{const :} \end{split}$$

$$\partial_s B_{\theta} = \partial_{\theta} B_s + \lambda \sqrt{g} (g^{s\zeta} B_s + g^{\theta\zeta} B_{\theta} + g^{\zeta\zeta} B_{\zeta})$$

$$\partial_s B_{\zeta} = \partial_{\zeta} B_s - \lambda \sqrt{g} (g^{s\theta} B_s + g^{\theta\theta} B_{\theta} + g^{\zeta\theta} B_{\zeta})$$

## Construction IA cont.: satisfying tangentiality at $S_i \& S_{i+1}$

**B** must be tangential to s = 0 and s = 1 surfaces:  $\mathbf{n} \cdot \mathbf{B} = 0$ 

Achieve on s = 0 by using surface magnetic potential f such that  $\mathbf{B} = \nabla_s f$  (exists because  $\mathbf{n} \cdot \nabla X \mathbf{B} = 0$ ), where surface gradient is defined as  $\nabla_s = \nabla - \mathbf{n} \frac{\partial}{\partial n}$ 

Use Fourier representations:

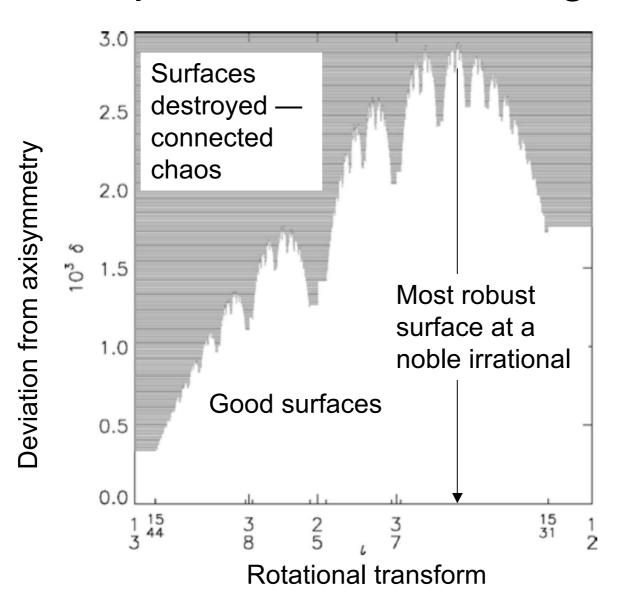
$$f = I\theta - G\zeta + \sum_{m,n} f_{mn} \sin(m\theta - n\zeta)$$
$$B_{\theta} = \sum_{m,n} B_{\theta,m,n}(s) \cos(m\theta - n\zeta) \qquad B_{\zeta} = \sum_{m,n} B_{\zeta,m,n}(s) \cos(m\theta - n\zeta)$$

Continue **B** from  $S_i$  by **shooting method**, satisfying  $\mathbf{n} \cdot \mathbf{B} = 0$ at  $S_{i+1}$ , to required tolerance, by iteratively adjusting  $f_{mn}$ 

### Construction IA conclusion:

- Published in S.R. Hudson, M.J. Hole and R.L. Dewar, Phys. Plasmas 14, 052505 (2007)
- Have verified above construction of 3D Beltrami fields works (though not elegant) for test problem: Beltrami equation between two specified toroidal surfaces
- Have studied non-standard eigenvalue problem posed by specifying *l* on bounding surfaces
- Have used Greene's method for finding KAM surfaces within the region: nest irrational no. by sequence of rationals, using Farey construction, giving rise to sequence of islands. If O-points of islands exist in limit, then KAM surface exists:

## KAM invariant tori at irrational $\iota$ : fractal dependence on winding no.



### Construction method I contd: B: Hamilton–Jacobi equation for *f*

Can relate surface magnetic potentials  $f^{+/-}$  such that  $\mathbf{B}^{+/-} = \nabla_s f^{+/-}$  on *either side* of a pressure barrier *S* by solving force balance as a PDE for  $f^+$  given  $f^-$  (& vice versa?) :

$$\left(\nabla_{s}f^{+}\right)^{2} = \left(\nabla_{s}f^{-}\right)^{2} + \left[\left[p\right]\right]$$

This is a Hamilton–Jacobi equation — characteristics are Hamiltonian orbits, with a purely *geometric* Hamiltonian. This is a *completely different* problem from the field-line flow problem, yet it leads to the same conclusion: the **rotational transforms on either side of pressure barrier must be irrational.** 

### Construction II: variational method

A: (Woltjer–)Taylor relaxation principle

Minimize total energy:  $W = \int_{P} \left( \frac{B^2}{2} + \frac{p}{\gamma - 1} \right) d\tau$ 

Under constraint of total helicity :  $K_0 = \frac{1}{2} \int_P (\mathbf{A} \cdot \mathbf{B}) d\tau$ 

Euler–Lagrange eqns. for  $\delta F = 0$ :  $F = W - \lambda K_0$ naturally give Beltrami equation:

Lagrange multiplier

 $\nabla \times \mathbf{B} = \lambda \mathbf{B}$ 

(To check whether *F* really is a minimum, need second variation — stability criterion similar to resistive stability, since reconnection is allowed.)

### Construction method IIA continued:

Generalization of Taylor principle — general idea

Cf. A. Bhattacharjee and R.L. Dewar, Phys. Fluids **25**, 887 (1982) Energy principle with global invariants

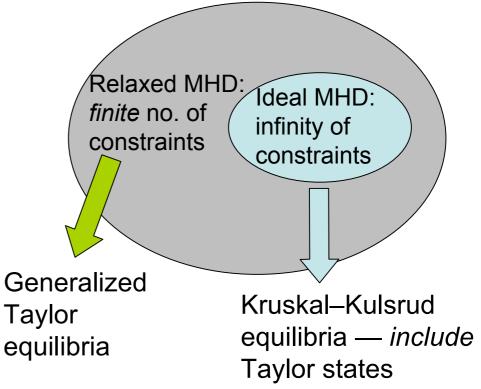
Idea: Extremize total energy

subject to *finite* number of ideal-MHD constraints (*unlike* ideal MHD where flux and entropy are "frozen in" to each fluid element — *infinite* no. of constraints).

Require constraints to be a **subset** of the **ideal-MHD** constraints, so generated states are ideal equilibria:

$$W = \int_{P \cup V} \left( \frac{B^2}{2} + \frac{p}{\gamma - 1} \right) d\tau$$

Spaces of allowed variations:



### Construction method IIA continued:

Generalization of Taylor principle — specific idea:

Assume invariant tori  $S_i$  act as ideal MHD barriers to relaxation, so that Taylor constraints are localized to subregions.

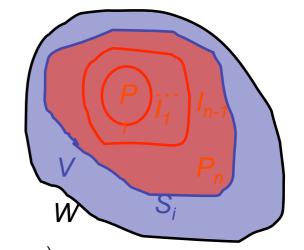
New system comprises:

- N plasma regions  $P_i$  in relaxed states.
- Regions separated by ideal MHD barrier S<sub>i</sub>.
- Enclosed by a vacuum V,
- Encased in a perfectly conducting wall W

#### **Constraints:**

**Constraints:**  
potential energy functionals: 
$$W_i = \int_{R_i} \left( \frac{B_i^2}{2} + \frac{P_i}{\gamma - 1} \right) d\tau^3$$
  
helicity functionals:  $K_i = \int_{V_i} \mathbf{A} \cdot \mathbf{B} \, d\tau$   
mass/entropy functionals:  $M_i = \int_{R_i} P_i^{1/\gamma} d\tau^3$ 

toroidal and poloidal fluxes:  $\Phi_i$  and  $\Psi_i$ 



### Construction method II B Hamiltonian trial function

Use representation

$$\mathbf{B} = \nabla \times \mathbf{A}$$

$$\mathbf{A} = \Phi \nabla \theta - \Psi(\Phi, \theta, \zeta) \nabla \zeta$$

with  $\Psi, \Phi$ , and  $\theta$  as unknown fields ( $\zeta$ being assumed a prescribed coordinate, say cylindrical polar angle  $\phi$ ).

Or, rather, use inverse representation,  $\phi = \zeta$ 

 $\mathbf{r} = R(\Phi,\theta,\zeta) \hat{r}(\phi) + Z(\Phi,\theta,\zeta) \hat{z}$ 

### Construction method II B Hamiltonian trial function contd.

- Unlike usual KAM problem, the Hamiltonian  $\Psi$  is not prescribed it is an *unknown* to be solved for.
- Furthermore, Ψ,Φ, and θ are not unique because arbitrary canonical transformations can be performed in the regions between the invariant tori, where action-angle coordinates do not in general exist
- Suggests using an extra principle to fix the representation, e.g. *quadratic flux minimization*

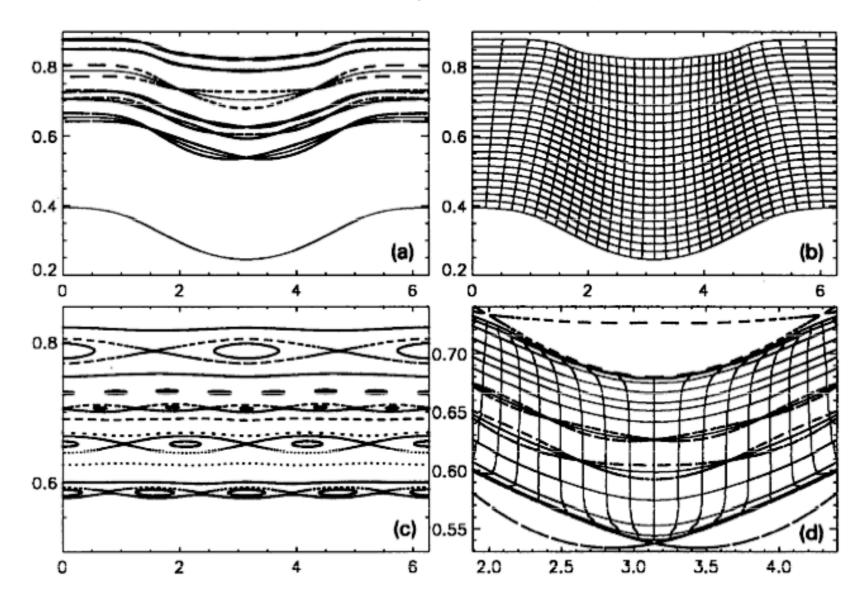
### Quadratic flux minimization

- R.L. Dewar & J.D. Meiss Physica D 57, 476 (1992); R.L. Dewar & A.B. Khorev Physica D 85, 66 (1995) — areapreserving twist maps
- S.R. Hudson & R.L. Dewar Phys. Lett. A
  226, 85 (1997) for magnetic fields: define field-line action S = ∮ A ⋅ dl
- Minimize square of "action gradient"  $\delta S/\delta \theta$

$$\delta S = \int_{\theta_1} \frac{\delta S}{\delta \theta} \delta \theta \, \mathrm{d} \zeta = \int_{\theta_1} \frac{\boldsymbol{B} \cdot \boldsymbol{n}}{\boldsymbol{n} \cdot \boldsymbol{\nabla} \theta \times \boldsymbol{\nabla} \zeta} \delta \theta \, \mathrm{d} \zeta.$$

### Action-angle coordinates for nonintegrable field

S.R. Hudson, R.L. Dewar/Physics Letters A 247 (1998) 246-251



### Conclusion

- Hamilton-Jacobi equation for force balance across interfaces relates directly to KAM ⇒ irrational *ι*, but defines a direction of "information transfer" ⇒ method of lines for Beltrami equation: *inappropriate* for an elliptic problem
- Variational approach is *a priori* more appropriate, but, to relate to KAM, need to find field-line Hamiltonian in inverse representation: Beltrami equation becomes nonlinear and need to fix nonuniqueness, either using Meiss' quadratic flux or minimizing  $\int (\nabla \zeta \times \nabla \widetilde{\Psi})^2 d^3 x$
- Second variation of free energy,  $\delta^2 F$ , is important both for optimization approach above and for stability calculations (Hole *et al* 2007 cylindrical studies)