

The MHD equilibrium problem in nonaxisymmetric toroidal plasma confinement systems (as a novel KAM problem)

R. L. Dewar¹, M. J. Hole¹, S. R. Hudson² M. McGann¹ R. Mills¹

[1] Research School of Physical Sciences and Engineering, Australian National University, ACT 0200, Australia [2] Princeton Plasma Physics Laboratory, New Jersey 08543, U.S.A.

Supported by Australian Research Council Grant DP0452728

Contents

- 1. Introduction: 3D MHD toroidal equilibrium problem, coordinates & field-line Hamiltonian
- 2. Problems (chaos & singular currents) and proposed solution: Stepped-pressure model with piecewise Beltrami fields
- 3. Sketches of two constructions
	- Surface potentials, radial continuation, and Hamilton–Jacobi extension across pressure barriers
	- **•** Variational principle
- 4. Summary

1. Introduction

"Well, what do you say to a person who tells you he's working on a doughnut-shaped energy field?"

3D Toroidal plasma equilibrium

Good model for toroidal fusion plasma steady state is force balance for total pressure *p* combined with Ampère's law relating magnetic field **B** and current density **J**:

 $=$ **J**,

$$
\nabla p = \mathbf{J} \times \mathbf{B}, \qquad \nabla \times \mathbf{B}
$$

EG Stellarators—intrinsically 3D, i.e. no continuous symmetry:

$$
\nabla \cdot \mathbf{B} = 0
$$

and Tokamaks, (*also* 3D due to coil ripple or instabilities):

Holy Grail — find constructive Solution of 50-year-old problem
Toroidal Containment of a Plasma

Phys. Fluids **10**, 137 (1967) Courant Institute of Mathematical Sciences, New York University, New York, New York (Received 5 July 1966; final manuscript received 10 October 1966)

The question of plasma containment in a torus is much more complicated than in an open-ended mirror system. Serious questions arise of the nonexistence of flux surfaces, of noncontained particle drifts, and of nonexistence of self-consistent equilibria at small gyroradius.

Project Aims

(1) design a convergent algorithm for constructing 3D equilibria,

- Find a mathematically well-posed formulation of problem and implement it numerically with aim to replace current unsatisfactory tools (e.g. VMEC code)
- quantify relationship between magnitude of departure from axisymmetry and existence of 3D equilibria—both fundamental and practical problem
- \triangleright provide a better computational tool for rapid design and analysis
- (2) explore relationship between ideal MHD stability of multiple interface model and *internal transport barrier* formation

Field-line flow as a $1\frac{1}{2}$ DoF Hamiltonian system

$$
\frac{d\theta}{d\zeta} = \frac{\mathbf{B} \cdot \nabla \theta}{\mathbf{B} \cdot \nabla \zeta} = \frac{\partial \Psi}{\partial \Phi}
$$

$$
\frac{d\Phi}{d\zeta} = \frac{\mathbf{B} \cdot \nabla \Phi}{\mathbf{B} \cdot \nabla \zeta} = -\frac{\partial \Psi}{\partial \theta}
$$

! *Hamiltonian system* with Ψ(Φ,θ, ζ) the I.e. magnetic field-line flow is a *non-autonomous* Hamiltonian, θ the generalized coordinate, Φ the canonically conjugate momentum, and ζ the "time".

2. Problems with 3D equilibria Prob. I — they are generically *non-integrable*

FIG. 7. Poincaré plot of Beltrami field: perturbation of outer boundary δ =0.0030, with Fourier resolution $M=7$, $N=2$. Shown in the upper half plot is the coordinates.

But *design* so there exist some invariant tori (magnetic surfaces)

θ

ζ

 $d\theta$

 $d\zeta$

- **B** field lines are everywhere tangential to a *magnetic surface*, winding around in a helical fashion
- Define winding number or *rotational transform*: $\iota = \lim_{n \to \infty}$
	- \blacksquare ι = irrational: **B** ergodically passes through all points in magnetic surface

 $Z \rightarrow \infty$

1

 $d\theta$

 $\int \frac{d\theta}{d\xi} d\xi =$

 $\int_{-Z/2}^{J} d\zeta$

Z / 2

Z

 \blacksquare ι = rational (m/n) : **B** lines close on each other. \mathbf{a}

(In tokamaks, often define $q = 1/t$)

Prob. II: 3D MHD equilibria have *current singularities* if $\nabla p \neq 0$

 $\mathbf{J} \times \mathbf{B} = \nabla p \implies \mathbf{J}_{\perp} = \mathbf{B} \times \nabla p / B^2$ Current perp.to **B** is OK:

Problem is parallel current: $J_{\parallel} \equiv \sigma B$

$$
\nabla \cdot \mathbf{J} = 0 \implies \mathbf{B} \cdot \nabla \sigma = -\nabla \cdot \mathbf{J}_{\perp} = -\nabla \cdot (\mathbf{B} \times \nabla p / B^2)
$$

Formal solution is: $\sigma = \lambda - (B \cdot \nabla)^{-1} \nabla \cdot (B \times \nabla p / B^2)$

where λ is an arb. const. along field lines (e.g. over *finite volume* in a chaotic region, filled ergodically by single **B**-line).

But **B**.V is a very singular operator: for general 3D fields, σ *blows up* at each rational magnetic surface unless \overline{a}

$$
\nabla \cdot (\mathbf{B} \times \nabla p / B^2) = 0
$$

Proposed solution: *Steppedpressure Beltrami equilibria*

To ensure a mathematically well-defined $J_{||}$, we set $\nabla p = 0$ over finite regions $\Rightarrow \nabla \times B = \lambda B$, λ = const (*Beltrami field*) separated by assumed *invariant tori*.

Cf. Grad, *Toroidal Containment of plasma,* Phys. Plas. **10** (1967)

"In order to have a static (3D) equilibrium, *p'*(Φ) must be zero in the neighborhood of **every** rational rotational transform, and *flux surfaces must be relinquished*"

- *Pros*
	- Beltrami eqn. is a linear elliptic PDE, solvable by variety of methods even if **B** has chaotic regions
	- Has already been partially investigated mathematically [e.g. Bruno & Laurence, Comm. Pure Appl. Math. **XLIX**, 717 (1996)]
- *Cons* (?)
	- Pressure profile not differentiable (**but** may approximate a smooth profile arbitrarily closely, limited only by existence of invariant tori)

Force balance on invariant tori

- Pressure discontinuous: $[[p]] \neq 0$ (where $[[\cdot]]$ is jump across an invariant torus), but *total* pressure, magnetic plus kinetic, is continuous: $[$ [p + B ²/2]] = 0
- ⇒ δ-function ∇*p*
- ⇒ sheet current **J**[⊥]
- ⇒ discontinuity in **B** (both magnitude & direction)
- \Rightarrow winding number ι not necessarily same on either side of invariant torus (*not* standard KAM problem)

Equilibrium construction method I: A: solution of 3D Beltrami eqn. by method of lines/shooting method **Coordinates:**

Assuming *Si* and *Si*+1 are given, construct curvilinear coord. system, *s*, ^θ, ζ where ^θ, ζ are resp. gen. poloidal & toroidal angles and *s* interpolates between S_i and S_{i+1} —

$$
\mathbf{x} = s\mathbf{x}_{i+1} + (1-s)\mathbf{x}_i
$$

 $\mathbf{x}_i = R_i(\theta, \zeta)\hat{r} + Z_i(\theta, \zeta)\hat{z}$

IA contd.: radial integration of poloidal & toroidal components of **B**

Write **B** in covariant form:

 $\mathbf{B} = B_s \nabla s + B_\theta \nabla \theta + B_\zeta \nabla \zeta$ Can express B_s in terms of B_θ & B_ζ : $B_s = \frac{B^s - g^{s\theta}B_{\theta} - g^{s\zeta}B_{\zeta}}{\sigma^{ss}}$ Where (if $\lambda \neq 0$): $B^s = \frac{\partial_{\theta}B_{\zeta} - \partial_{\zeta}B_{\theta}}{\lambda \sqrt{\sigma}}$ So just need to solve for θ & ζ components. Can be done by integrating radially along curves θ , ζ = const :

$$
\partial_s B_\theta = \partial_\theta B_s + \lambda \sqrt{g} (g^{s\zeta} B_s + g^{\theta\zeta} B_\theta + g^{\zeta\zeta} B_\zeta)
$$

$$
\partial_s B_{\zeta} = \partial_{\zeta} B_s - \lambda \sqrt{g} (g^{s\theta} B_s + g^{\theta\theta} B_{\theta} + g^{\zeta\theta} B_{\zeta})
$$

Construction IA cont.: satisfying tangentiality at S_i & S_{i+1}

B must be tangential to $s = 0$ and $s = 1$ surfaces: $n \cdot B = 0$

Achieve on *s* = 0 by using surface magnetic potential *f* such that **B** = $\nabla_s f$ (exists because **n** $\nabla \times \mathbf{B} = 0$), where surface gradient is defined as $\nabla_s = \nabla - \mathbf{n} \frac{\partial}{\partial n}$ *surface gradient* is defined as

Use Fourier representations:

$$
f = I\theta - G\zeta + \sum_{m,n} f_{mn} \sin(m\theta - n\zeta)
$$

$$
B_{\theta} = \sum_{m,n} B_{\theta,m,n}(s) \cos(m\theta - n\zeta)
$$

$$
B_{\zeta} = \sum_{m,n} B_{\zeta,m,n}(s) \cos(m\theta - n\zeta)
$$

Continue **B** from *Si* by **shooting method**, satisying **n. B**= 0 at S_{i+1} , to required tolerance, by iteratively adjusting f_{mn}

Construction IA conclusion:

- Published in S.R. Hudson, M.J. Hole and R.L. Dewar, Phys. Plasmas **14**, 052505 (2007)
- Have verified above construction of 3D Beltrami fields works (though not elegant) for test problem: Beltrami equation between two specified toroidal surfaces
- Have studied non-standard eigenvalue problem posed by specifying *on bounding surfaces*
- Have used Greene's method for finding KAM surfaces within the region: nest irrational no. by sequence of rationals, using Farey construction, giving rise to sequence of islands. If O-points of islands exist in limit, then KAM surface exists:

KAM invariant tori at irrational ι : fractal dependence on winding no.

Construction method I contd: B: Hamilton–Jacobi equation for *f*

Can relate surface magnetic potentials *f +/–* such that **B***+/–* = ∇*sf +/–* on *either side* of a pressure barrier *S* by solving force balance as a PDE for *f+* given *f –* (& vice versa?) :

$$
\left(\nabla_s f^+\right)^2 = \left(\nabla_s f^-\right)^2 + \left[\left[p\right]\right]
$$

! This is a *completely different* problem from the field-line This is a Hamilton–Jacobi equation — characteristics are Hamiltonian orbits, with a purely *geometric* Hamiltonian. flow problem, yet it leads to the same conclusion: the **rotational transforms on either side of pressure barrier must be irrational.**

Construction II: variational method

A: (Woltjer–)Taylor relaxation principle

 $W =$ $B²$ 2 ⁺ *^p* $\gamma - 1$ $\sqrt{2}$ \setminus $\left(\frac{B^2}{2}+\frac{p}{\gamma-1}\right)$ \int $\int_{P} \left(\frac{\epsilon}{2} + \frac{P}{\gamma - 1} \right) d\tau$ Minimize total energy: $W = \int$

Under *constraint of total helicity* : $K_0 =$ 1 $\frac{1}{2}\int_{P}^{ }(\mathbf{A}\cdot\mathbf{B})d\tau$

Euler–Lagrange eqns. for $\delta F = 0$: $F = W - \lambda K_0$ י
naturally give Beltrami equation:

Lagrange multiplier

 $\nabla \times \mathbf{B} = \lambda \mathbf{B}$

!!
... (To check whether *F* really is a minimum, need second variation — stability criterion similar to resistive stability, since reconnection is allowed.)

Construction method IIA continued:

Generalization of Taylor principle — general idea

Cf. A. Bhattacharjee and R.L. Dewar, Phys. Fluids **25**, 887 (1982) *Energy principle with global invariants*

Idea: Extremize total energy

subject to *finite* number of ideal-MHD constraints (*unlike* ideal MHD where flux and entropy are "frozen in" to each fluid element — *infinite* no. of constraints). !!!
! _

Require constraints to be a **subset** of the **ideal-MHD** constraints, so generated states are ideal equilibria:

$$
W = \int_{P \cup V} \left(\frac{B^2}{2} + \frac{p}{\gamma - 1} \right) d\tau
$$

Spaces of allowed variations:

Construction method IIA continued:

Generalization of Taylor principle — specific idea:

Assume invariant tori *Si* act as ideal MHD barriers to relaxation, so that Taylor constraints are localized to subregions.

New system comprises:

- *N* plasma regions P_i in relaxed states.
- Regions separated by ideal MHD barrier *Si* .
- Enclosed by a vacuum *V*,
- Encased in a perfectly conducting wall *W*

Constraints:

Wi = potential energy functionals:

helicity functionals:

mass/entropy functionals:

$$
W_{i} = \int_{R_{i}} \left(\frac{B_{i}^{2}}{2} + \frac{P_{i}}{\gamma - 1}\right) d\tau^{3}
$$

$$
K_{i} = \int_{V_{i}} \mathbf{A} \cdot \mathbf{B} \ d\tau
$$

$$
M_{i} = \int_{R_{i}} P_{i}^{1/\gamma} d\tau^{3}
$$

p

! toroidal and poloidal fluxes: ^Φ*ⁱ* and ^Ψ*ⁱ*

Construction method II B Hamiltonian trial function

Use representation

$$
B = \nabla \times A
$$

$$
\mathbf{A} = \Phi \nabla \theta - \Psi(\Phi, \theta, \zeta) \nabla \zeta
$$

with Ψ, Φ , and θ as unknown fields (ζ being assumed a prescribed coordinate, say cylindrical polar angle ϕ).

Or, rather, use inverse representation, $\phi = \xi$

 $\mathbf{r} = R(\Phi, \theta, \zeta) \hat{r}(\phi) + Z(\Phi, \theta, \zeta) \hat{z}$

Construction method II B Hamiltonian trial function contd.

- Unlike usual KAM problem, the Hamiltonian Ψ is not prescribed — it is an *unknown* to be solved for.
- Furthermore, Ψ,Φ, and ^θ are *not unique* because arbitrary canonical transformations can be performed in the regions between the invariant tori, where action-angle coordinates do not in general exist
- Suggests using an extra principle to fix the representation, e.g. *quadratic flux minimization*

Quadratic flux minimization

- R.L. Dewar & J.D. Meiss Physica D **57**, 476 (1992); R.L. Dewar & A.B. Khorev Physica D **85**, 66 (1995) — areapreserving twist maps
- S.R. Hudson & R.L. Dewar Phys. Lett. A **226**, 85 (1997) — for magnetic fields: define field-line action $S = \oint A \cdot dI$
- Minimize square of "action gradient" δ*S*/δθ

$$
\delta S = \int\limits_{\theta_1} \frac{\delta S}{\delta \theta} \delta \theta \, \mathrm{d} \zeta = \int\limits_{\theta_1} \frac{\boldsymbol{B} \cdot \boldsymbol{n}}{\boldsymbol{n} \cdot \nabla \theta \times \nabla \zeta} \delta \theta \, \mathrm{d} \zeta.
$$

Action-angle coordinates for *nonintegrable* field

Conclusion

- Hamilton-Jacobi equation for force balance across interfaces relates directly to KAM \Rightarrow irrational ι , but defines a direction of "information transfer" ⇒ method of lines for Beltrami equation: *inappropriate* for an elliptic problem
- Variational approach is *a priori* more appropriate, but, to relate to KAM, need to find field-line Hamiltonian in inverse representation: Beltrami equation becomes nonlinear and need to fix nonuniqueness, either using Meiss' quadratic flux or minimizing $\int (\nabla \zeta \times \nabla \tilde{\Psi})^2 d^3x$
- Second variation of free energy, $\delta^2 F$, is important both for optimization approach above and for stability calculations (Hole *et al* 2007 — cylindrical studies)